

IBIS-Compatible Macromodel and Interconnect Simulation Techniques

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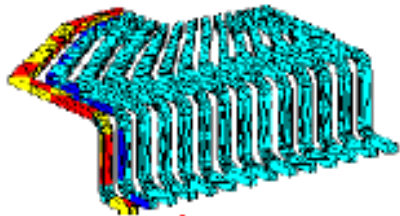
University of Illinois
at
Urbana-Champaign

**IBIS Summit
May 25, 2018
Brest France**

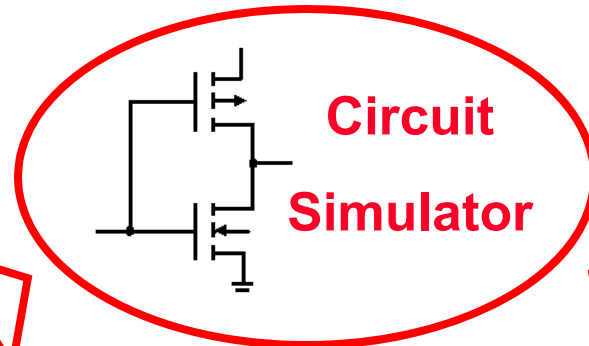


Interconnect Structures

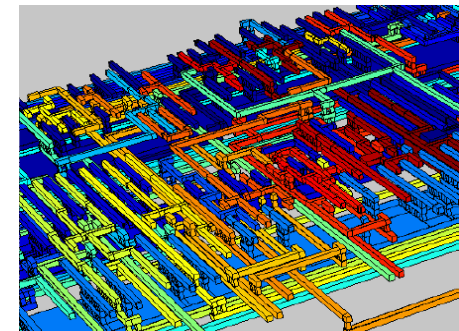
Crosstalk
Couplings
Reflections
Losses
Dispersion



