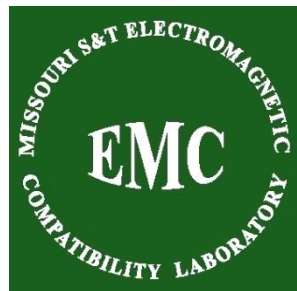


Behavioral Modeling and Parameter Extraction of VRMs for Power Integrity Analysis

Hanyu Zhang, Jiahuan Huang, Junho Joo, Chulsoon Hwang

Hybrid IBIS Summit at IEEE EMC+SIPI 2025
Raleigh, North Carolina
August 22, 2025



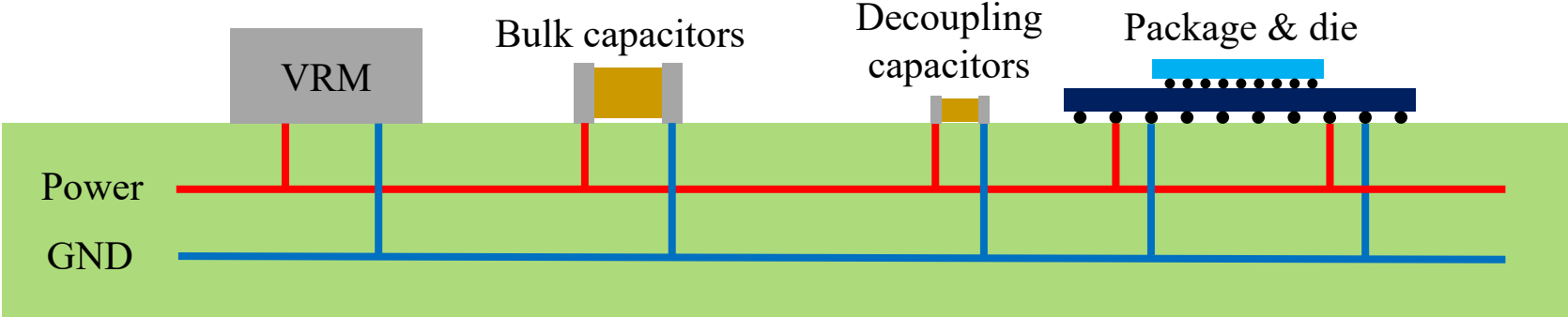
Outline

- Background: VRM and PDN
- VRM behavioral model
- VRM model parameter extraction
- Validation
- Conclusion

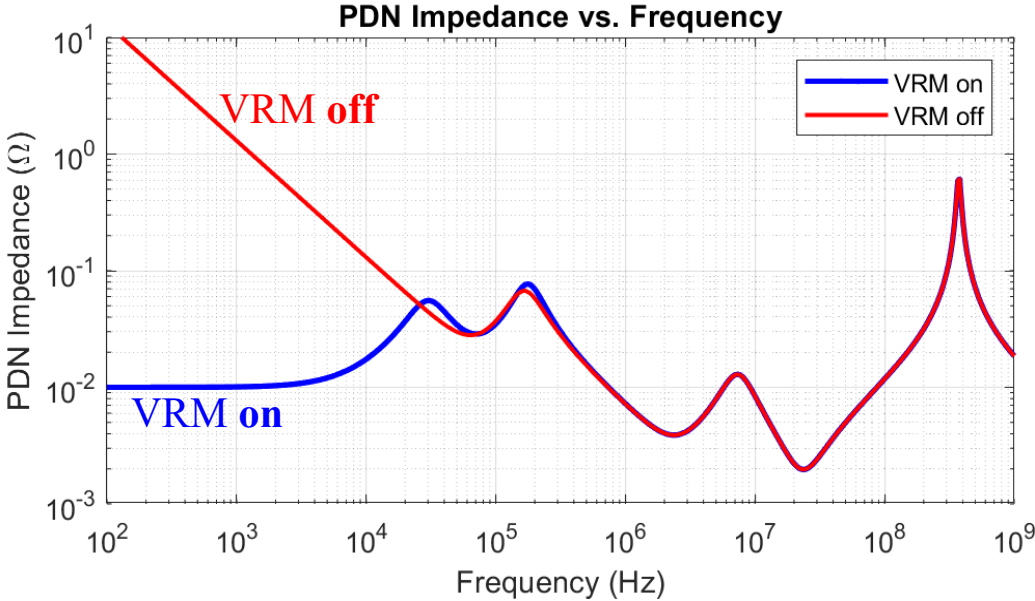
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Introduction: VRM and PDN



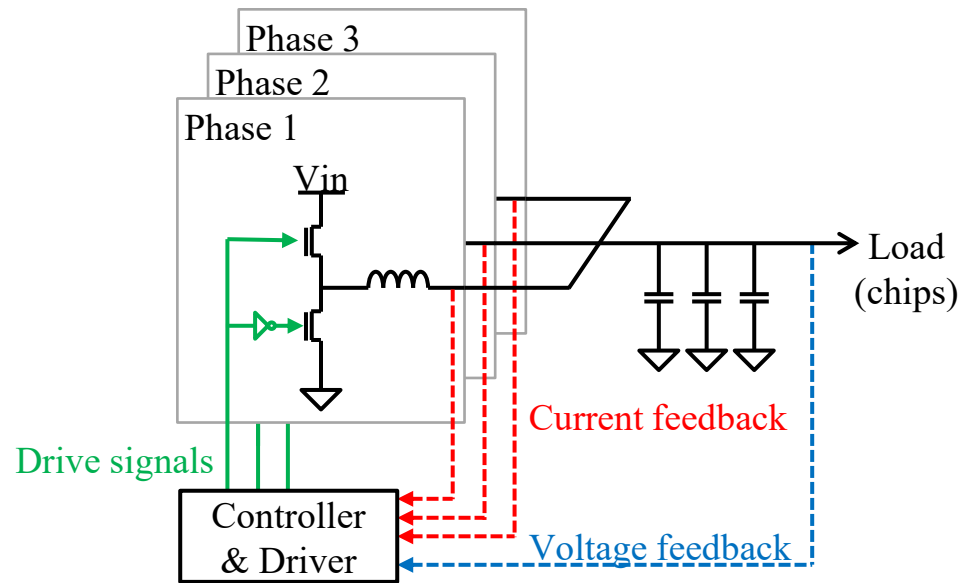
< Power delivery network >



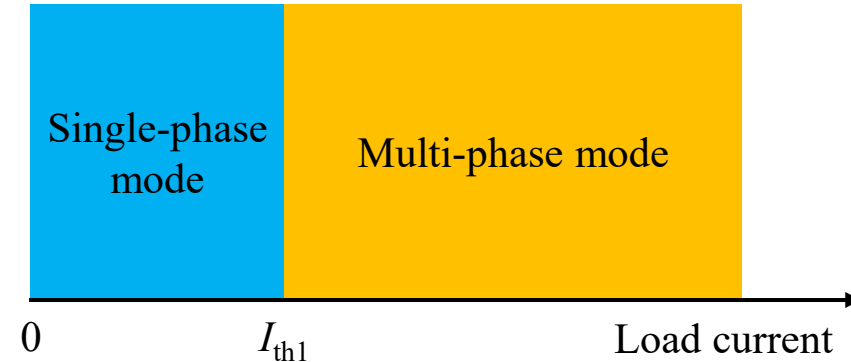
< PDN impedance: with vs. without VRM >

- VRM plays an important role in the PDN.
- Especially at the low frequencies.

