

# Circuit Synthesis of Multiport Networks from Passive Poles and Residues

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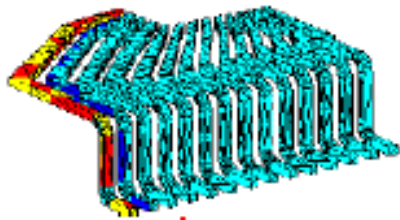
**Siegen, Germany**

**Virtual**

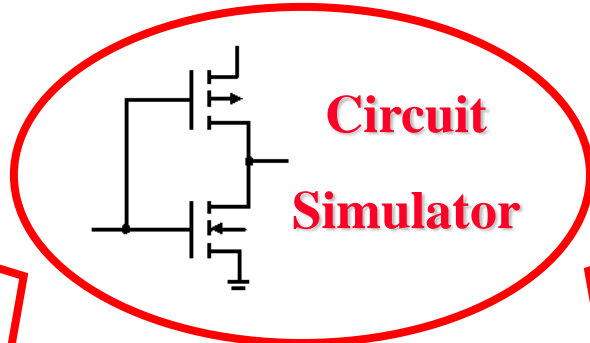
**May 26, 2022**

# Interconnect Structures

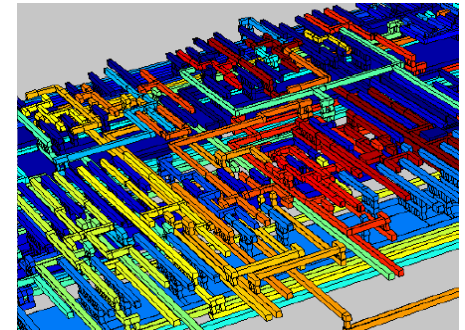
Crosstalk  
Couplings  
Reflections  
Losses  
Dispersion



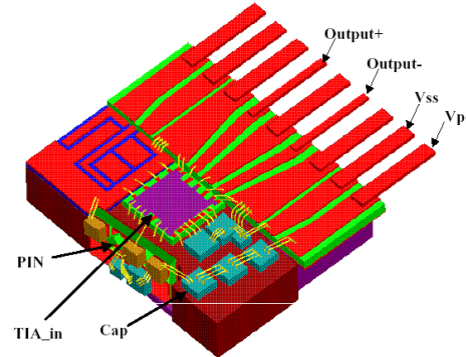
Packages



Ground Noise  
Nonlinear effects  
Radiation, EMI



Interconnects

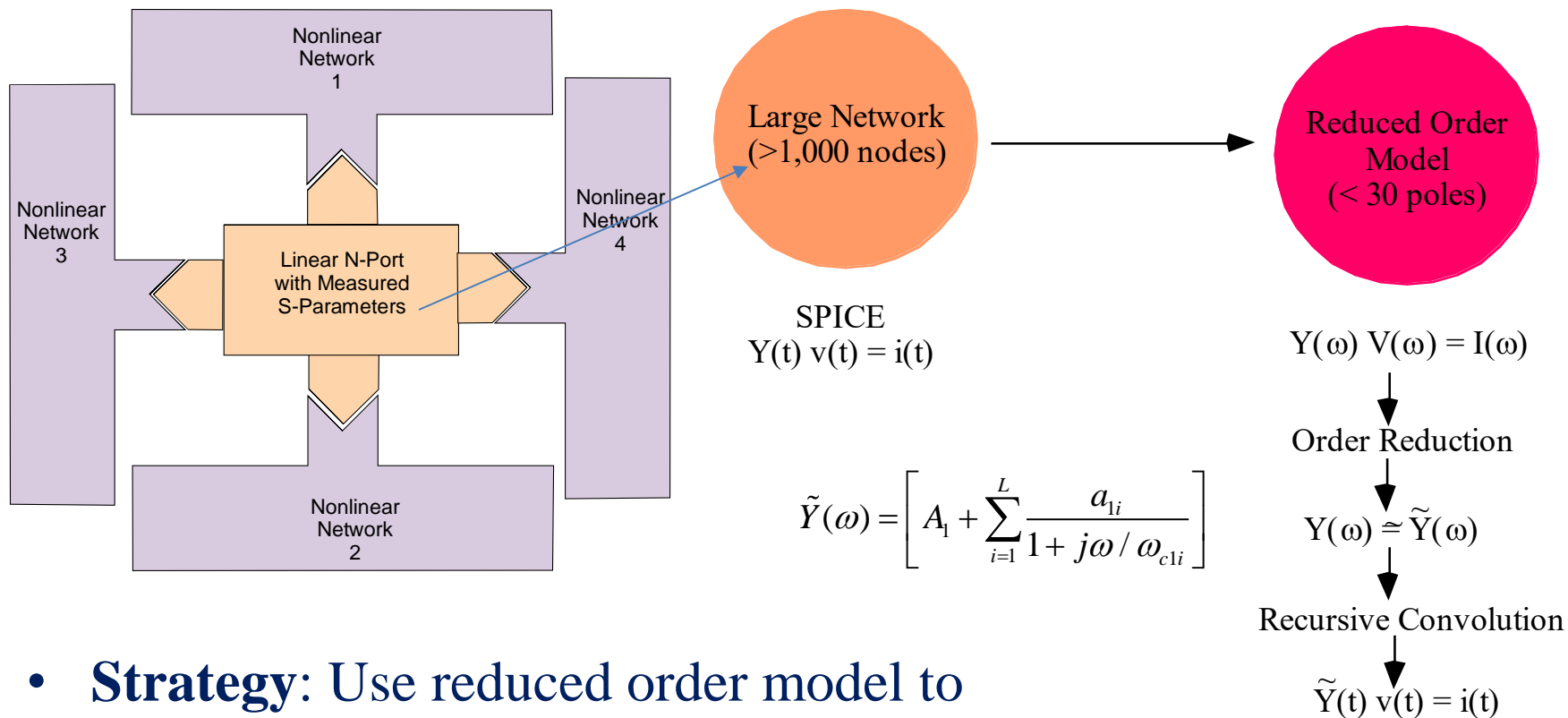


Courtesy of [http://www.ansoft.com/hfworkshop03/Weimin\\_Sun\\_Vitesse.pdf](http://www.ansoft.com/hfworkshop03/Weimin_Sun_Vitesse.pdf)