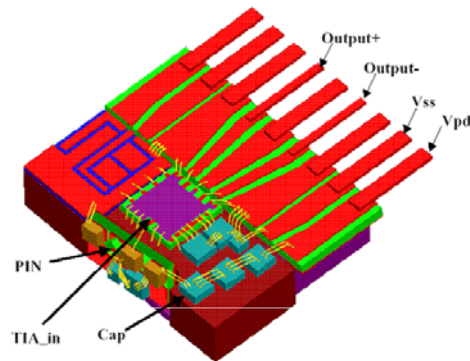
Packages



Ground Noise
Nonlinear effects
Radiation, EMI



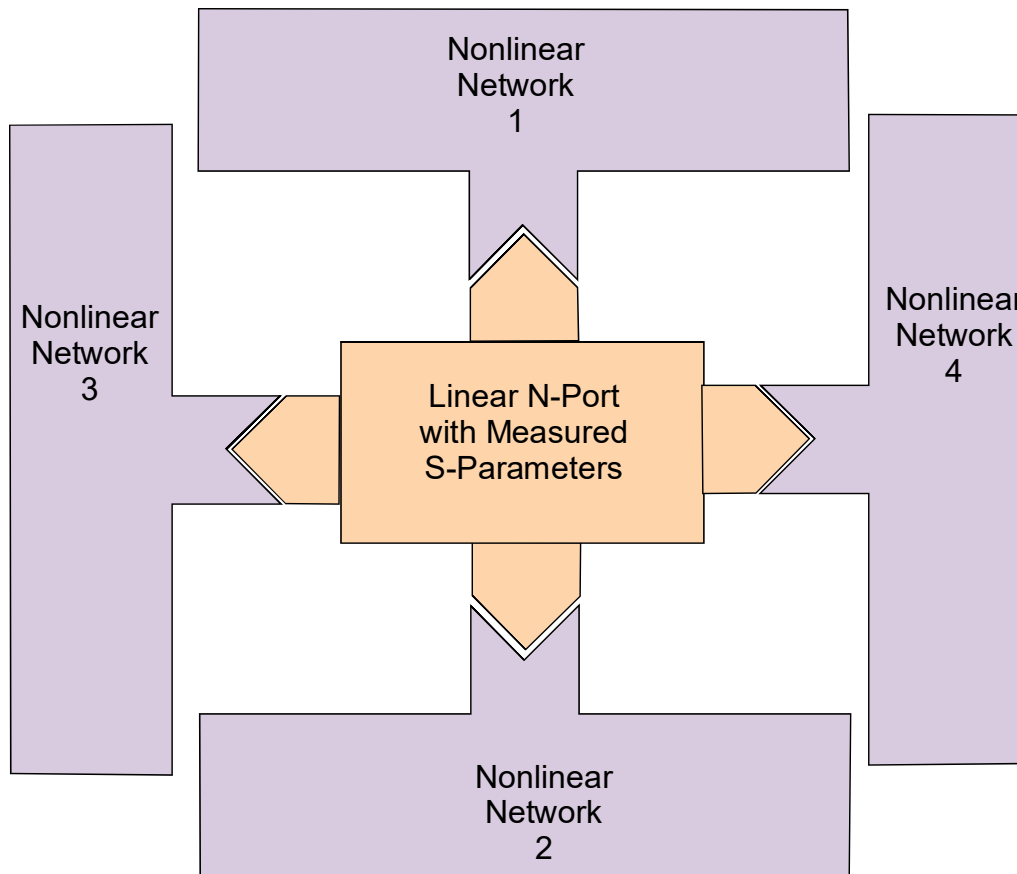
Interconnects



Courtesy of http://www.ansoft.com/hfworkshop03/Weimin_Sun_Vitesse.pdf



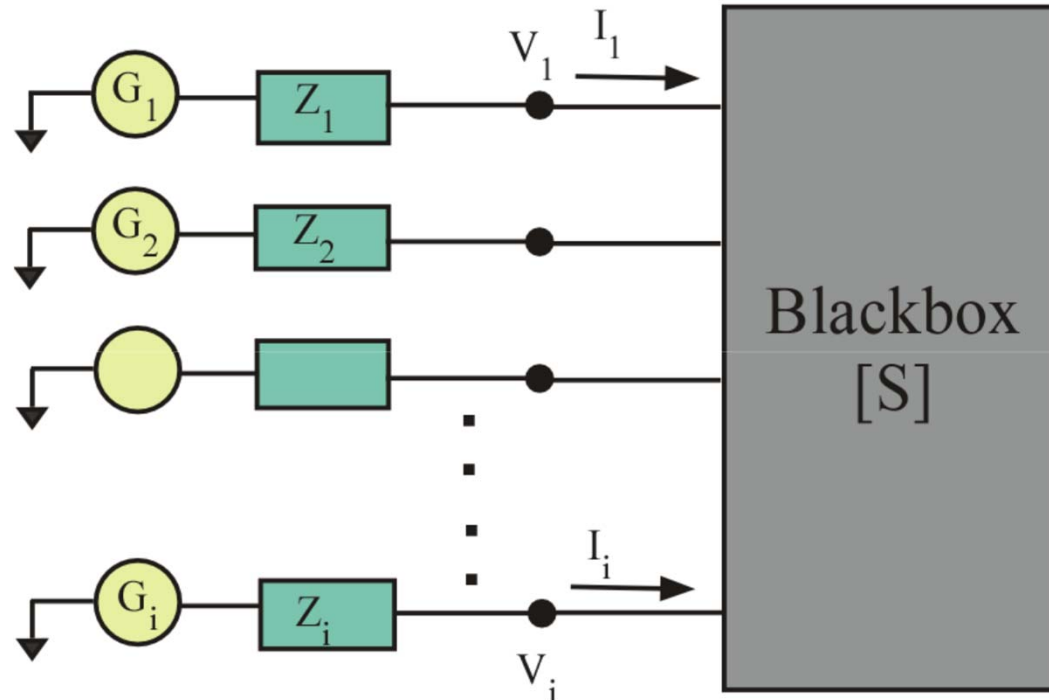
Blackbox Macromodeling



Objective:
Perform time-domain simulation of composite network to determine timing waveforms, noise response or eye diagrams