Introduction: VRM and Power Integrity Simulation



< Typical multi-phase VRM >



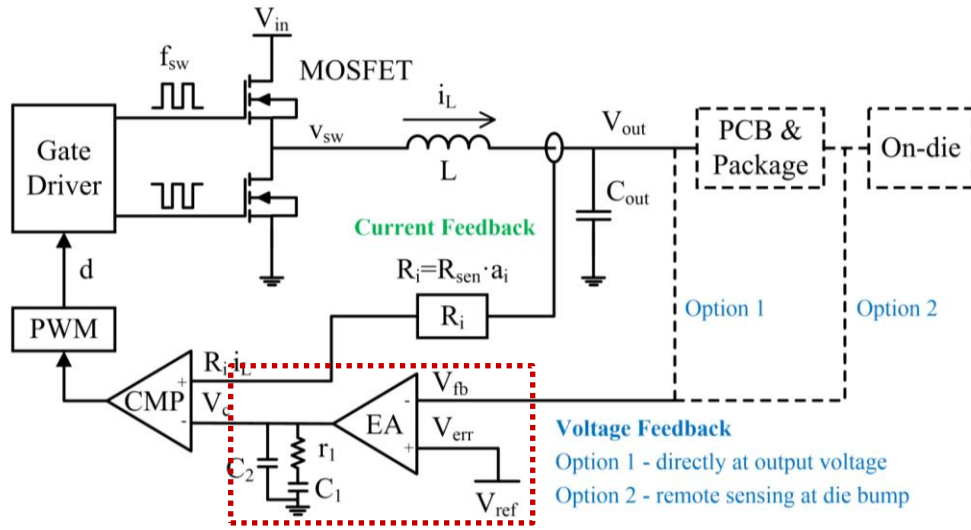
< Operation mode vs. Load current >

- Multi-phase Buck converter is widely used nowadays.
 - It selects the best operation mode based on the load current.
 - Single-phase mode and multi-phase mode.
- The mode transition is **nonlinear** behavior.
- Goal: build a VRM behavioral model for power integrity simulation in the time-domain.

Outline

- Background: VRM and PDN
- **VRM behavioral model**
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Modeling of Voltage Control Loop



< Single-phase VRM >

- VRM:
 - Power stage
 - Controller: voltage loop, current loop
- Type-II voltage compensator
 - Equivalent to LPF + PI controller

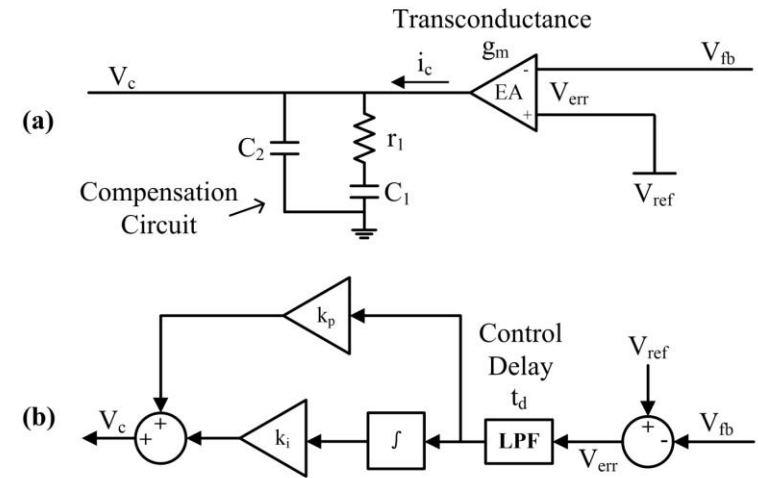
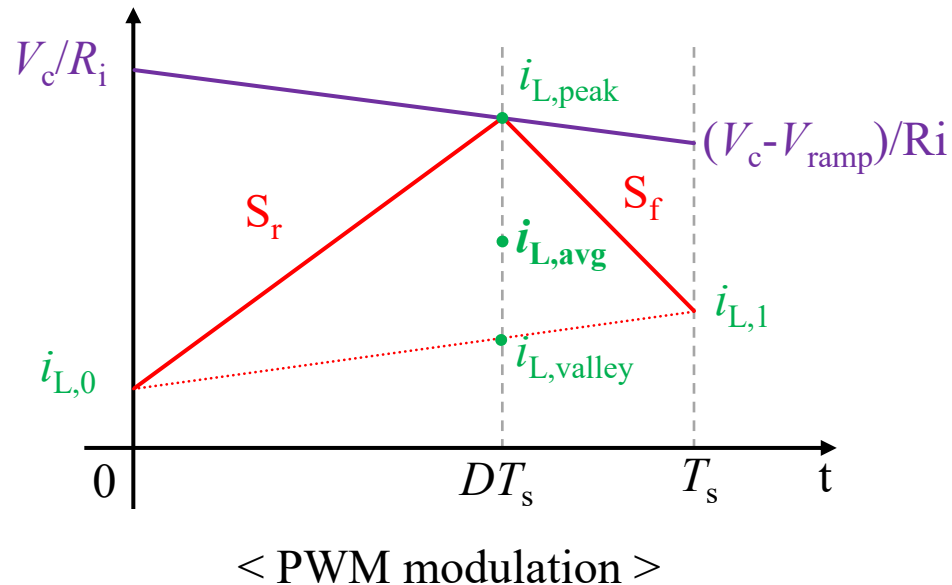


Fig. 4. Modeling of the voltage control loop: (a) actual design with the Type II compensation circuit; and (b) equivalent model with LPF and PI control.

< Type-II Voltage Compensator >

$$\begin{aligned} \frac{V_c}{V_{err}} &\approx \frac{g_m(sC_1r_1 + 1)}{s^2C_1C_2r_1 + sC_1} \\ &= \underbrace{\frac{1}{sC_2r_1 + 1}}_{\text{LPF}} \underbrace{\left(g_m r_1 + \frac{g_m}{C_1} \cdot \frac{1}{s} \right)}_{\text{PI controller}} \end{aligned}$$

Modeling of PWM Modulator (Current Control Loop)



- Average inductor current definition:

$$- i_{L,avg} = \frac{1}{2} (i_{L,peak} + i_{L,valley})$$

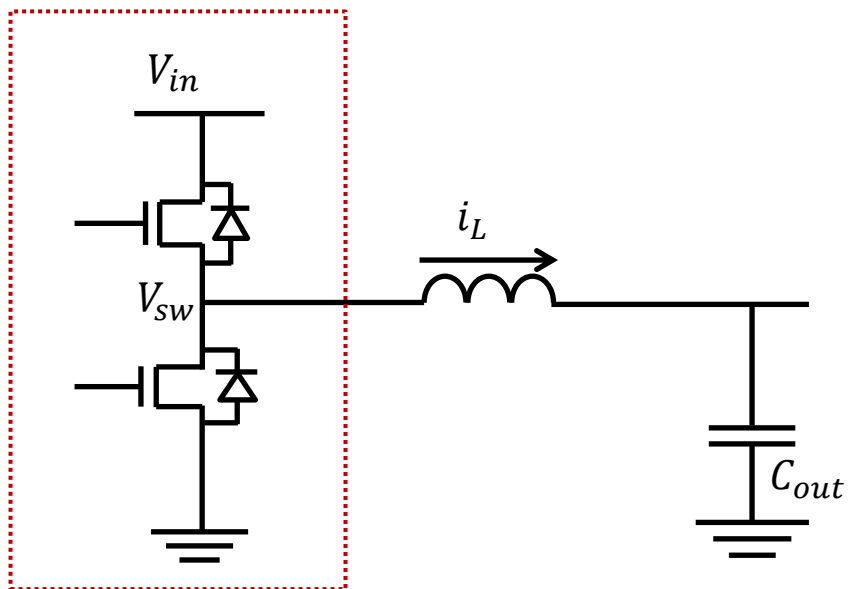
- Then, we have the follow derivation:

$$- i_{L,avg} = \left(\frac{V_c}{R_i} - \frac{V_{ramp}}{R_i} D \right) + \frac{1}{2} [(S_r - S_f) T_s D^2 - (S_r - S_f) T_s D]$$