26<sup>th</sup> IEEE Workshop On Signal and Power Integrity

European IBIS Summit – May 26, 2022

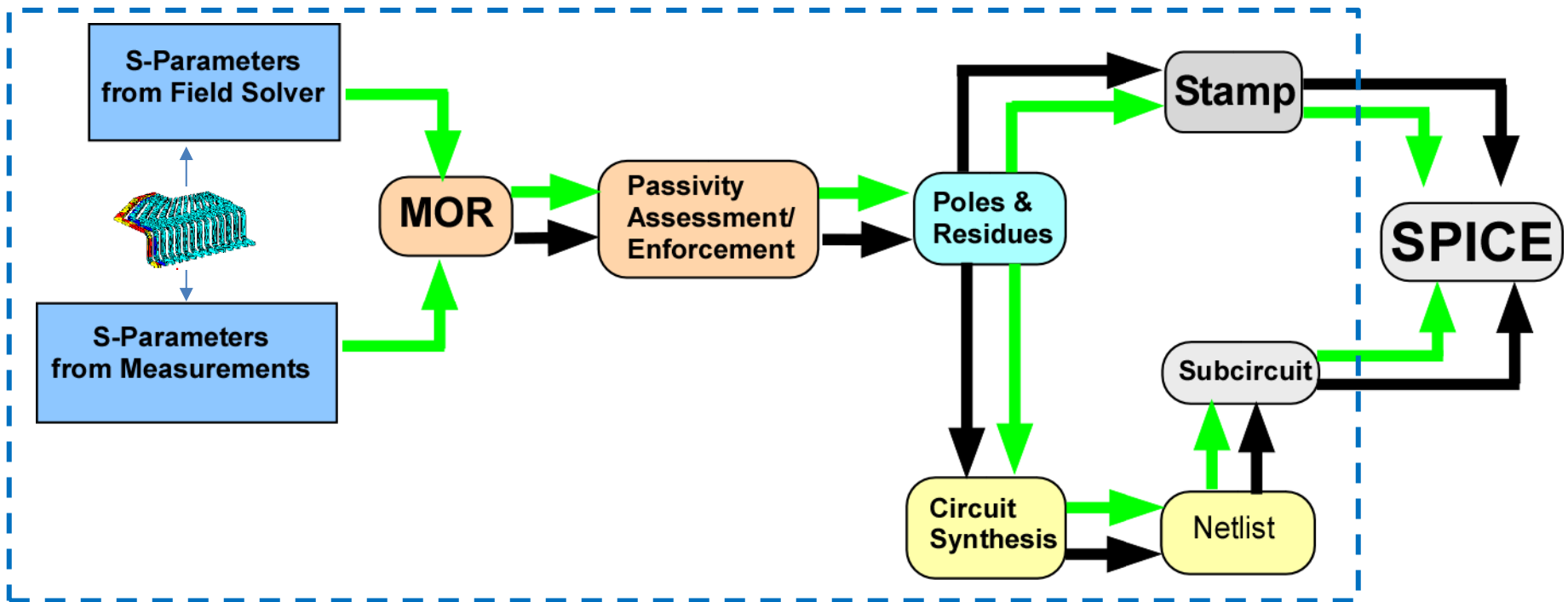
# Model-Order Reduction



- **Strategy:** Use reduced order model to minimize computation time.

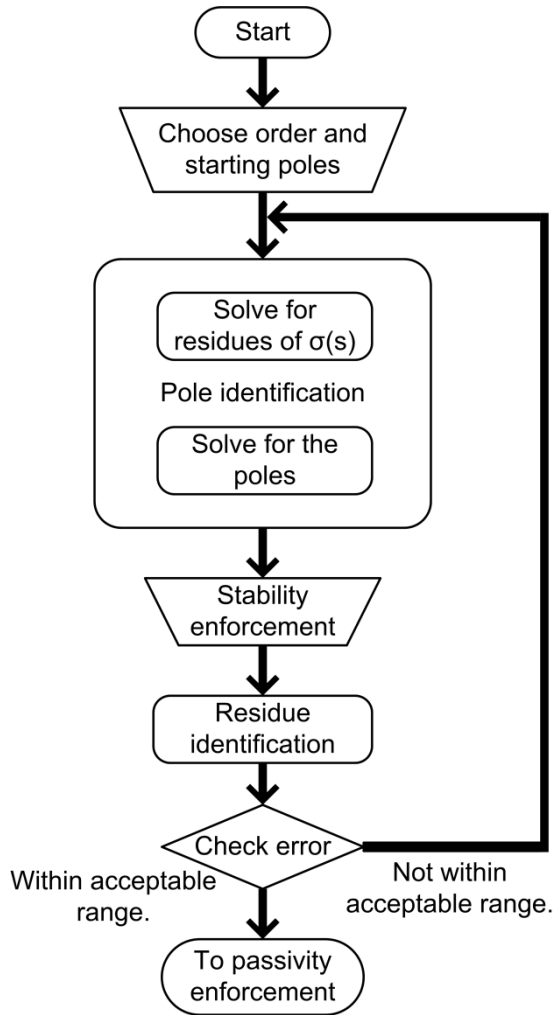
$$\tilde{Y}(\omega) \square Y(\omega)$$

# Model-Order Reduction



- **Objective:** Incorporate frequency dependence into time-domain simulator
- **Approaches:** 1) Direct integration of code into SPICE – 2) Generation of SPICE-compatible netlist

# MOR via Vector Fitting



- Rational function approximation:

$$f(s) \approx \sum_{n=1}^N \frac{c_n}{s - a_n} + d + sh$$

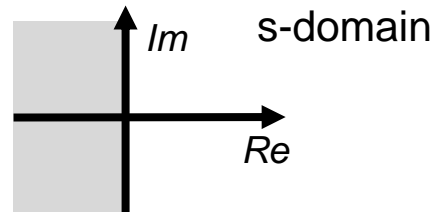
- Introduce an unknown function  $\sigma(s)$  that satisfies:

$$\begin{bmatrix} \sigma(s)f(s) \\ \sigma(s) \end{bmatrix} \approx \begin{bmatrix} \sum_{n=1}^N \frac{c_n}{s - \tilde{a}_n} + d + sh \\ \sum_{n=1}^N \frac{\tilde{c}_n}{s - \tilde{a}_n} + 1 \end{bmatrix}$$

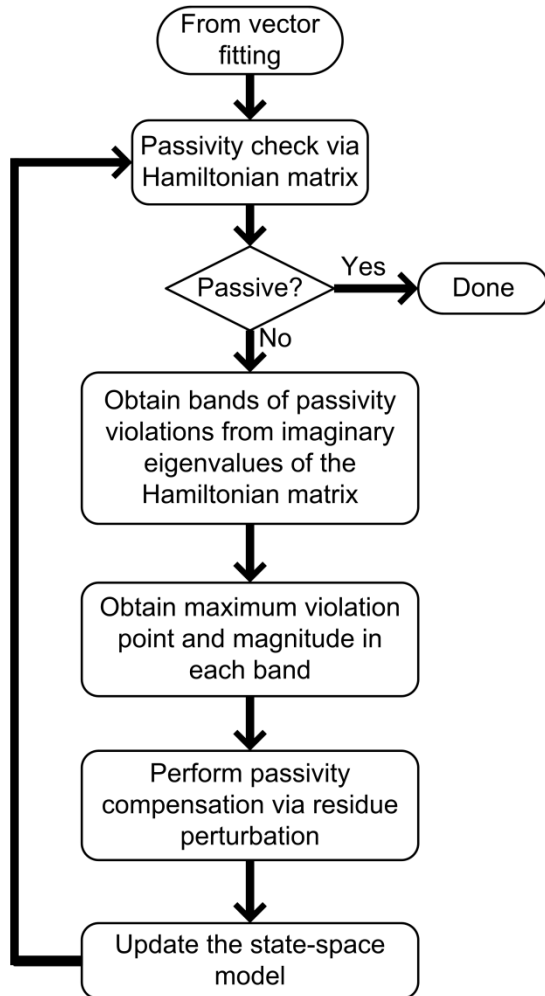
- Poles of  $f(s)$   
= zeros of  $\sigma(s)$ :

$$f(s) \approx \frac{\sum_{n=1}^N \frac{c_n}{s - \tilde{a}_n} + d + sh}{\sum_{n=1}^N \frac{\tilde{c}_n}{s - \tilde{a}_n} + 1} = \frac{\prod_{n=1}^{N+1} (s - z_n)}{\prod_{n=1}^N (s - \tilde{z}_n)}$$

- Flip unstable poles into the left half plane.



# Passivity Enforcement



- State-space form:

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

- Hamiltonian matrix:

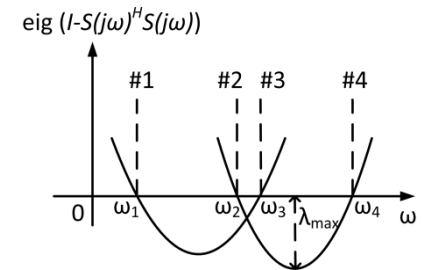
$$M = \begin{bmatrix} A + BKD^T C & BKB^T \\ -C^T LC & -A^T - C^T DKB^T \end{bmatrix}$$

$$K = (I - D^T D)^{-1} \quad L = (I - DD^T)^{-1}$$

- Passive if  $M$  has no imaginary eigenvalues.