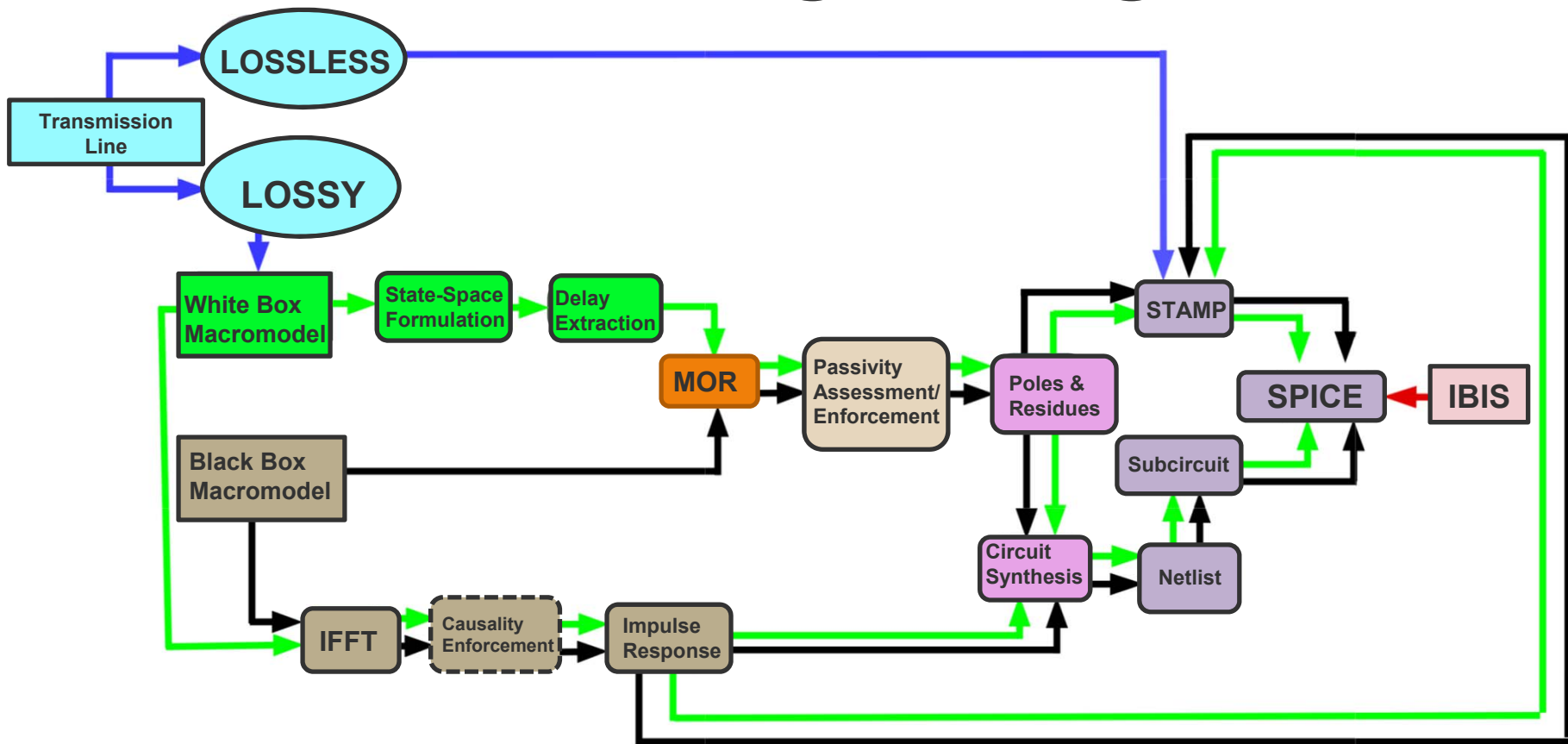
Advantages of Macromodels



- **Protect intellectual property (IP)**
- **Reduce complexity (fewer poles, fewer ports)**
- **Capture frequency dependence**



Interconnect/Macromodel Modeling Strategies



Model Order Reduction

Objective: Approximate frequency-domain transfer function to take the form:

$$H(\omega) = \left[A_1 + \sum_{i=1}^L \frac{a_{1i}}{1 + j\omega / \omega_{cli}} \right]$$

Methods

- AWE – Pade
- Pade via Lanczos (Krylov methods)
- Rational Function
- Chebyshev-Rational function
- **Vector Fitting Method**



Model Order Reduction (MOR)

Question: Why use a rational function approximation?

