

Low-Frequency Modal Extrapolation and Regularization for Full-Bandwidth Macromodeling of Electromagnetic Structures

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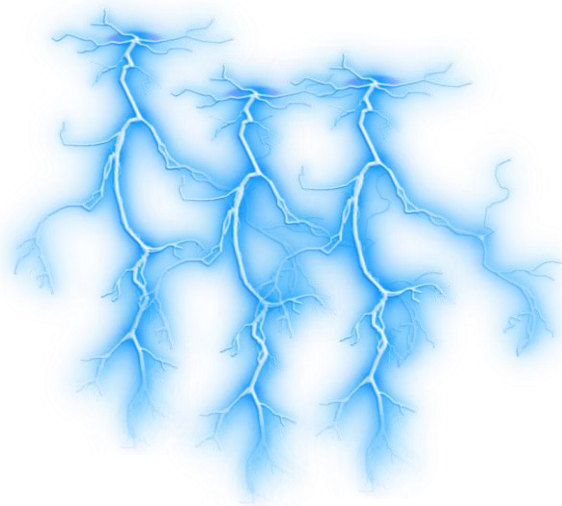
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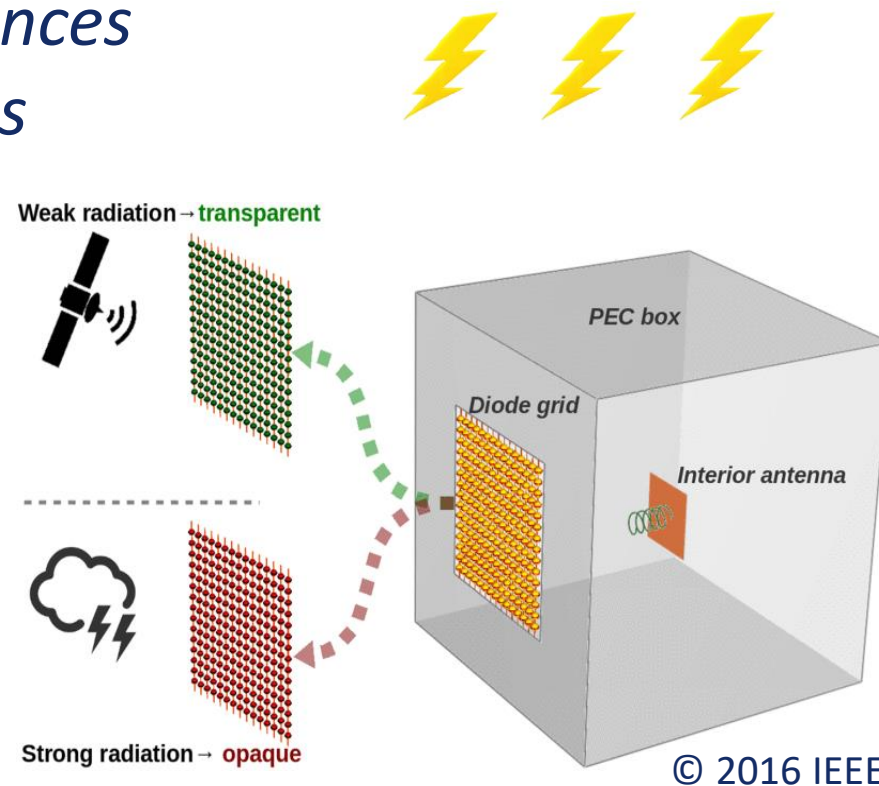


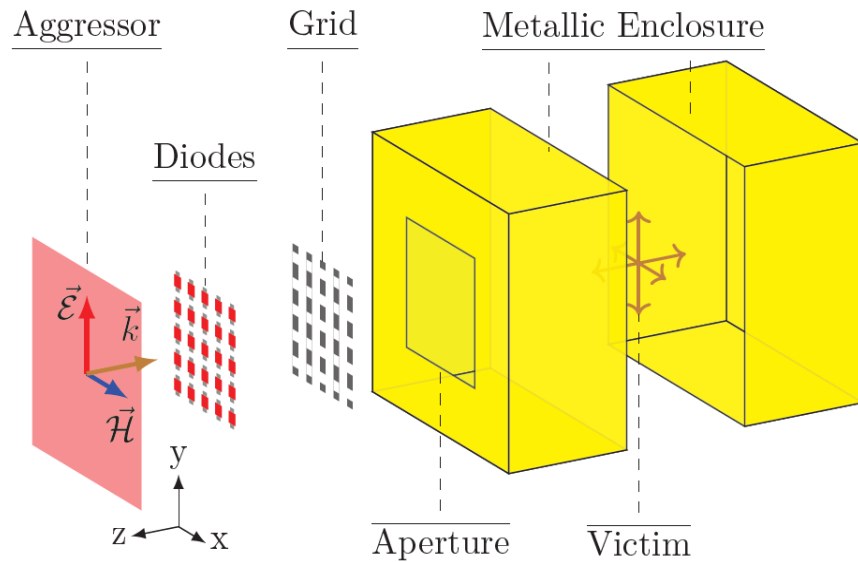
High-intensity radiation fields (HIRFs) and Electromagnetic Interference (EMI) can result in software or even hardware failure for many electronics devices