- Sweep:

$$\text{eig}(I - S(j\omega)^H S(j\omega))$$



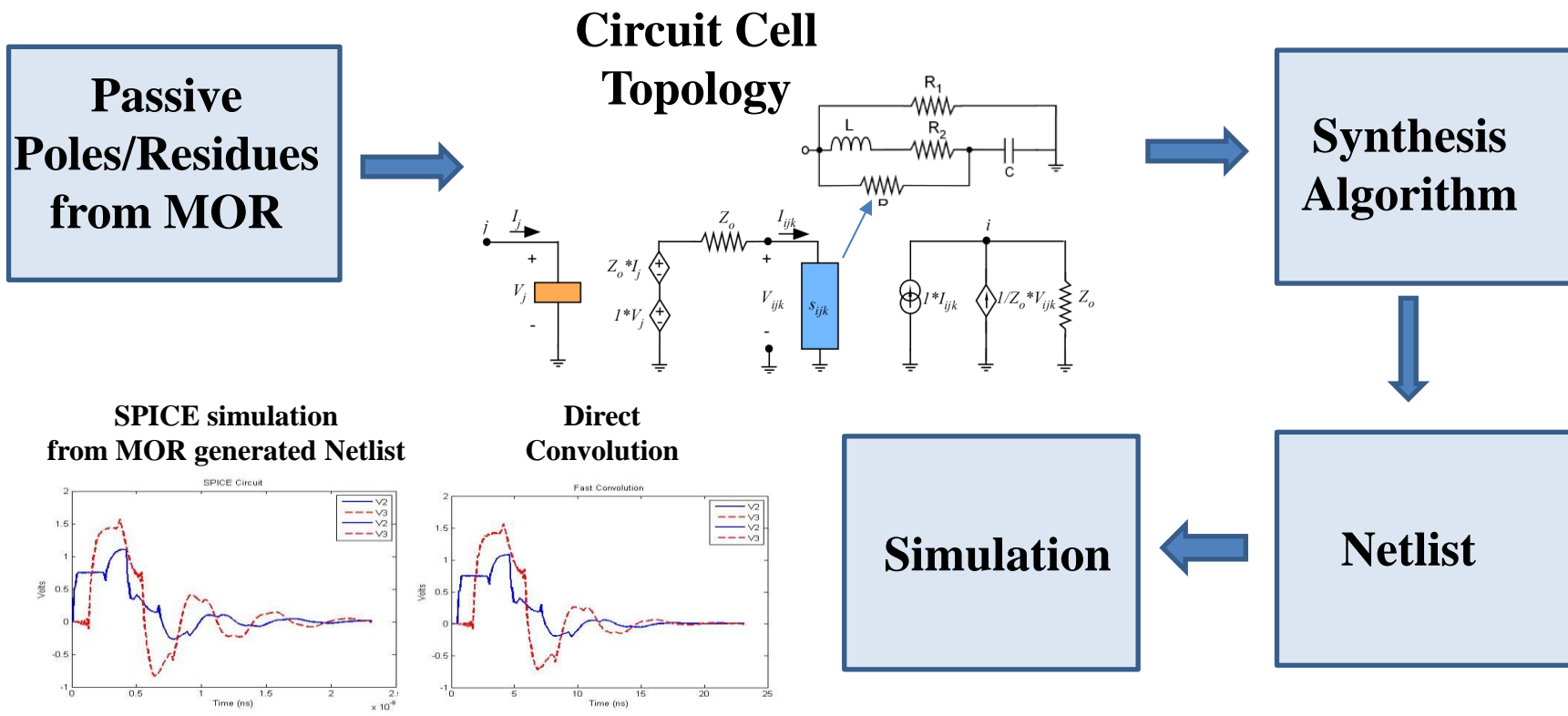
- Quadratic programming:

– Minimize (change in response) subject to (passivity compensation).

$$\min(\text{vec}(\Delta C)^T H \text{vec}(\Delta C)) \quad \text{subject to} \quad \Delta \lambda = G \cdot \text{vec}(\Delta C).$$

# SPICE Netlist Synthesis

- Goal is to generate (using pole/residue information) a circuit netlist that will exhibit the same (frequency-dependent) behavior as that of the S-parameters of connector under study



# Equivalent-Circuit Extraction

*Macromodel is curve-fit to take the form*

$$S(s) = d + \sum_{k=1}^L \frac{r_k}{s - p_k}$$

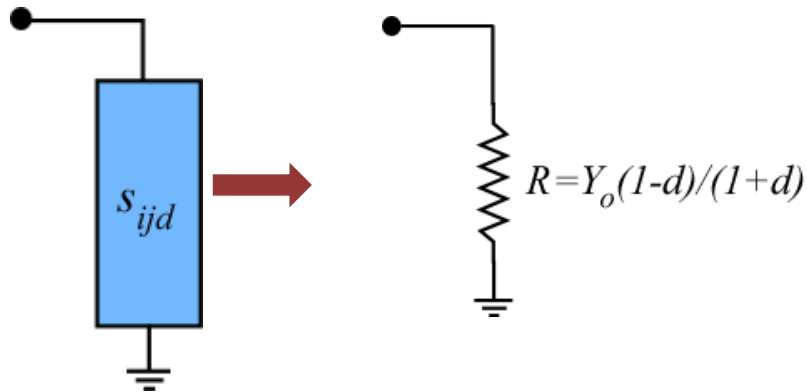
*Need to find equivalent circuit associated with*