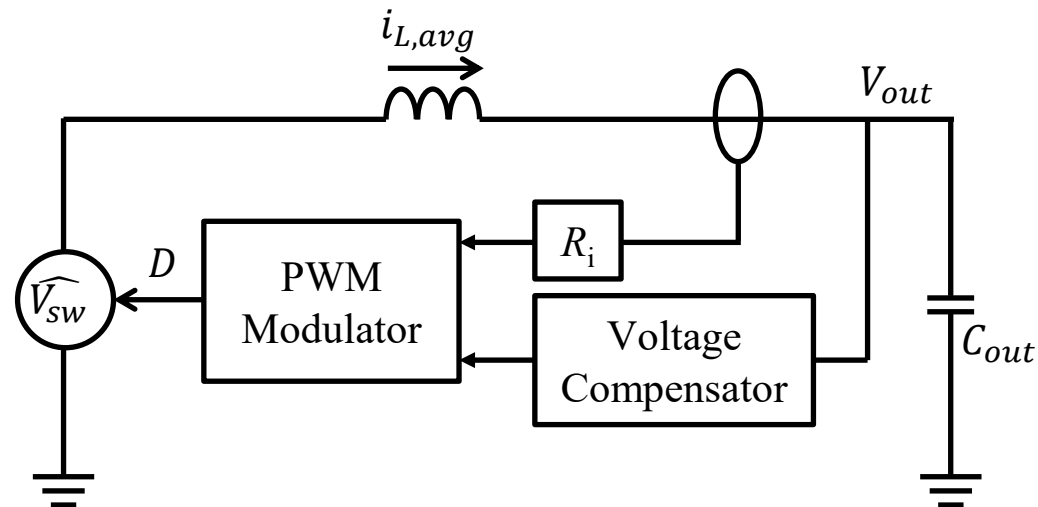
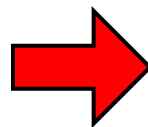
- Eventually, the duty cycle D can be found:

$$- D = \frac{1}{2} - \frac{V_{ramp}}{T_s \Delta S R_i} + \sqrt{\left(\frac{1}{2} - \frac{V_{ramp}}{T_s \Delta S R_i} \right)^2 + \frac{2}{T_s \Delta S} \left(\frac{V_c - V_{ramp}}{R_i} - \hat{i}_L \right)}$$

Modeling of Power Stage



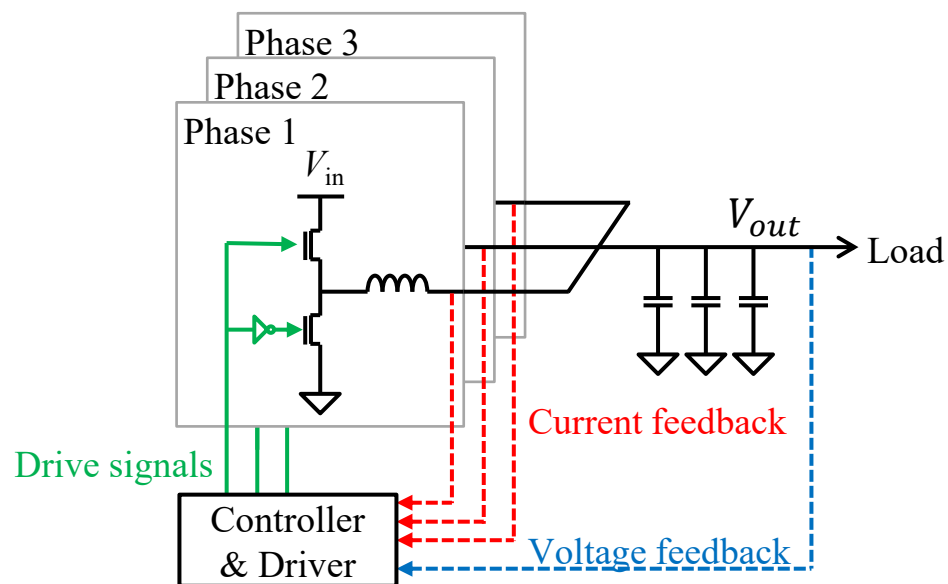
< VRM power stage >



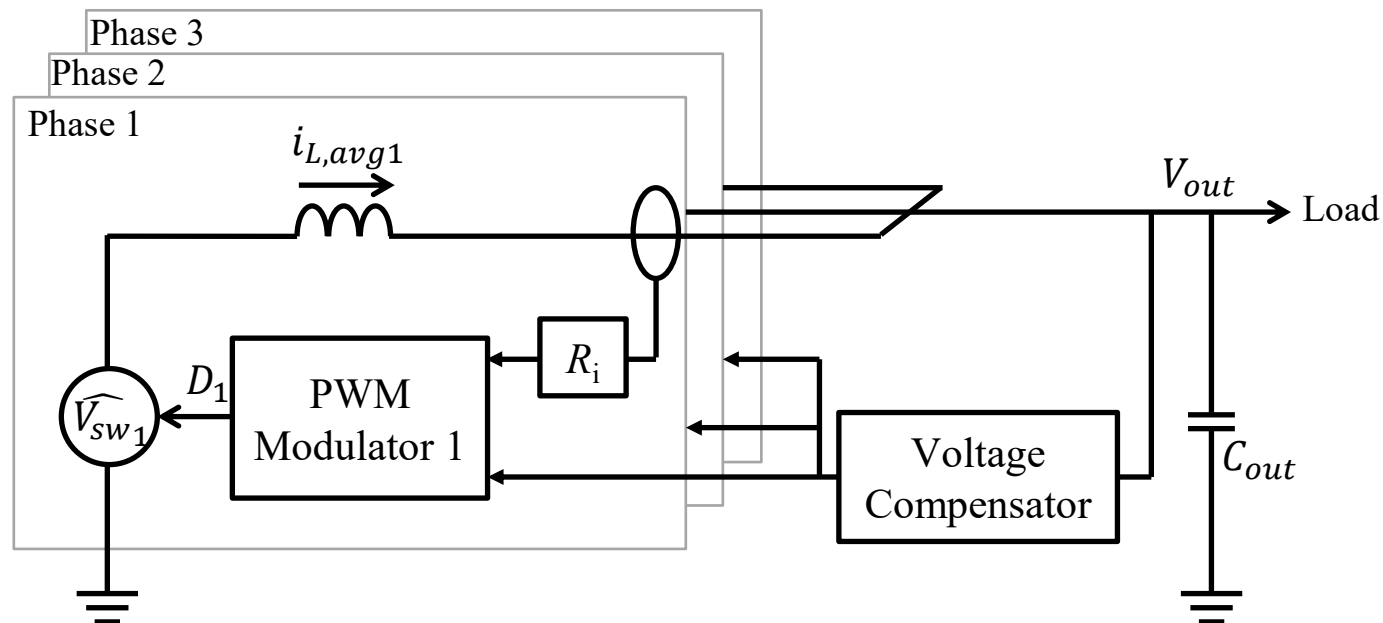
< Averaged behavioral VRM model >

- The high-side and low-side MOSFETs are replaced with a voltage source \widehat{V}_{sw} :
 - $\widehat{V}_{sw} = D \cdot V_{in}$
- Everything can be easily built in a SPICE model.

Modeling of Multiphase VRM



< Typical multi-phase VRM >



< Averaged behavioral VRM model >

- Each phase have its own power stage, and PWM modulator
- All phases share a common voltage compensator
- Some phases can be disabled dynamically based on load current.
 - A Verilog-A module is used to determine the state of each phase (enabled or disabled).
 - Many commercial simulation tools support Verilog-A.

Outline

- Background: VRM and PDN
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- **VRM model parameter extraction**
- Validation
- Conclusion

Parameters in the VRM Behavioral Model

Type	Parameters	Description
Power stage	V_{in}	Input voltage
	L	Inductor
	R_{ind}	Inductor ESR
	R_{on-h}	High-side MOSFET turn-on resistance
	R_{on-l}	Low-side MOSFET turn-on resistance
	f_s	Switching frequency
	C_{out}	Output capacitor
Mode transition	I_{th-add}	Phase add threshold
	t_{d-add}	Phase add delay
	$I_{th-drop}$	Phase drop threshold
	t_{d-drop}	Phase drop delay
	$I_{th-PFM2PWM}$	PFM to PWM threshold
	$t_{d-PFM2PWM}$	PFM to PWM delay
	$I_{th-PWM2PFM}$	PWM to PFM threshold
	$t_{d-PWM2PFM}$	PWM to PFM delay

Known parameters: easy to get
 Datasheets / simple measurement

Type	Parameters	Description
Control loop	V_{ref}	Reference voltage
	K_{DC}	Single-phase DC gain
	K_P	Single-phase proportional gain
	K_I	Single-phase integral gain
	V_{rp}	Ramp compensation
	R_i	Current sensing gain
	K_{P2}	Multi-phase proportional gain
	K_{I2}	Multi-phase integral gain
	K_{DC2}	Multi-phase DC gain

Unknown parameters: hard to obtain!