Answer: because the frequency-domain relation

$$Y(\omega) = H(\omega)X(\omega) = \left[d + \sum_{k=1}^L \frac{c_k}{1 + j\omega / \omega_{ck}} \right] X(\omega)$$

will lead to a time-domain *recursive* convolution:

$$y(t) = dx(t-T) + \sum_{k=1}^L y_{pk}(t)$$

where

$$y_{pk}(t) = a_k x(t-T) \left(1 - e^{-\omega_{ck}T} \right) + e^{-\omega_{ck}T} y_{pk}(t-T)$$

which is very fast!



State-Space Representation

The State space representation of the transfer function is given by

$$\dot{\mathbf{x}}(t) = \mathbf{A}\mathbf{x}(t) + \mathbf{B}u(t)$$

$$\mathbf{y}(t) = \mathbf{C}\mathbf{x}(t) + \mathbf{D}u(t)$$

The transfer function is given by

$$S(s) = \mathbf{C} (s\mathbf{I} - \mathbf{A})^{-1} \mathbf{B} + \mathbf{D}$$

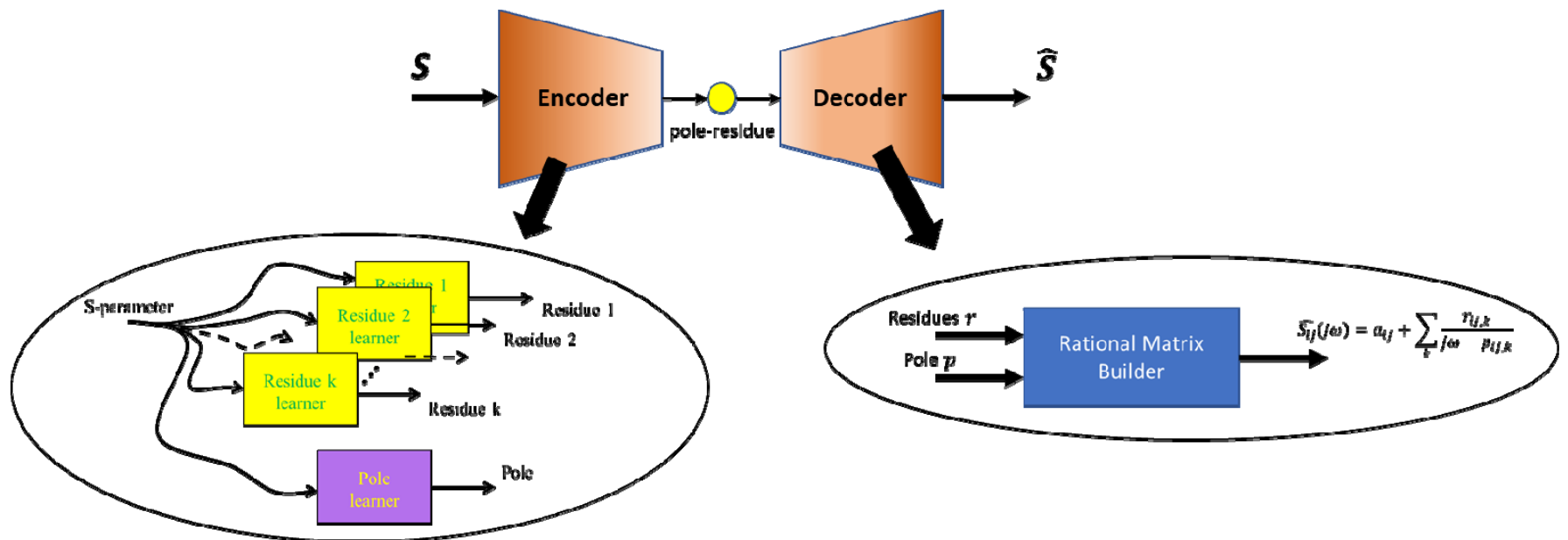
\mathbf{A} , \mathbf{B} , \mathbf{C} and \mathbf{D} are constructed from poles and residues