***Protect** from interferences*
***Allow** communications*

Energy selective (shielding) structures



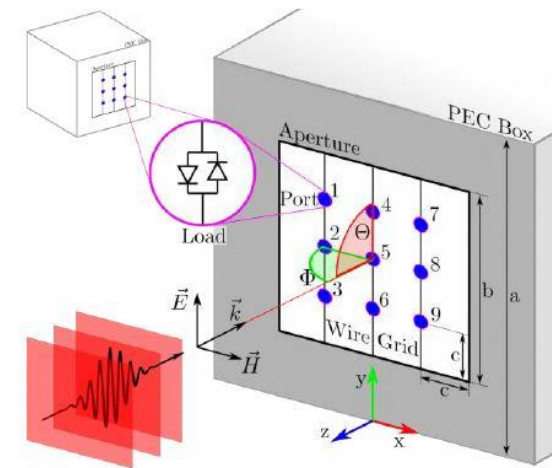


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Design through simulation

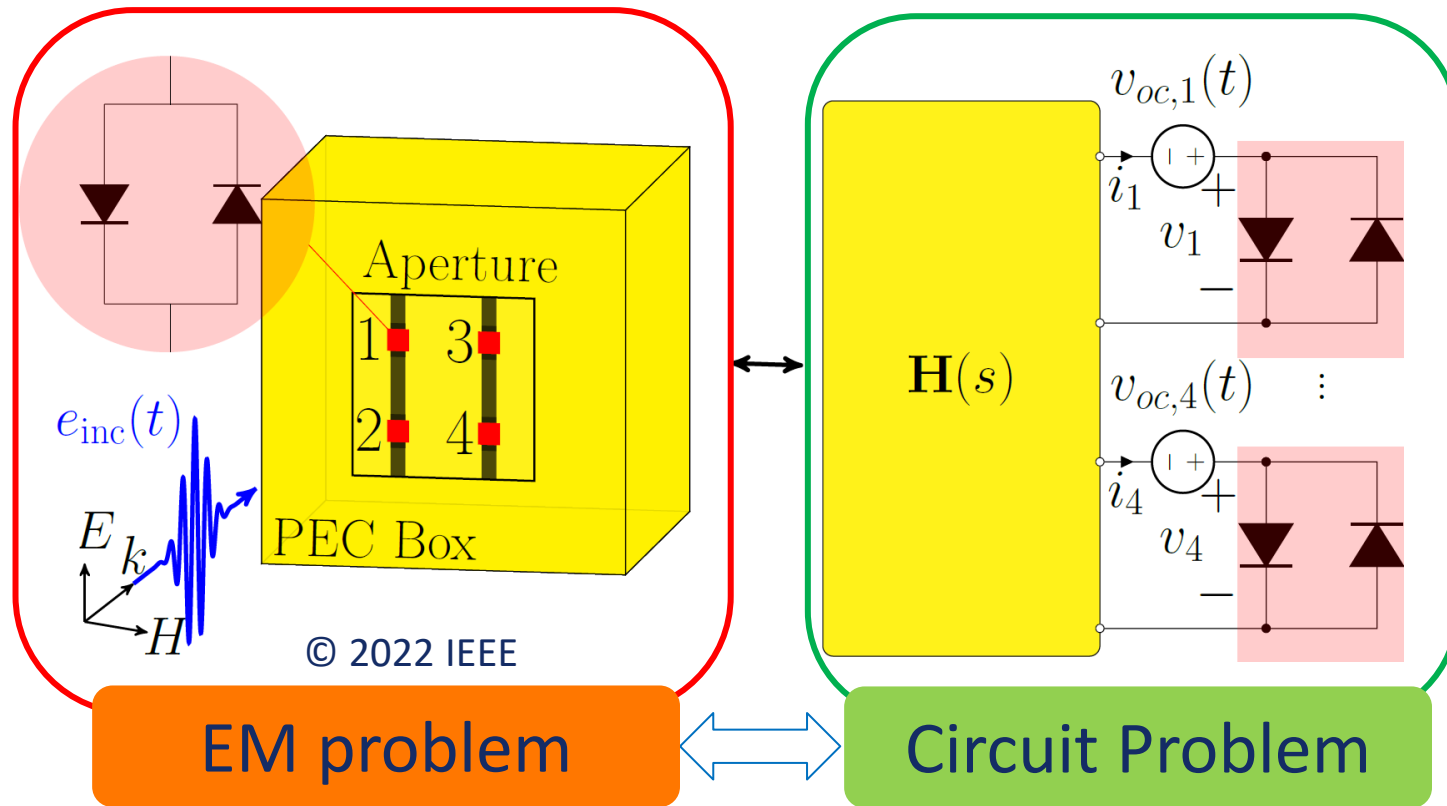
1. Full time-domain solvers
2. **Hybrid techniques: decouple**
 - **linear part**
 - **nonlinear terminations**