- Typically, not listed in datasheet.
- Cannot be directly measured.

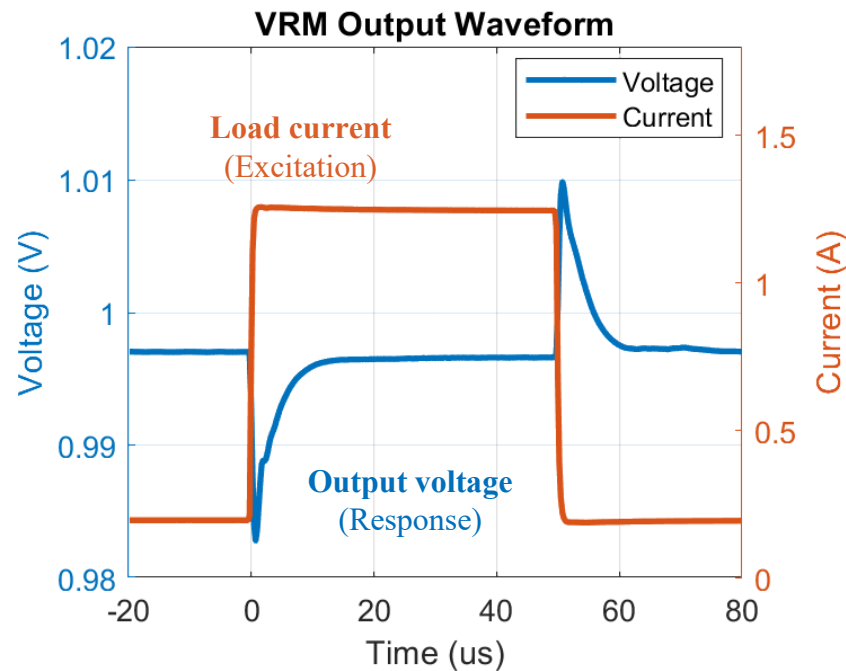
Automatic Parameter Extraction

We proposed a VRM parameter extraction method.

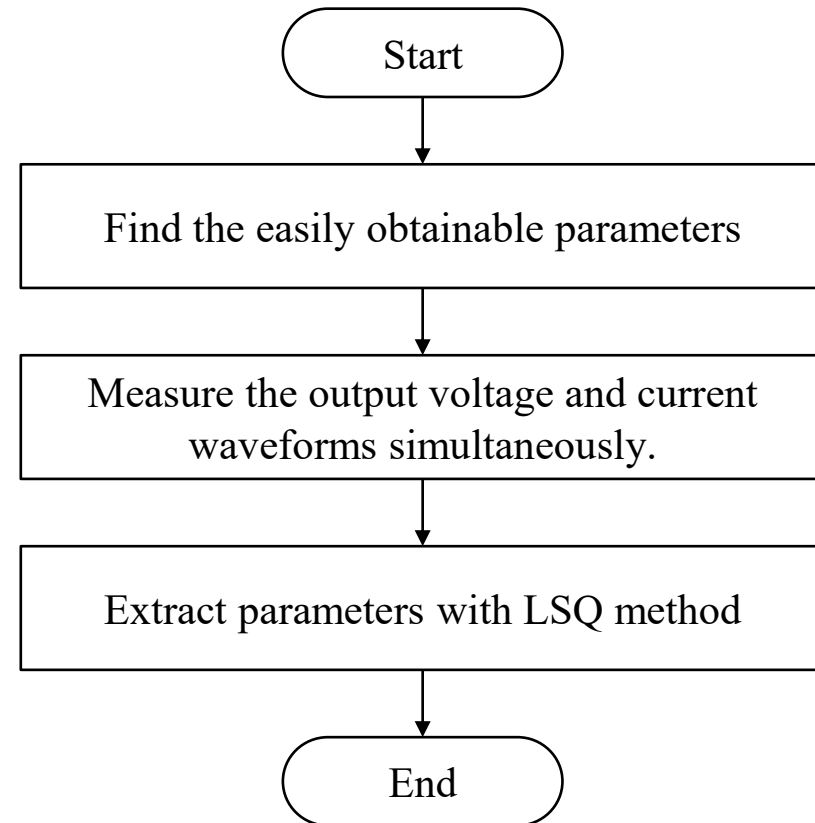
Employ nonlinear least-square (LSQ) method.

Take **output voltage** and **output current** waveforms as reference input.

From oscilloscope measurement.

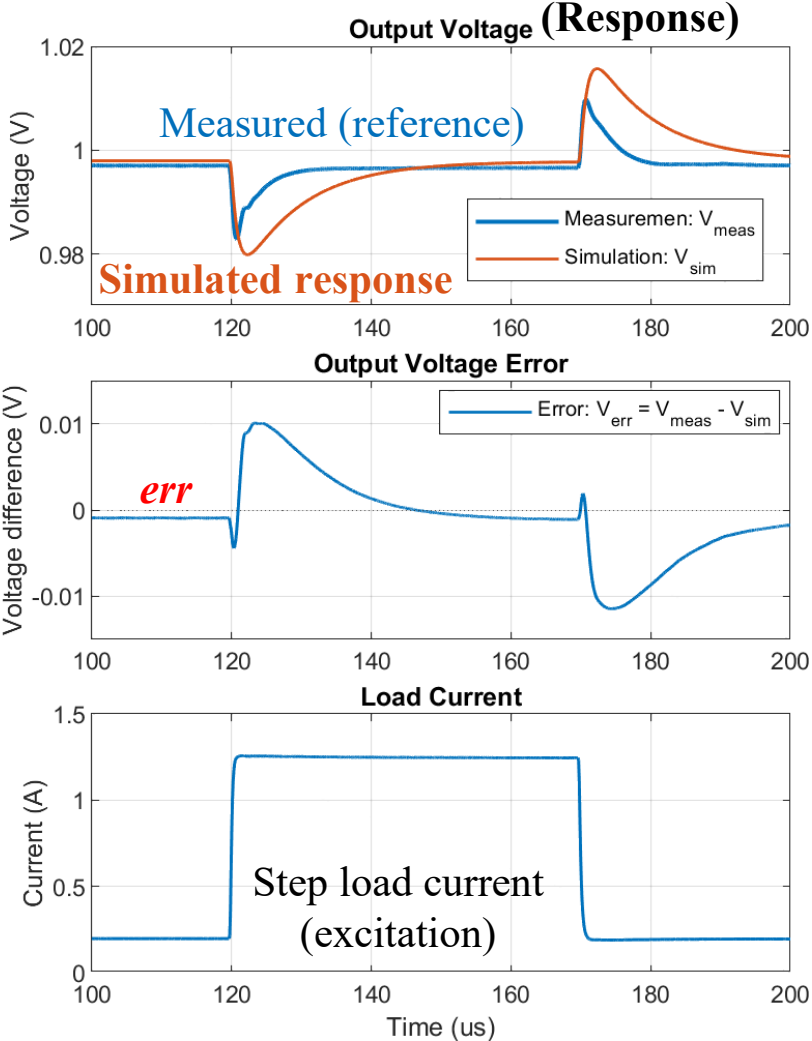


< VRM output waveform >



< Parameter extraction workflow >

Extract PWM-related Parameters



< Example waveform >

- Reference input waveform
 - Step load current excitation.
- Use nonlinear LSQ method to find the best estimation of the **unknown parameters**.
 - By minimizing the **cost function**.
 - SPICE simulations will be conducted in every iteration to update the cost function.