Looking Forward

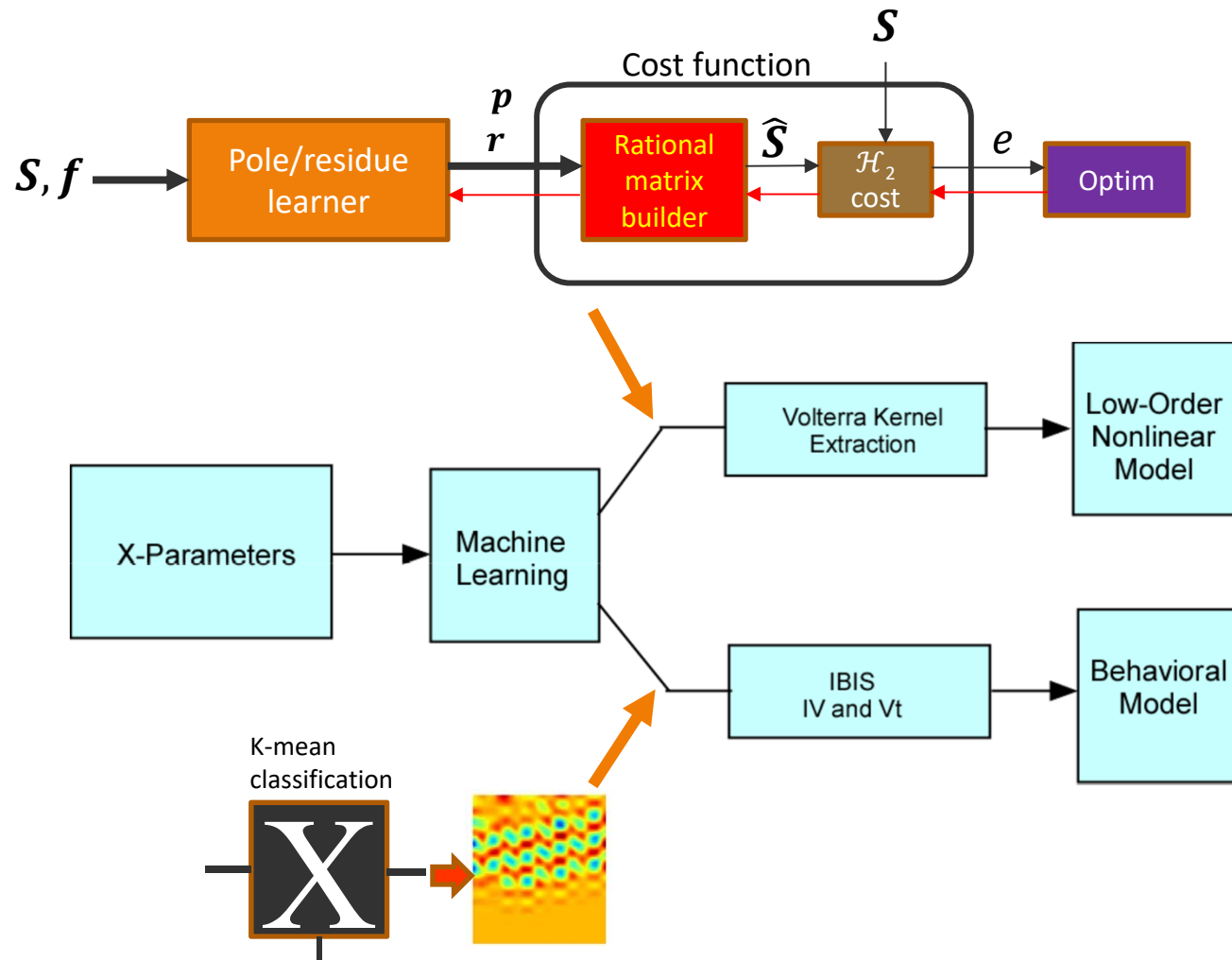
Machine Learning for Macromodeling

- S-parameter feed forward neural network (SFNN) works like an **auto encoder**
 - No need to prepare pole/residue for training. It trains on the input it sees itself.
 - This is the beginning for GAN (Generative Adversarial Networks) for stochastic modeling.