- Constant term  $d$
- Real Poles
- Complex Poles



# Equivalent-Circuit Extraction

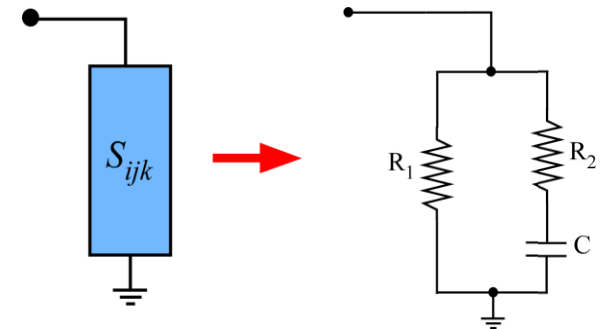
## Constant Term



$$R = Y_o \left( \frac{1-d}{1+d} \right)$$

$$a = p_k + r_k, \quad \text{and} \quad b = p_k - r_k$$

## Real Poles



$$R_2 = \frac{-1}{bC}$$

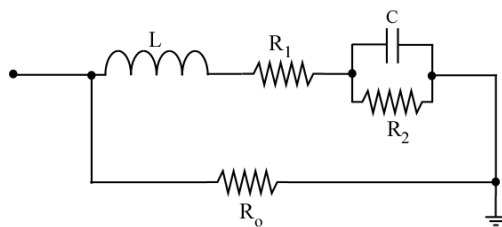
$$R_1 = -R_2 - \frac{1}{aC}$$

$$C = -\frac{(b-a)}{b^2 Z_o}$$

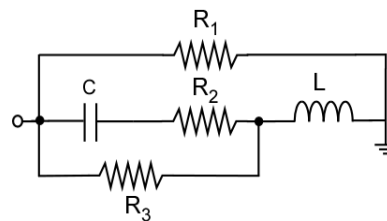
# Realization – Complex Poles

There are several circuit topologies that will work

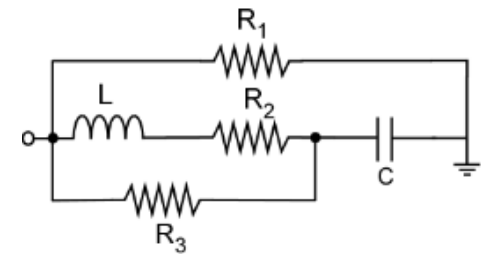
Model 1



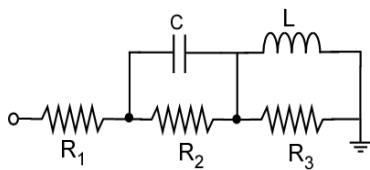
Model 8



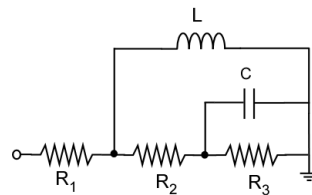
Model 9



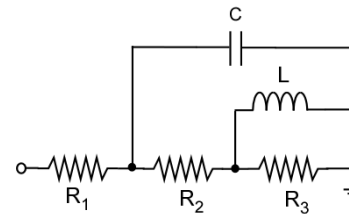
Model 11



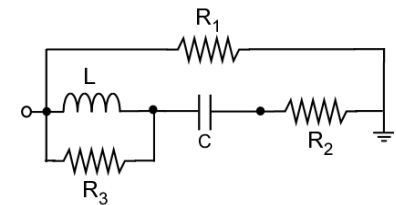
Model 12



Model 13



Model 10



# Netlist from Poles & residues

\*Poll 2-port S-parameter circuit model

\* 14 -pole approximation

```
.subckt Poll 42000 56000
vsens42001 42000 42001 0.0
vsens56001 56000 56001 0.0
```

\*subcircuit for s[1][1]

\*complex residue-pole pairs for S[1][1] at k= 1 -> 1st pole: -4.8961e+00 3.6506e+01 residue: 2.1006e-01 -2.8971e-01

\* -> 2nd pole: -4.8961e+00 -3.6506e+01 residue: 2.1006e-01 2.8971e-01

\*circuit type = 9

elc1 1 0 42001 0 1.0

hc2 2 1 vsens42001 50.0

rtersc3 2 3 50.0

vp4 3 4 0.0

r1cd5 4 0 5.17406e+01

l1cd5 4 5 -1.25500e-08

r2cd6 5 6 -1.30103e+03

c1cd6 6 0 -7.19920e-15

r3cd6 4 6 1.48633e+03

\*complex residue-pole pairs for S[1][1] at k= 2 -> 1st pole: -1.3039e+00 2.7679e+01 residue: -4.3856e-01 -1.9087e+00

\* -> 2nd pole: -1.3039e+00 -2.7679e+01 residue: -4.3856e-01 1.9087e+00

rtersc9 8 9 50.0

:

:

gs196 0 56001 196 0 0.020

rnort42001 42001 0 5.00000e+01

rnort56001 56001 0 5.00000e+01

.ends Poll

\*main circuit

rge1 1 2 50.0

x1 2 3 Poll

vin 1 0 pulse (0 1 0.20000ns 0.10000ns 0.10000ns 2.00000ns 6.00000ns)

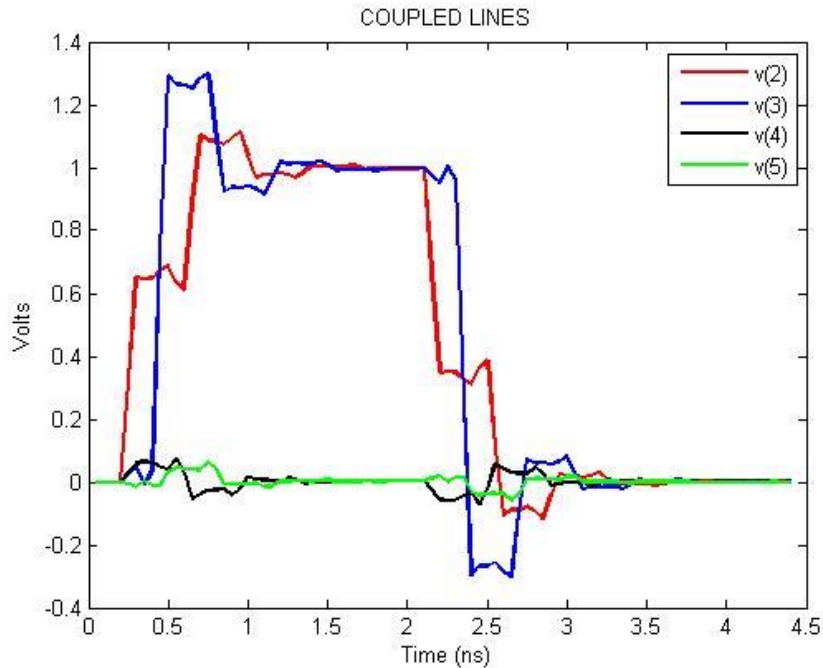
rport2 3 0 50000.0000000

.tran 0.00039ns 7.00000ns

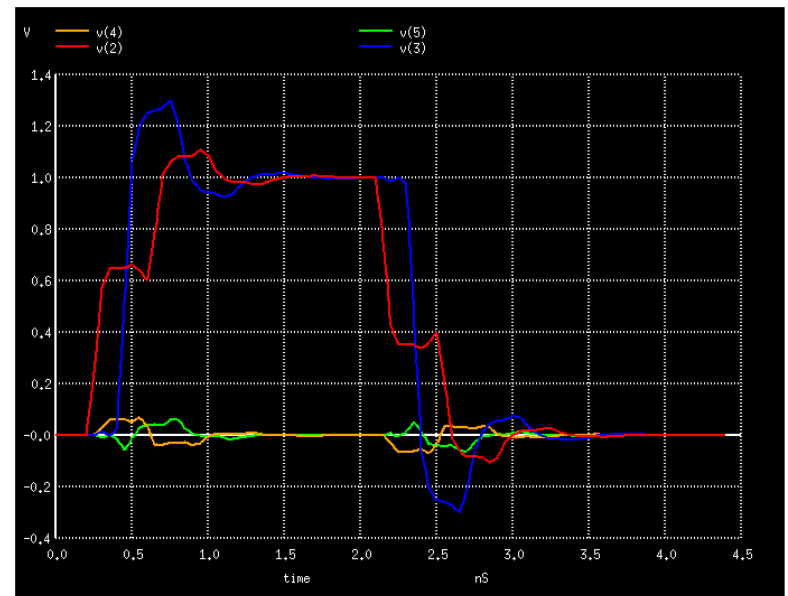
.end

# 4-Port Network

Direct

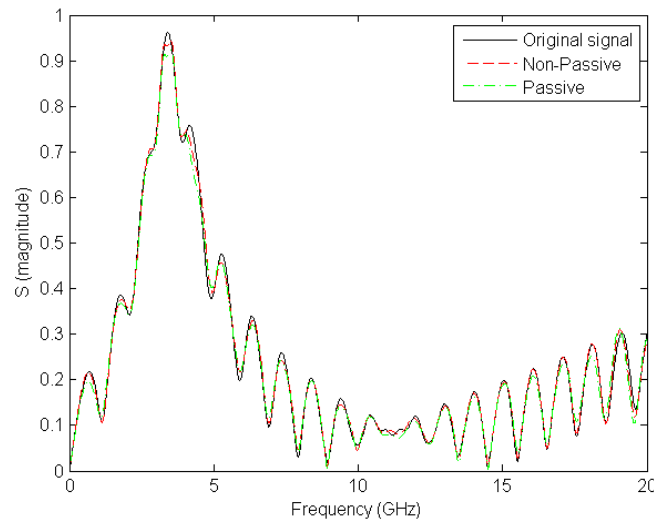


SPICE simulation  
Using generated netlist  
(Method 2)