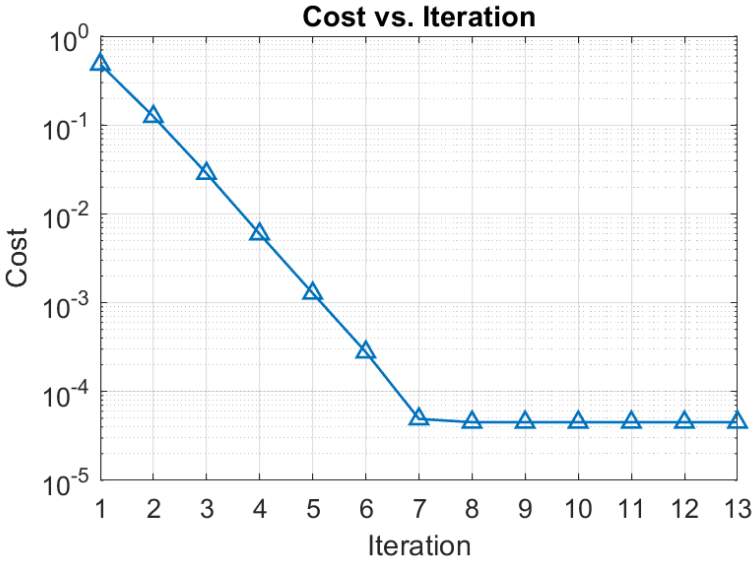
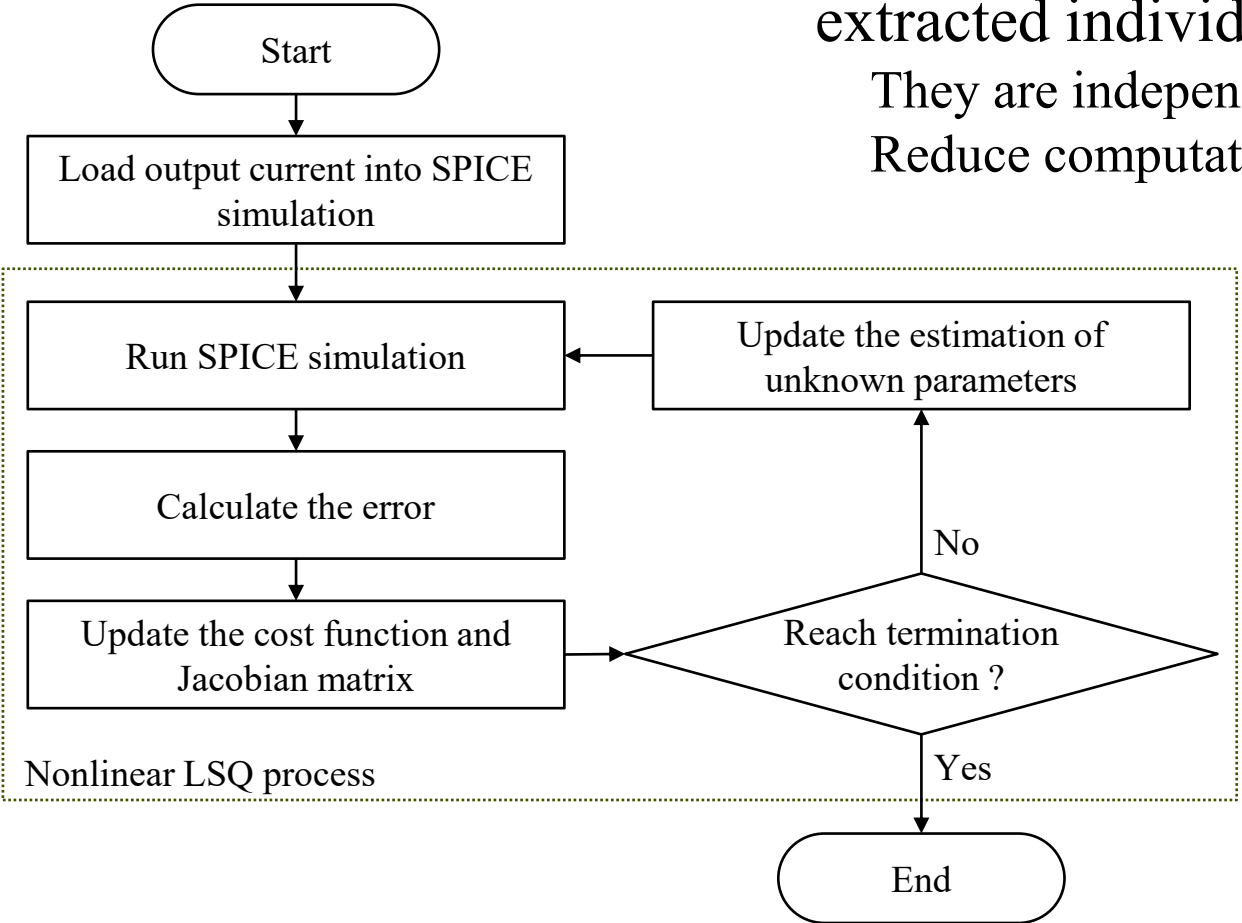
$$err[x] = V_{Meas.}[x] - V_{Sim.}[x]$$

$$Cost(parameters) = \sum_{x=1}^n err[x]^2$$

↑ ↑
Minimize **Tune**

Extract Parameters (cont.)

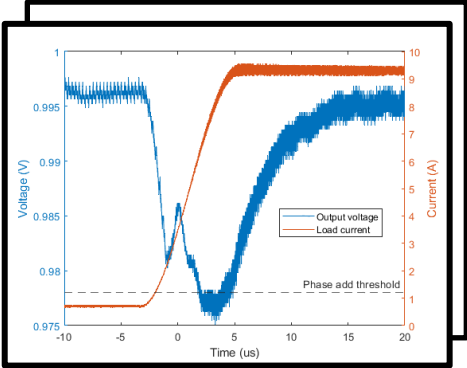
Single-phase parameters and multi-phase parameters are extracted individually.
 They are independent.
 Reduce computation time and improve convergence.



< Nonlinear LSQ cost vs. iteration >

< Parameter extraction algorithm >

Implementation: Automatic Parameter Extraction

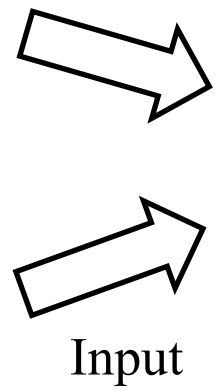


- Single-phase PWM waveform
- Multi-phase PWM waveform

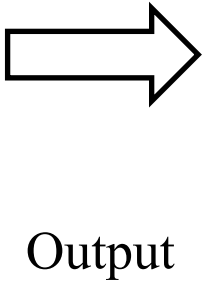
Measurement waveforms

Type	Parameters	Description
Power stage	V_{in}	Input voltage
	L	Inductor
	R_{ind}	Inductor ESR
	R_{on-h}	High-side MOSFET turn-on resistance
	R_{on-l}	Low-side MOSFET turn-on resistance
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	$I_{th-PWM2PFM}$	PWM to PFM threshold
	$t_{d-PWM2PFM}$	PWM to PFM delay

Known parameters



Python script:
Parameter extraction



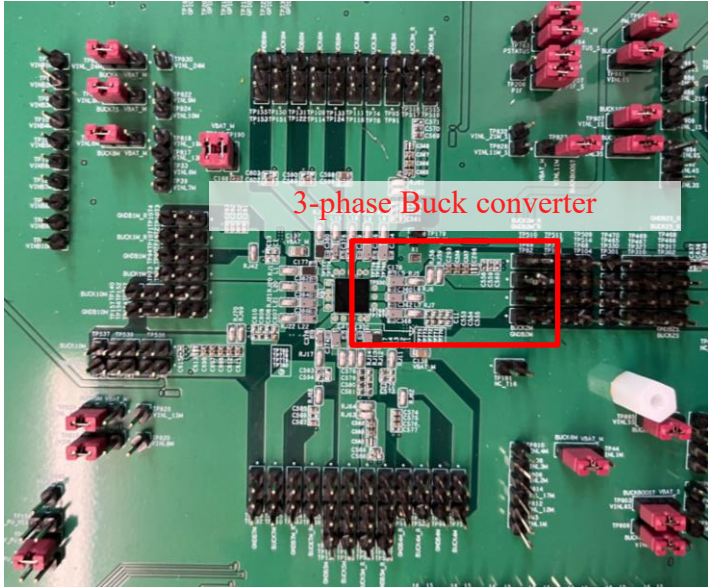
Type	Parameters	Description
Control loop	V_{ref}	Reference voltage
	K_{DC}	Single-phase DC gain
	K_P	Single-phase proportional gain
	K_I	Single-phase integral gain
	V_{rp}	Ramp compensation
	R_i	Current sensing gain
	K_{P2}	Multi-phase proportional gain
	K_{I2}	Multi-phase integral gain
	K_{DC2}	Multi-phase DC gain