Looking Forward

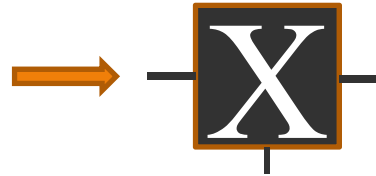
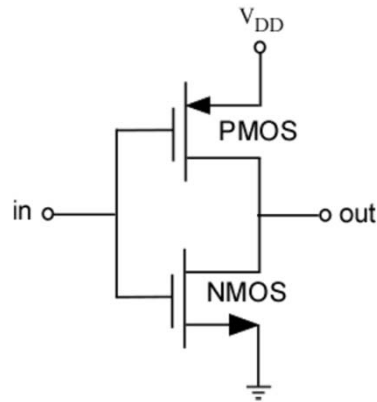
Machine Learning for Buffer Modeling



Looking Forward

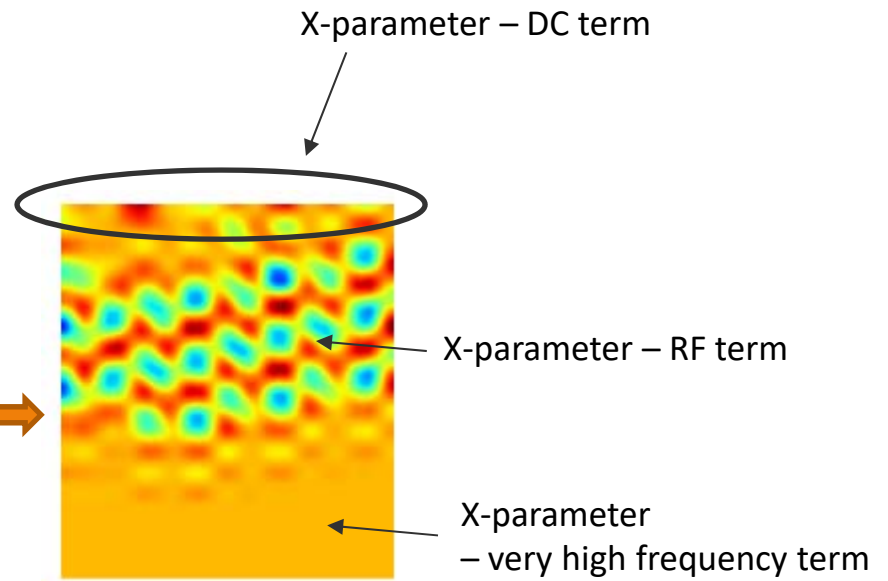
Machine Learning for Buffer Modeling

Heat Map of X-Parameters



One-port X-parameter data is vectorized for all types and all frequencies and mapped to two-dimensional image

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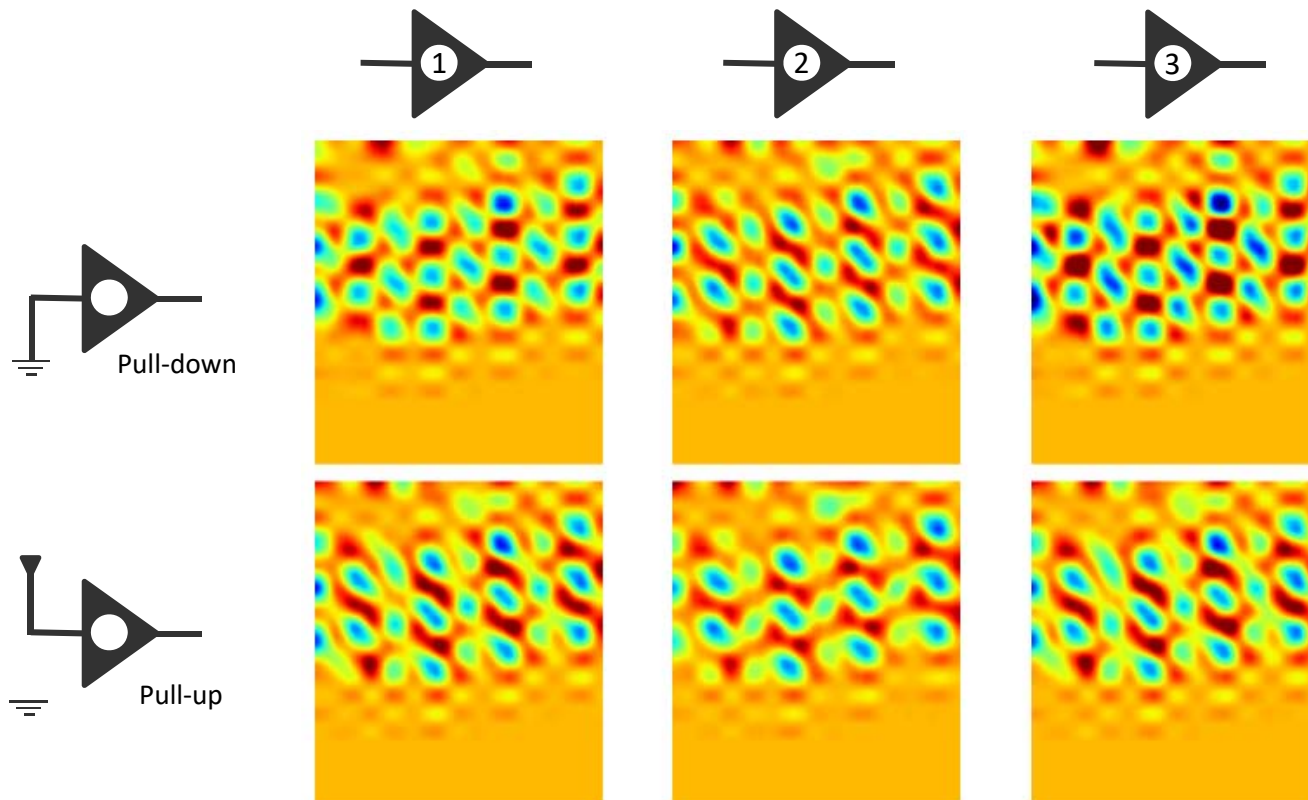