# Model-Order Reduction

- Start with S parameters from field solver
- Use vector fitting to get poles & residues
- Perform assessment via Hamiltonian
- Enforcement: Residue Perturbation Method
- Simulation: Recursive convolution → **Fast**



Number of Ports	Order	CPU-Time
4	20	1.7 secs
6	32	3.69 secs
10	34	8.84 secs
20	34	33 secs
40	50	142 secs
80	12	255 secs

# Review of some classic synthesis approaches for S matrix in pole-residue form\*

1. (PI network for Y matrix)
2. PI network for S by Y + VCVS + CCVS
3. State-space S
4. State-space S-to-Y then PI
5. Pole-residue S-as-Y
6. Direct pole-residue specification

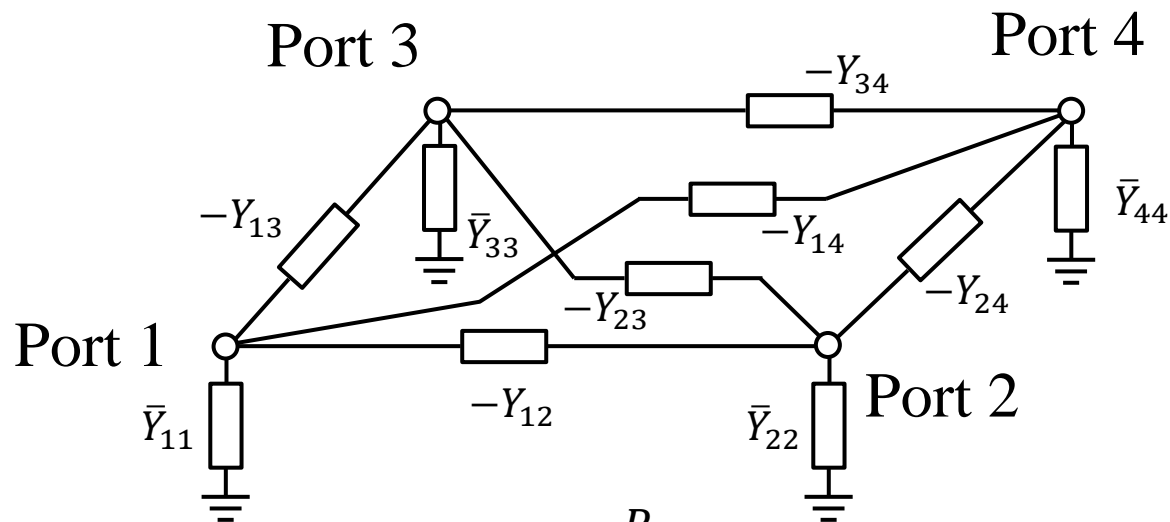
$$S_{ij} = d^{(ij)} + \sum_{k=1}^N \frac{r_k^{(ij)}}{s - p_k^{(ij)}} = d^{(ij)} + \sum_{k=1}^N S_{ij,k}$$

\* Chiu-Chih Chou, José E. Schutt-Ainé, "Equivalent Circuit Synthesis of Multiport S Parameters in Pole-Residue Form", *IEEE Transactions on Components, Packaging and Manufacturing Technology*, Volume 11, Issue: 11, pp. 1971-1979, 2021, November 2021

## Model 1. PI network for Y matrix (1/2)

$$Y_{ij} = d^{(ij)} + \sum_{k=1}^N \frac{r_k^{(ij)}}{s - p_k^{(ij)}}$$

Pole-residue Y matrix  $\rightarrow$  PI model  
(direct correspondence)

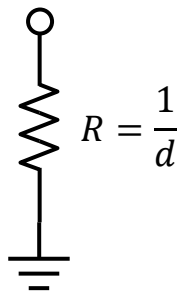


$$\bar{Y}_{ii} = \sum_{j=1}^P Y_{ij}$$

# Model 1. PI network for Y matrix (2/2) (no controlled sources, but have negative elements)

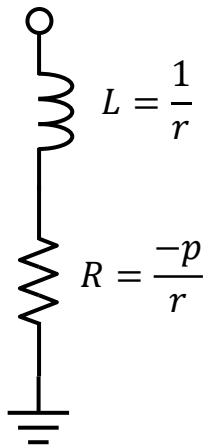
Constant

$$Y = d$$



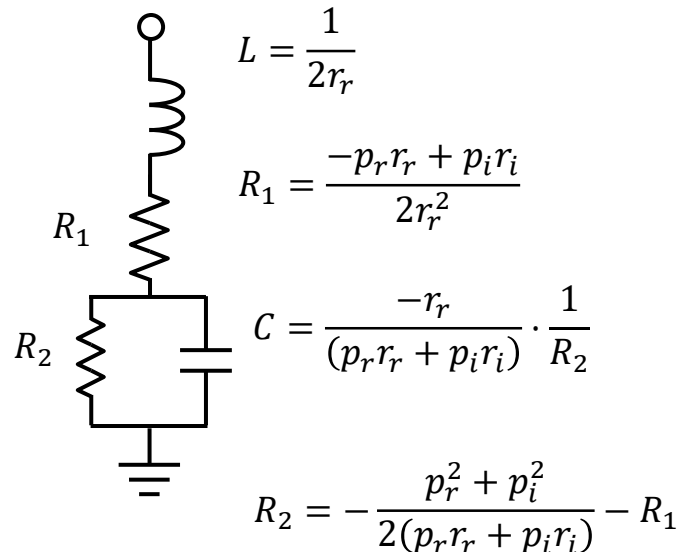
A real pole

$$Y = \frac{r}{s - p}$$



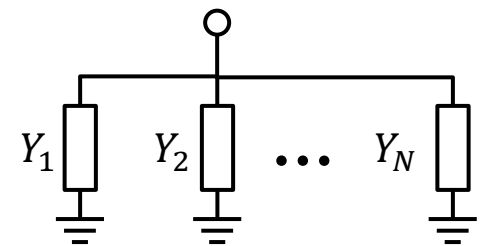
A pair of complex conjugate poles (RLCR)