Unknown parameters

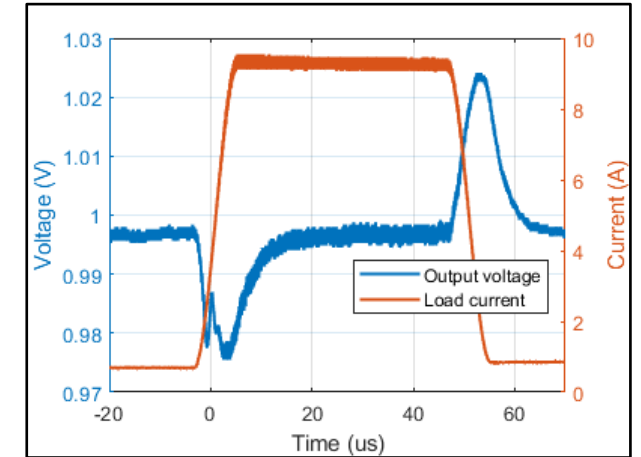
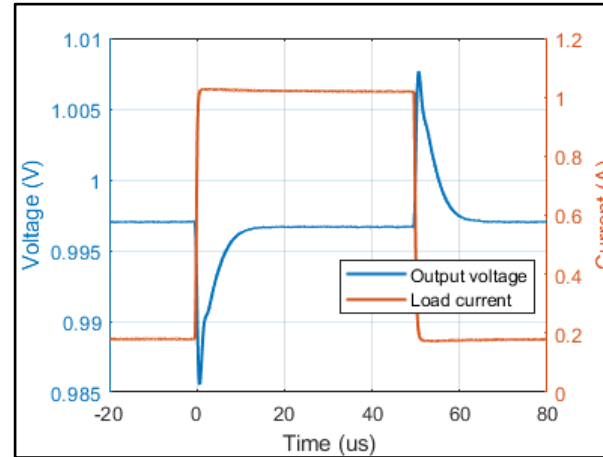
Outline

- Background: VRM and PDN
- VRM behavioral model
- VRM model parameter extraction
- **Validation**
- Conclusion

Validation Case 1: VRM EVB



< Measured output waveform of the EVB >



< VRM evaluation board for mobile applications >

< Single-phase PWM waveform >

< Multi-phase PWM waveform >

- A 3-phase Buck converter
 - With single-phase mode and 3-phase mode.
- With the given input, the Python script found the unknown parameters in 20 mins.

Parameter Extraction Result

Known parameters

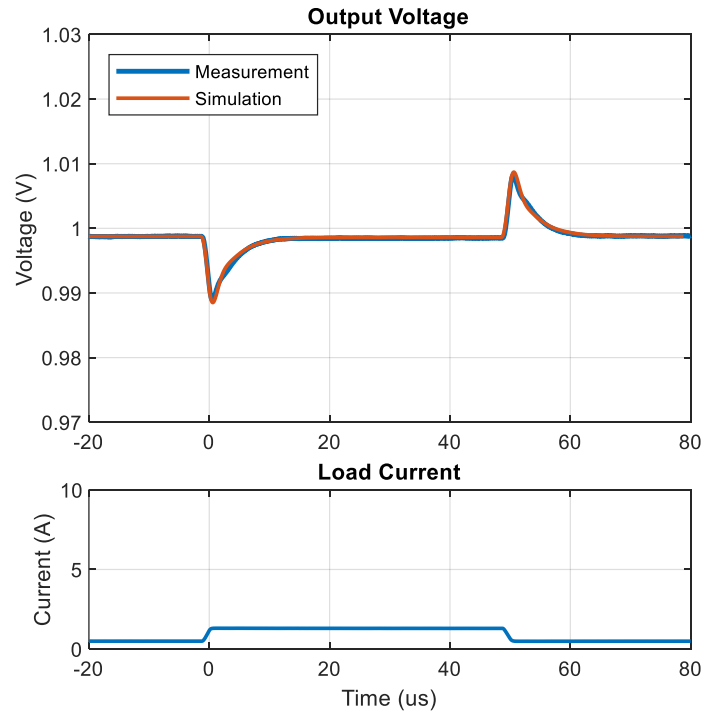
Category	Parameters	Value
Power stage	V_{in}	4
	L	240e-9
	R_{ind}	24e-3
	R_{on-h}	34e-3
	R_{on-l}	13e-3
	f_s	3.25e6
	C_{out}	1.5
	Mode transition	I_{th-add}
t_{d-add}		1.2
$I_{th-drop}$		20e-6
t_{d-drop}		0.57
$I_{th-PFM2PWM}$		0.33
$t_{d-PFM2PWM}$		0
$I_{th-PWM2PFM}$		40e-6
$t_{d-PWM2PFM}$		14e-6

Extracted parameters

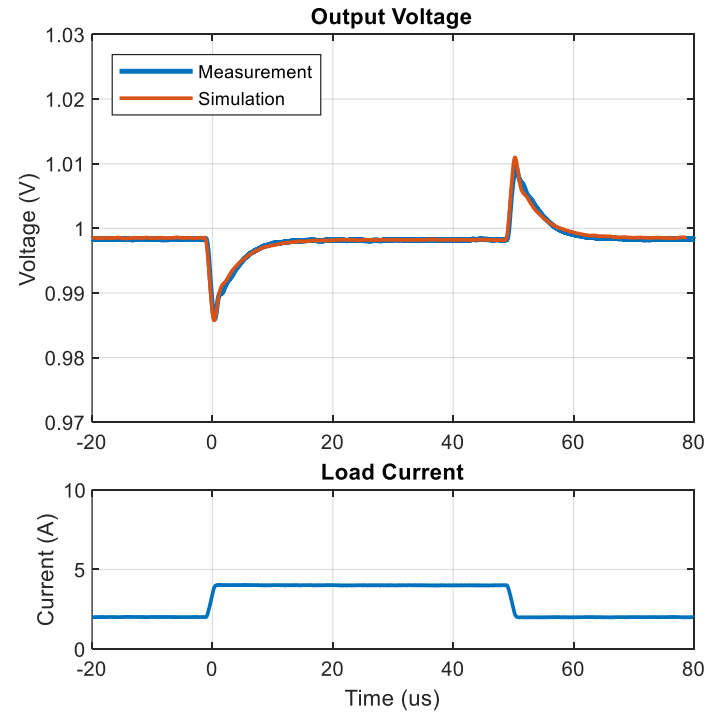
Category	Parameters	Initial value	Extracted value
PWM-related parameters	V_{ref}	1	0.99757
	K_{DC}	10	242.7
	K_P	1	5.693
	K_I	1e6	1441845
	V_{rp}	0.1	0.2793
	R_i	0.1	0.07246
	K_{P2}	1	3.836
	K_{I2}	1e6	1092029
	K_{DC2}	100	200.2

- The initial value is the start point for parameter extraction.
 - A very rough estimation of the unknown parameter.
 - The initial value listed here is a good start point for unknown VRM.