Looking Forward

Machine Learning for Buffer Modeling

X-parameter for IBIS generation

- X-parameter as in the neural network's eye

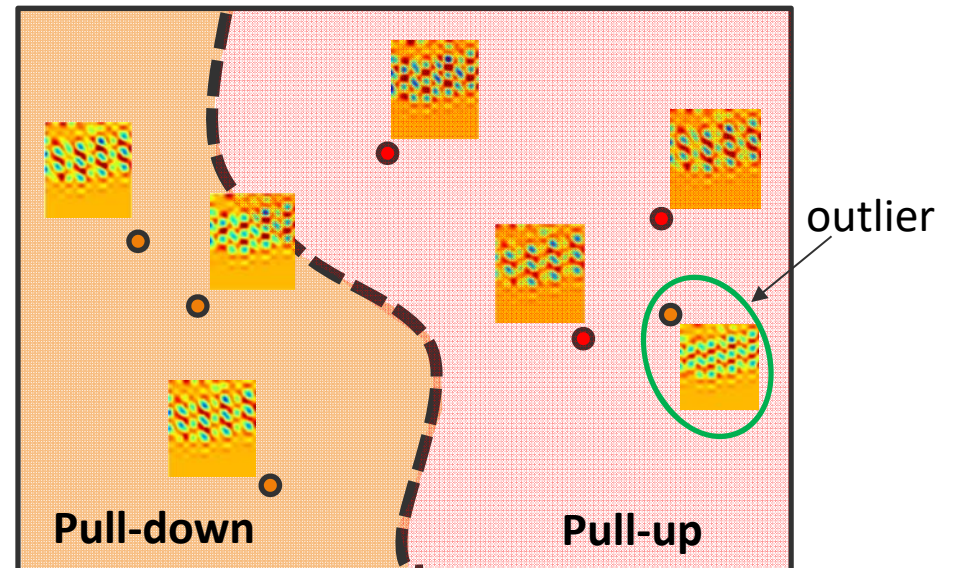


Looking Forward

Machine Learning for Buffer Modeling

X-parameter for IBIS generation

- X parameter for static IBIS curve is generated.
- An unsupervised classification algorithm (as simple as K-mean) is used to verify that pull-up and pull-down data is separable.
- Watch out for potential outliers: recollect data, unusual dynamic nature between pull-up and pull-down.
- Then the X-parameters of pull-up or pull-down configurations and its corresponding static curves are used to train a feed forward neural network (FFN).