$$Y = \frac{r}{s - p} + \frac{r^*}{s - p^*}$$



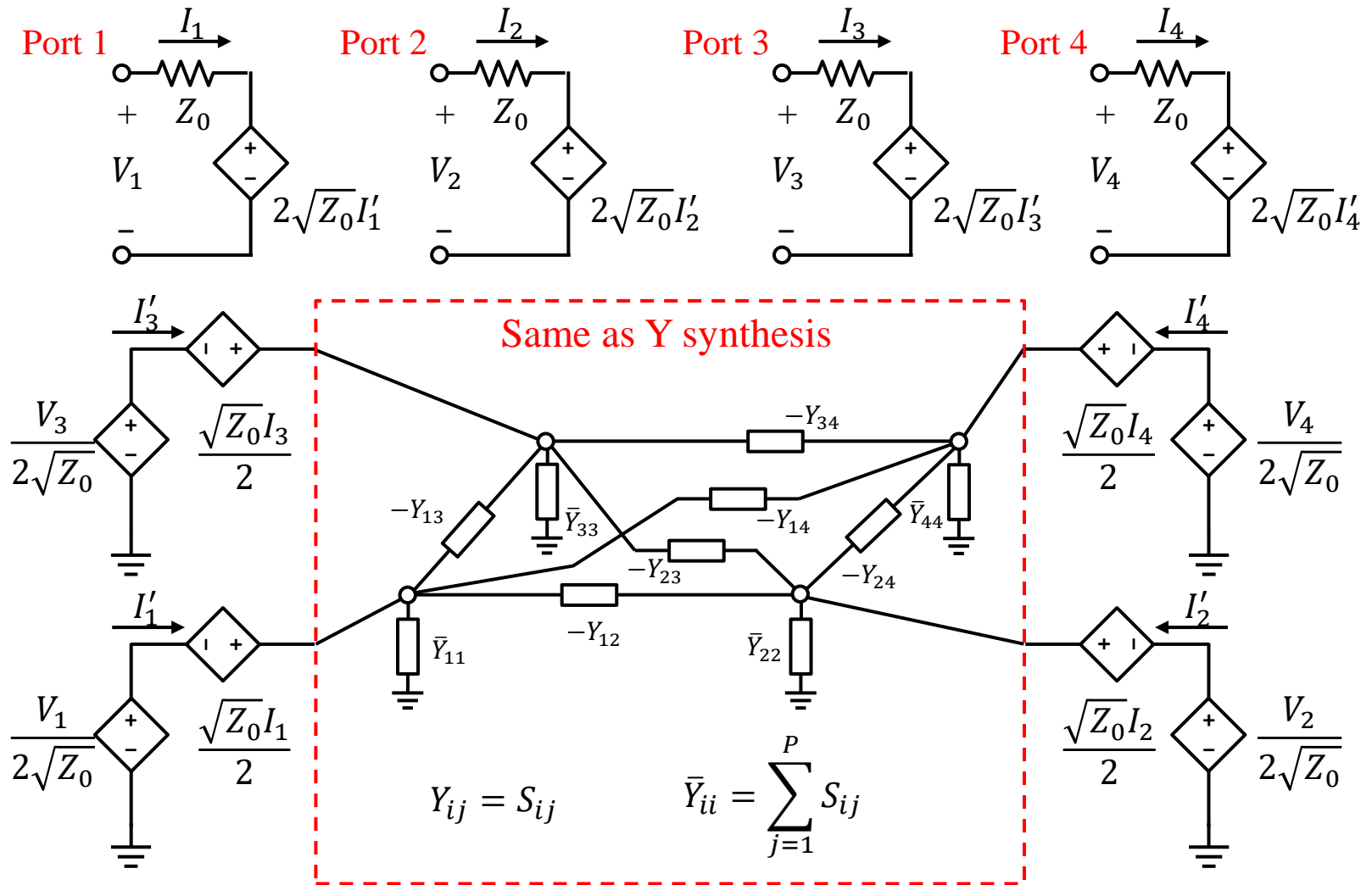
N pole-residue pairs

$$Y = \sum_{k=1}^N Y_k$$



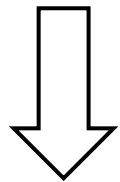


# Model 2. PI network for S by Y + VCVS + CCVS



# Model 3. State-space S (1/2) (a common cross-platform topology)

$$S_{ij} = d^{(ij)} + \sum_{k=1}^N \frac{r_k^{(ij)}}{s - p_k^{(ij)}}$$



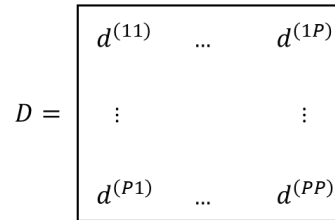
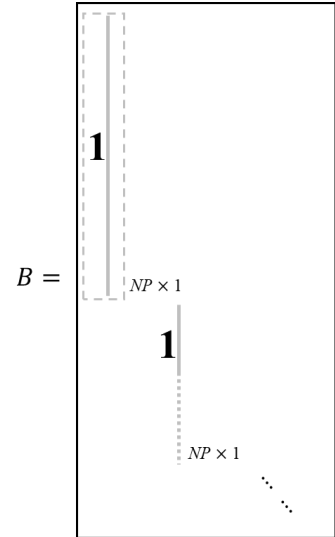
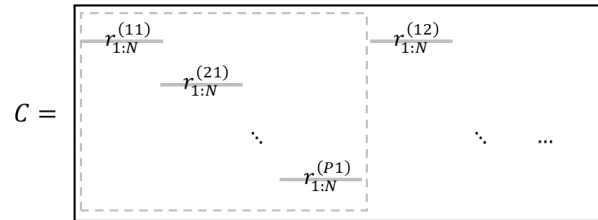
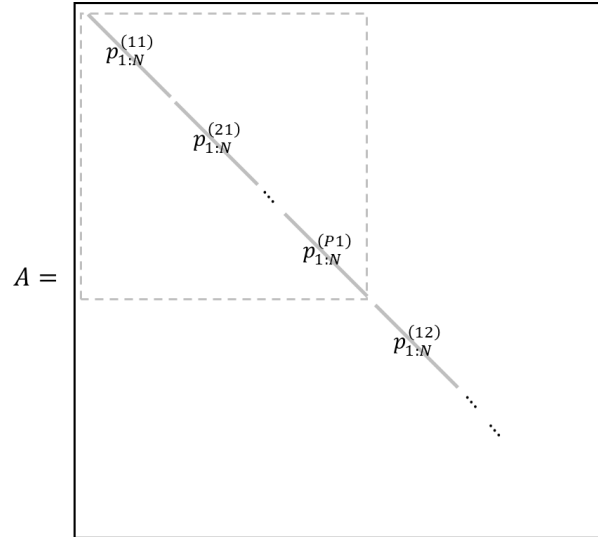
Pole-residue  
to state-space

$$A = \text{diag}_{\substack{j=1 \dots P \\ i=1 \dots P \\ k=1 \dots N}} p_k^{(ij)}$$

$$B_{nj} = 1_{\{(j-1)NP < n \leq jNP\}}$$

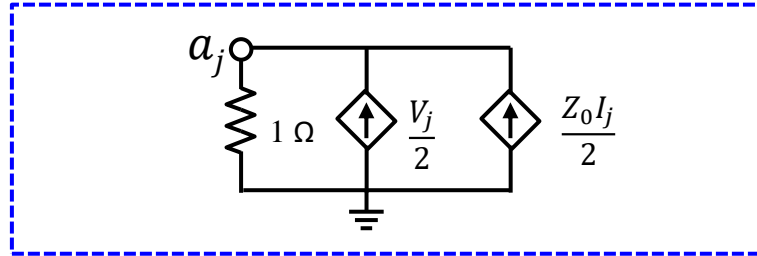
$$C_{in} = r_k^{(ij)} \cdot 1_{\{n = (j-1)NP + (i-1)N + k\}}$$