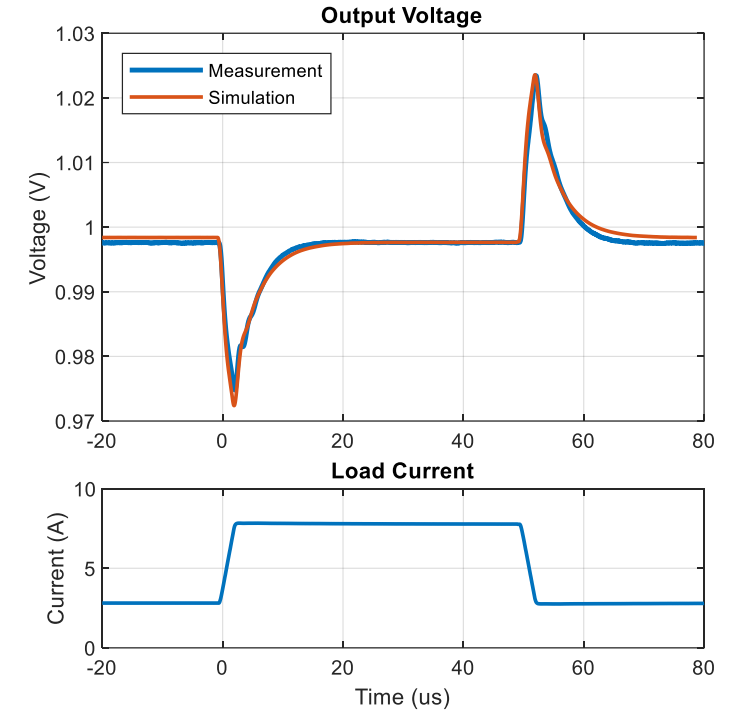
VRM EVB Validation Result



$V_{in} = 3V$, $I_{out} = 0.5A \leftrightarrow 1.3A$,
 $t_{r/f} = 1\mu s$, single-phase mode



$V_{in} = 4.5V$, $I_{out} = 2A \leftrightarrow 4A$,
 $t_{r/f} = 1\mu s$, 3-phase mode

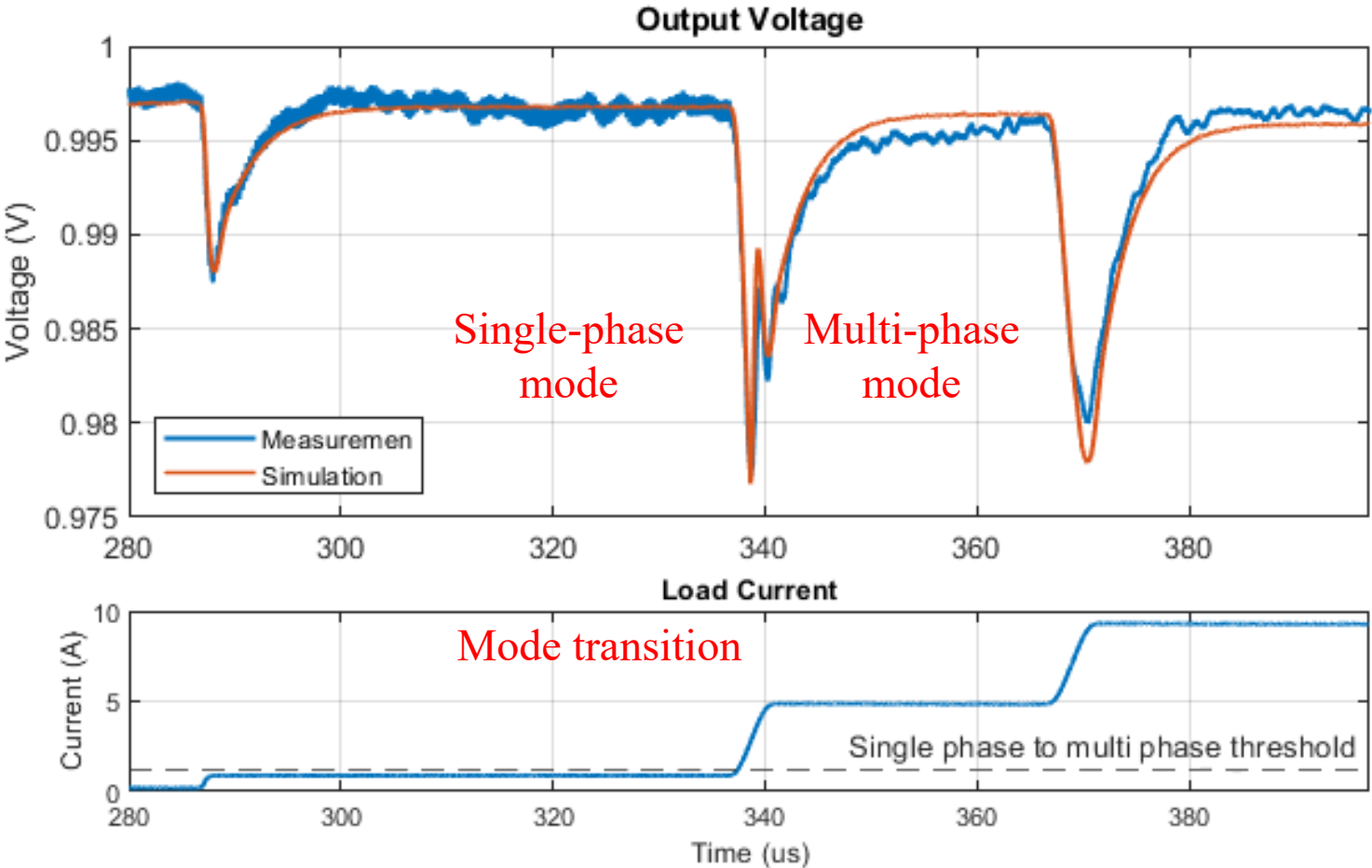


$V_{in} = 4.0V$, $I_{out} = 3A \leftrightarrow 8A$,
 $t_{r/f} = 2\mu s$, 3-phase mode

- Different test conditions.
 - Input voltage, current level, rising/falling time.

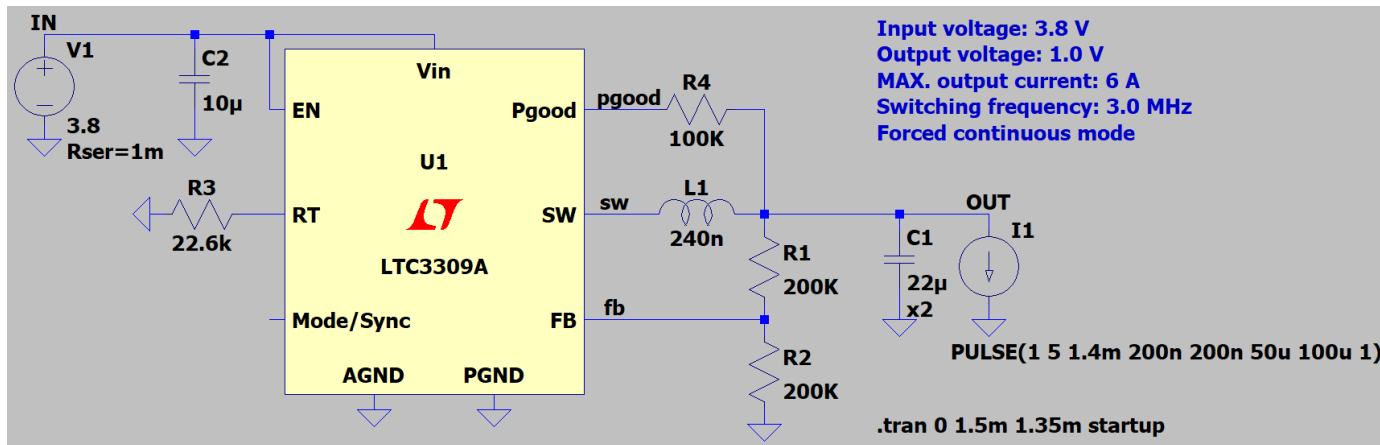
VRM EVB Validation Result (cont.)

- Nonlinear mode transition:
 - Single-phase mode to multi-phase mode.