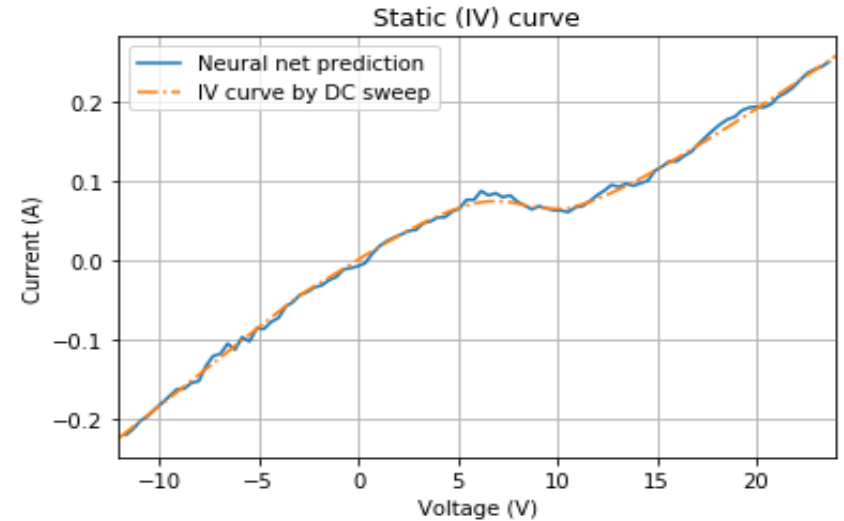
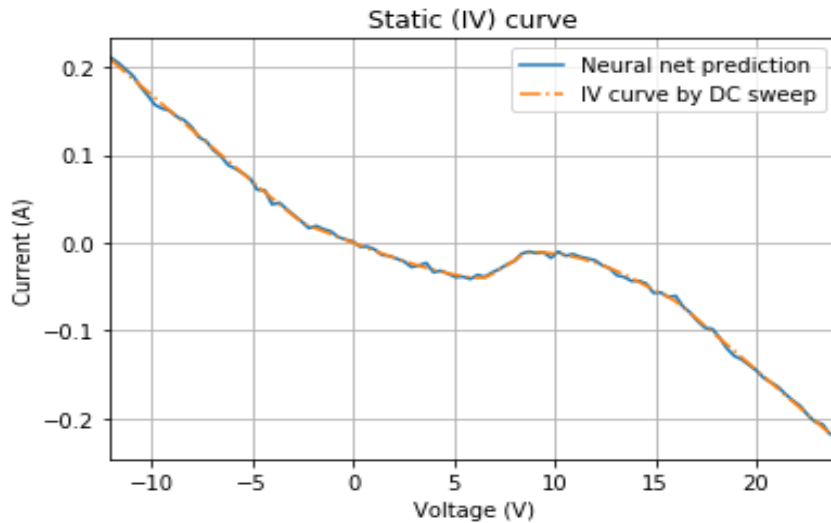
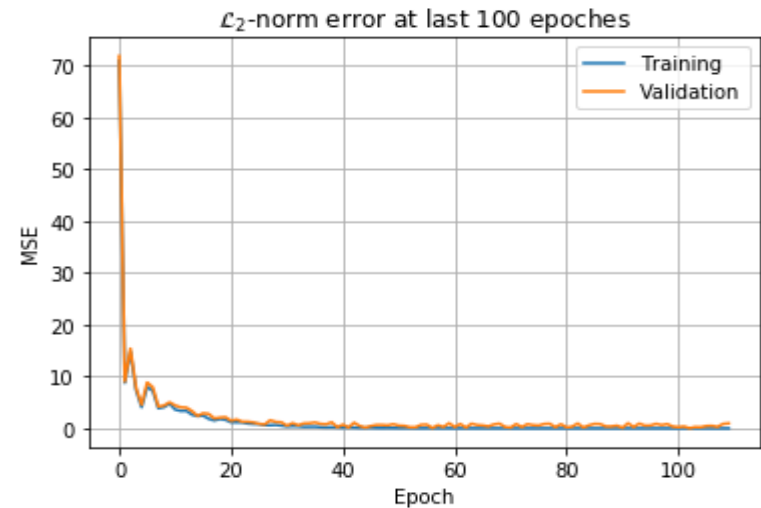
X-parameter in separable hyperspace



Looking Forward

Machine Learning for Buffer Modeling

- Use importance sampling with assumed Gaussian distribution to bootstrap the result due to limited number of training samples.
- Need more (a lot more) practical data for further investigations.



\mathcal{L}_2 -norm error: $\sim e^{-4}$

\mathcal{L}_2 -norm error: $\sim e^{-4}$



Looking Forward

- Machine learning approach to extract poles and residues
- X-parameters for IBIS models
- Machine learning and X parameters for IBIS
- Volterra series expansion of X parameters