$$D_{ij} = d^{(ij)}$$

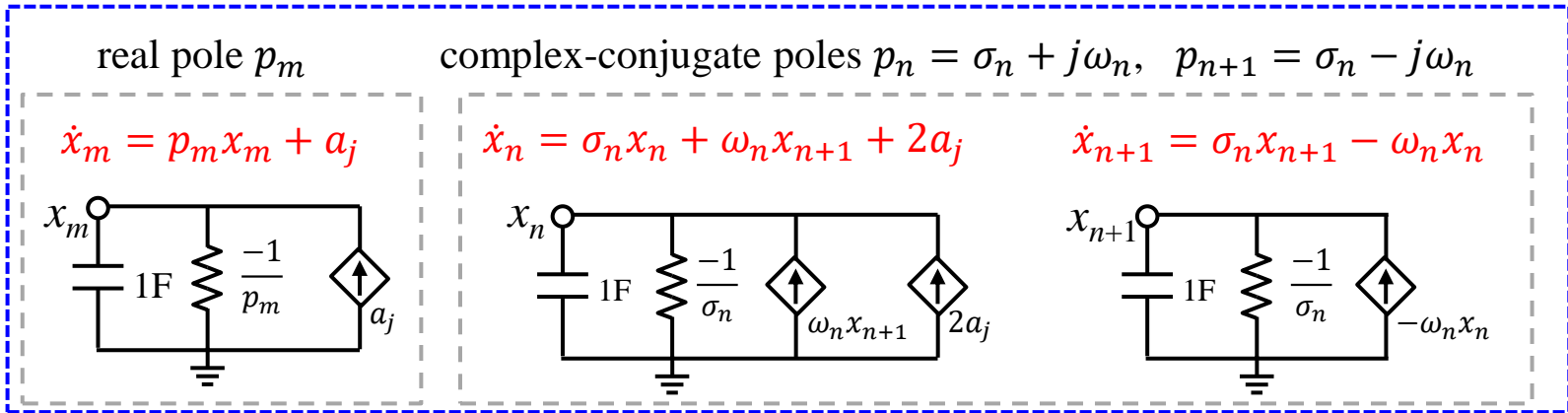


# Model 3. State-space S (2/2)

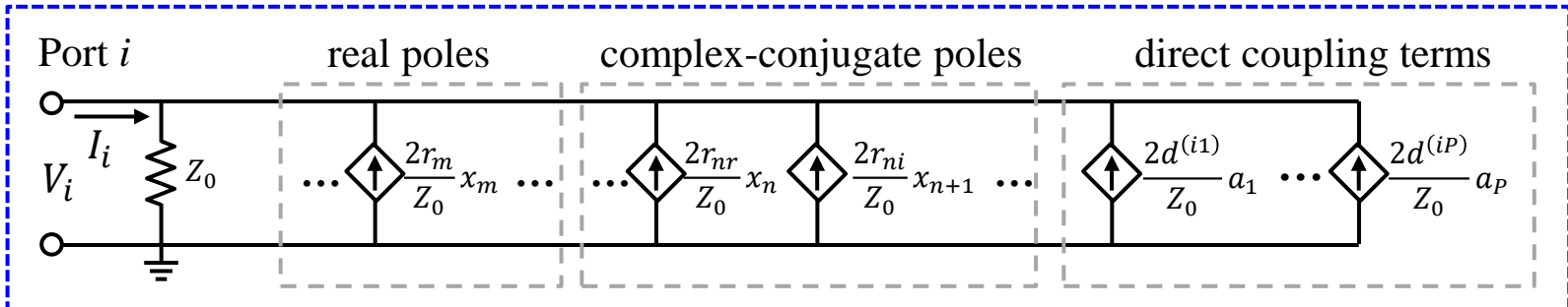
Input equations  
(incident wave):



State equations:



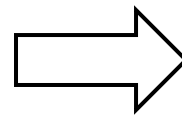
Output equations:



# Model 4. State-space S to Y then PI (no controlled sources needed)

## State-space for S matrix

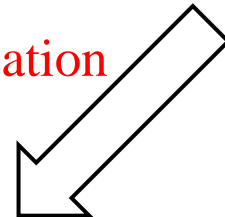
$$\left\{ \begin{array}{l} A = \text{diag } p_k^{(ij)} \\ \quad \begin{array}{l} j=1\dots P \\ i=1\dots P \\ k=1\dots N \end{array} \\ B_{nj} = 1_{\{(j-1)NP < n \leq jNP\}} \\ C_{in} = r_k^{(ij)} \cdot 1_{\{n = (j-1)NP + (i-1)N + k\}} \\ D_{ij} = d^{(ij)} \end{array} \right.$$



## State-space for Y matrix

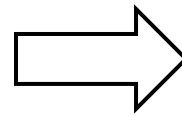
$$\left\{ \begin{array}{l} A' = A - B(I + D)^{-1}C \\ B' = \frac{1}{\sqrt{Z_0}} B(I + D)^{-1} \\ C' = \frac{-2}{\sqrt{Z_0}} (I + D)^{-1}C \\ D' = \frac{1}{Z_0} (I - D)(I + D)^{-1} \end{array} \right.$$

## Diagonalization

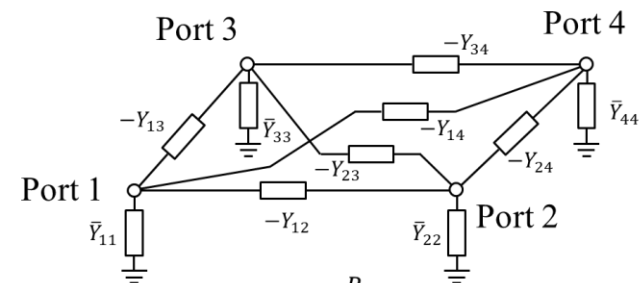


## Pole-residue for Y matrix

$$Y_{ij} = d^{(ij)} + \sum_{k=1}^N \frac{r_k^{(ij)}}{s - p_k^{(ij)}}$$



## PI model

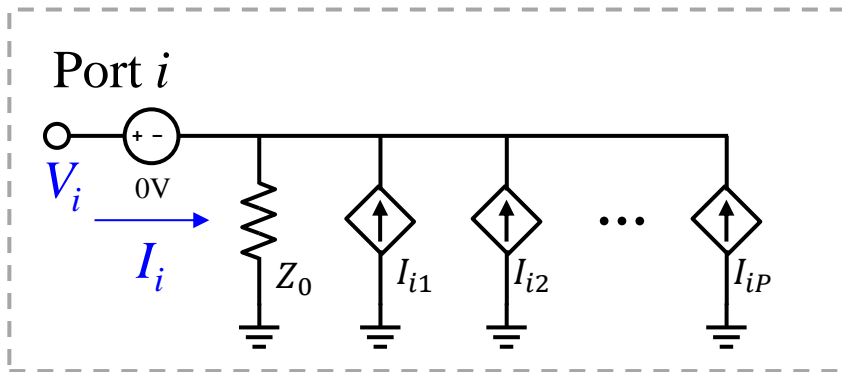


$$\bar{Y}_{ii} = \sum_{j=1}^P Y_{ij}$$

Problem:  $(I + D)$  may be singular!