Validation Case 2: LTC3309A

- Sometimes, we have the simulation model from the vender.
- But it is not suitable for PI simulation.
 - Encrypted, slow, not compatible with common PI simulation tools, ...
- So, it need to be converted to the behavioral model.



LTC3309A simulation model

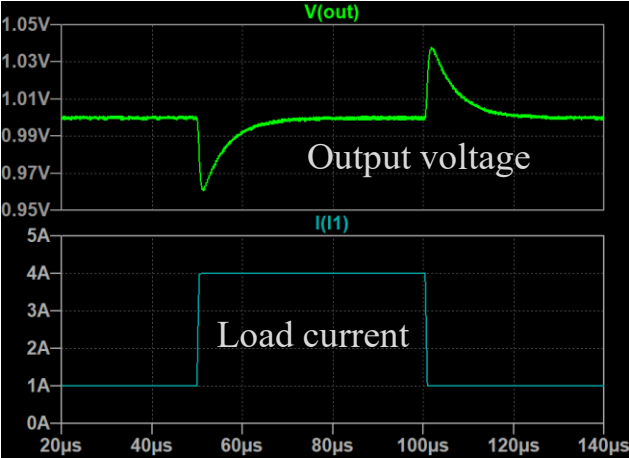
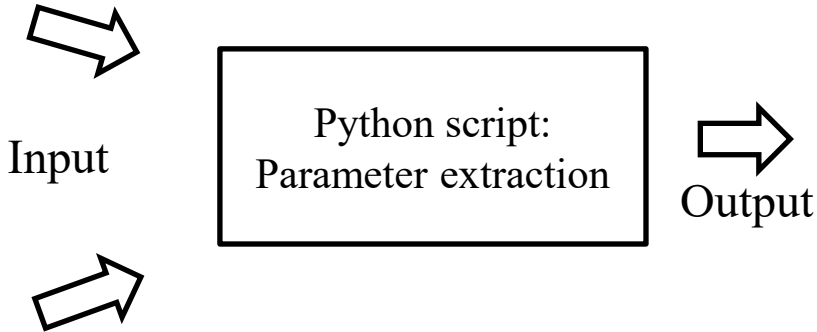
- Analog Device LTC3309A
 - Single-phase Buck converter
 - VRM model (encrypted) from vender
 - Input / output voltage: 3.8 V / 1.0 V
 - VRM: force continuous mode (FPWM)

Parameters of LTC3309A Model

- The unknown parameters were extracted based on the simulation result from the vender's model.

Parameters	Value
V_{in}	3.8
L	240e-9
R_{ind}	19.5e-3
R_{on-h}	31e-3
R_{on-l}	8e-3
f_s	3e6
C_{out}	44e-6

Known parameters

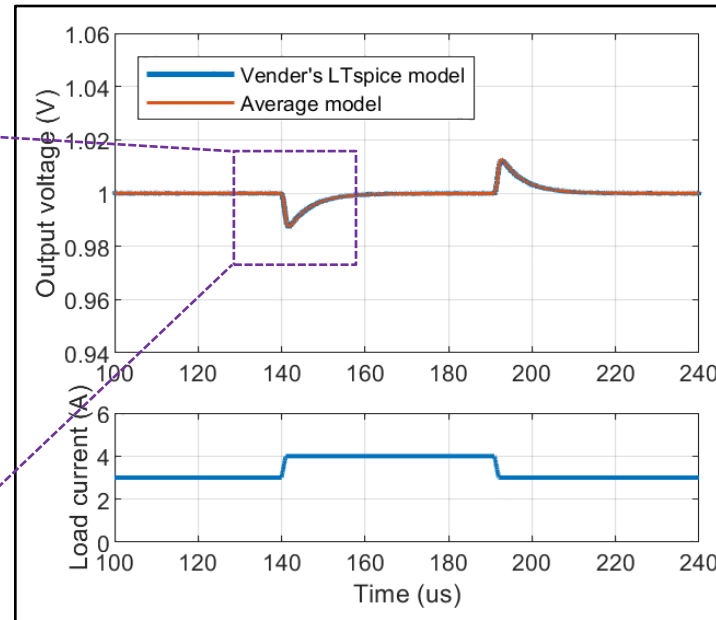
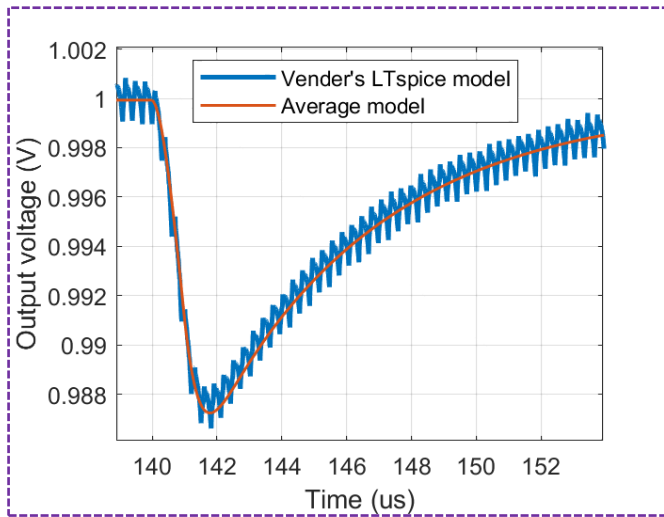


Simulated waveform from vender's VRM model

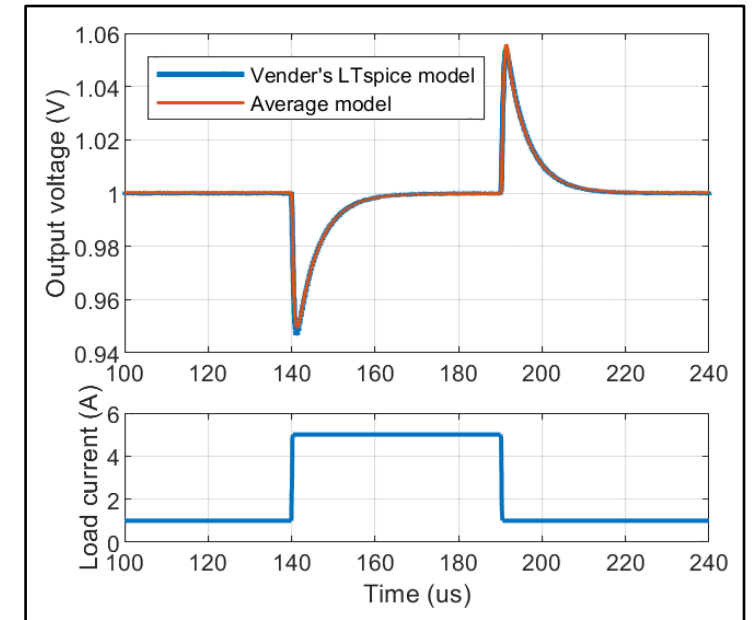
Extracted parameters

Parameters	Initial value	Extracted value
V_{ref}	1	1.00023
K_P	1	6.948848
K_I	1e6	1183846.49
V_{rp}	0.1	0.13695
R_i	0.1	0.09399

LTC3309A Validation Result



$I_{out}: 3A - 4A / t_{r/f} = 1 \text{ us}$



$I_{out}: 1A - 5A / t_{r/f} = 200 \text{ ns}$

- Behavioral model.

- Good correlation with the Vender's model.
- Neglect the output ripple; smooth output.
- Compatible with PI simulation tools.
- Took 2.01 seconds.

- Vender's model

- Includes the output ripple.
- Took 19.21 seconds.

Outline

- Background: VRM and PDN
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Conclusion

- An averaged behavioral VRM model was introduced.
 - It can be used for time-domain simulation.
 - This model works for both single-phase and multi-phase VRMs.
 - It captures the nonlinear mode transition.
 - Compatible with common PI simulation tools.
- A parameter extraction method for VRM was introduced.
 - It uses the reference waveform as input.
 - Use nonlinear LSQ method to extract the unknown parameters automatically.
- An encrypted VRM model can be converted to the behavioral model for PI analysis.
- This method simplifies the VRM modeling process.