# Model 5. Pole-residue S-as-Y (minimized for SISO pole)

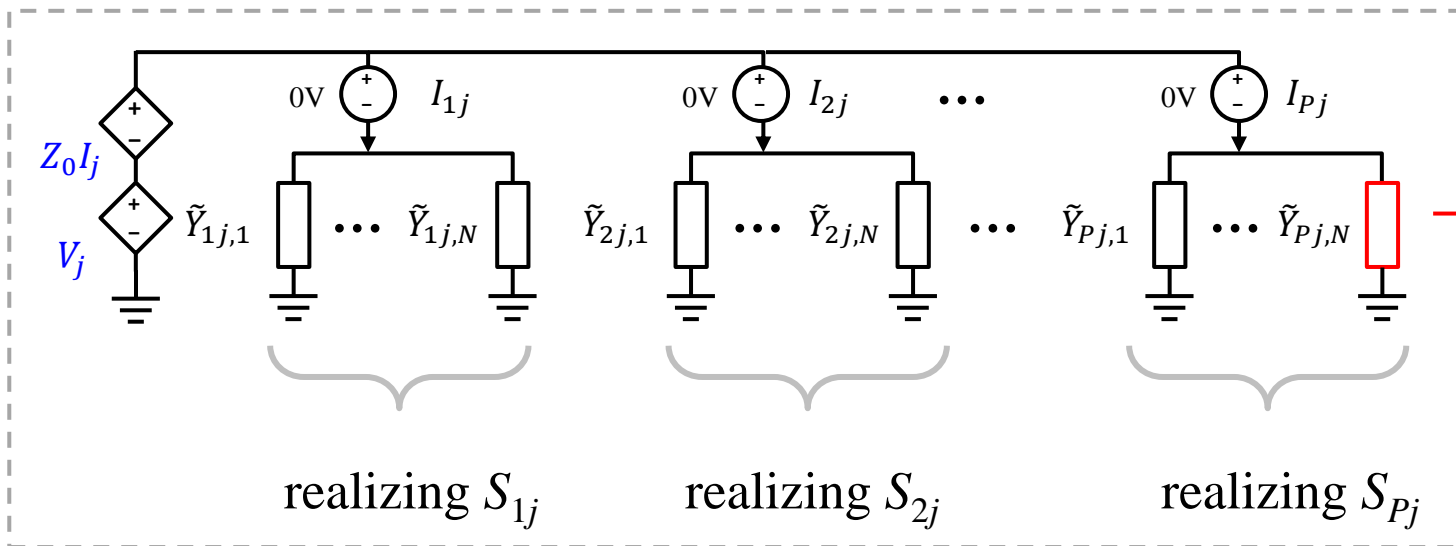
Port sections:  $i = 1, 2, \dots, P$



Use the same approach as model 1 (Y branch)

$$\tilde{Y}_{ij,k} \triangleq \frac{1}{Z_0} S_{ij,k}$$

Intermediate stages:  $j = 1, 2, \dots, P$

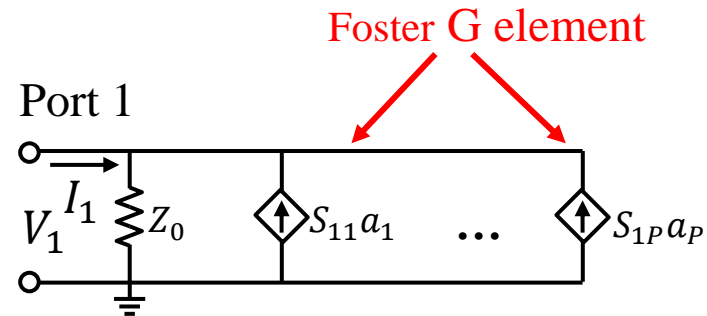
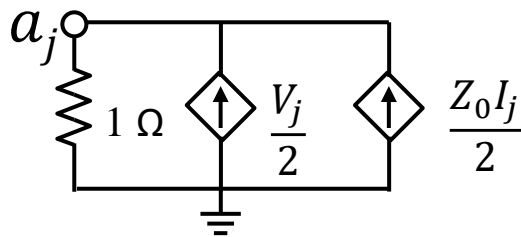


# Model 6. Direct pole-residue specification (permit recursive convolution)

$$S_{ij} = d^{(ij)} + \sum_{k=1}^N \frac{r_k^{(ij)}}{s - p_k^{(ij)}}$$

Not all simulator support this format!

Incident wave calculator for each port



```

Gs_1_1  gnd_0  p_1  FOSTER  inc_1  0  -5.692434755414126e-03  0
+ ( -2.439150431856222e+04, 0 ) / ( -4.960476041619210e+07, 0 )
+ ( 6.160731778543656e+07, 0 ) / ( -1.714170394664603e+09, 0 )
+ ( -1.894788422520538e+07, 5.662293766458602e+07 ) / ( -1.67218
+ ( 8.713966348296802e+07, -8.139622129292254e+07 ) / ( -1.84733
+ ( 2.617173411981527e+08, 1.358464434932994e+08 ) / ( -2.17708
+ ( 1.633543792451439e+07, 6.271573488187740e+08 ) / ( -2.57889
+ ( -7.925453224991798e+08, -3.731457479447733e+07 ) / ( -2.81115
+ ( -1.393416945756004e+08, -3.078398088322048e+08 ) / ( -2.26115
+ ( 3.612283069470346e+06, -4.993908414386742e+06 ) / ( -1.357632
+ ( -1.359750933146977e+07, -2.875752648146065e+08 ) / ( -2.39584
    
```

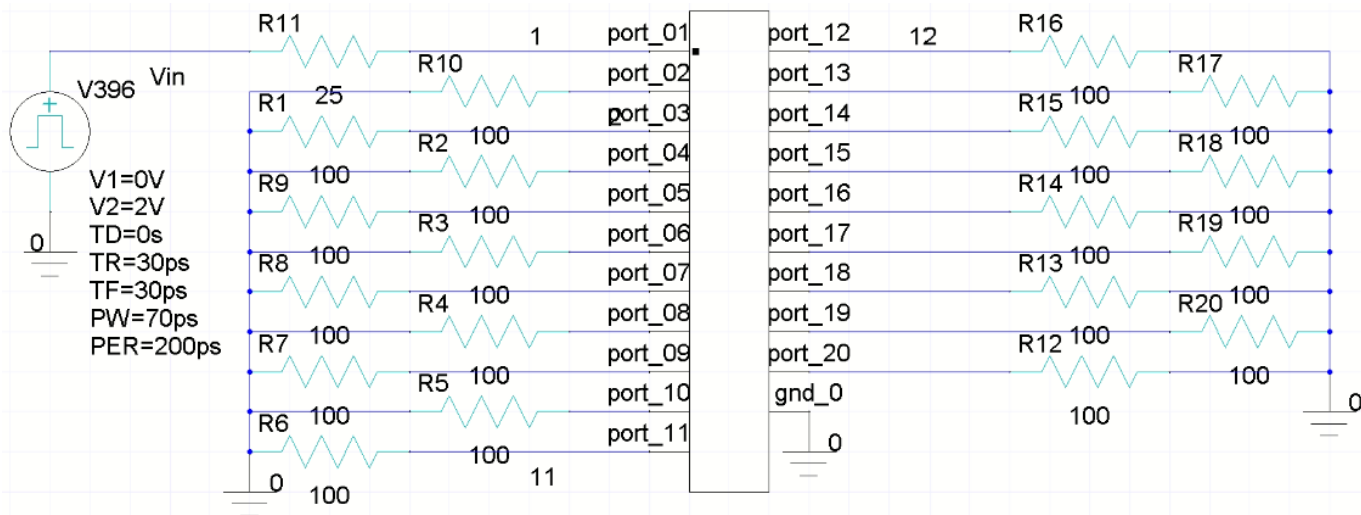
# Comparison

	<b>Model 2</b>	<b>Model 3</b>	<b>Model 4</b>	<b>Model 5</b>	<b>Model 6</b>
	<b>PI network for S by Y + VCVS+CCVS</b>	<b>State-space S</b>	<b>State-space S to Y</b>	<b>Pole-residue S-as-Y</b>	<b>Direct pole-residue specification</b>
Controlled sources	Yes	Yes	No	Yes	Yes
Negative RLC	Yes	No	Yes	Yes	No
Recursive convolution	No	No	No	No	Yes
Cross platform	Yes*	Yes	Yes*	Yes*	No

\* if negative RLC permitted


  
 Offered by many commercial EDA tools.

# Example: macromodel of 20 ports and 110 MIMO poles (10 coupled microstrips)



TRAN  
 Tstep = 1ps  
 Tstop = 100ns

## Total simulation time (s)

	State-space S (model 3)	PI network (model 2)	Foster (model 6)
EDA Tool A	338	815	190
EDA Tool B	295	383	94
Ngspice	200	788	

egrity



# Conclusion

- Many different ways to synthesize equivalent circuits for S-parameters in pole-residue form
- Considerations for choosing circuit topology
  - Want recursive convolution?
  - Want cross platform exchangeability?
  - Controlled source and negative RLC acceptable?
  - SISO or MIMO pole-residue model?