Frequency-domain solver based on Method of Moments (**MoM**)



Source: www.tet.tuhh.de

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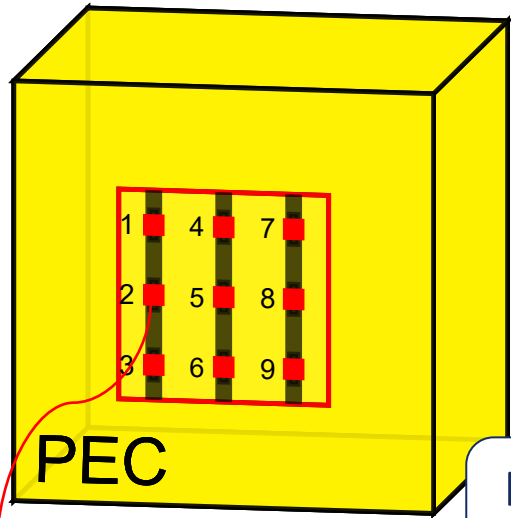
Large-scale **LTI system** terminated with many **nonlinear loads**

Main ingredients

1. Characterization of the shielding enclosure $\rightarrow \mathbf{H}(s)$
2. Characterization of nonlinear terminations
3. Incident field $e_{inc}(t) \rightarrow$ eqv sources $v_{oc}(t)$

*T. Wendt, C. Yang, H. D. Bruns, S. Grivet-Talocia, and C. Schuster, "A Macromodeling-Based Hybrid Method for the Computation of Transient Electromagnetic Fields Scattered by Nonlinearly Loaded Metal Structures," *IEEE Trans. Electromagn. Compat.*, vol. 62, no. 4, pp. 1098–1110, Aug. 2020, doi: 10.1109/TEMC.2020.2991455.

Remove loads \rightarrow Field Solver \rightarrow Data $\mathbf{H}(s) \rightarrow$ Model



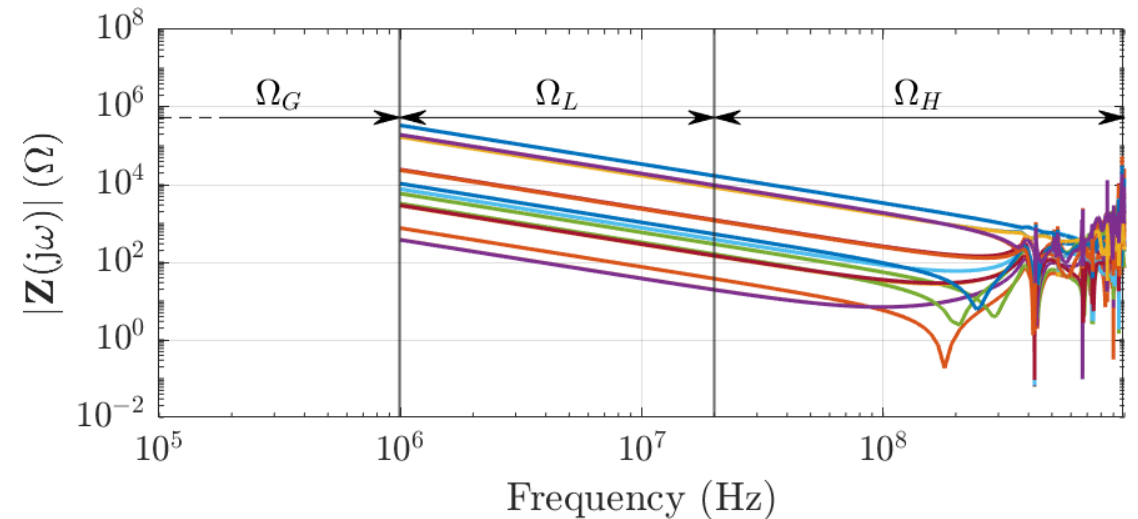
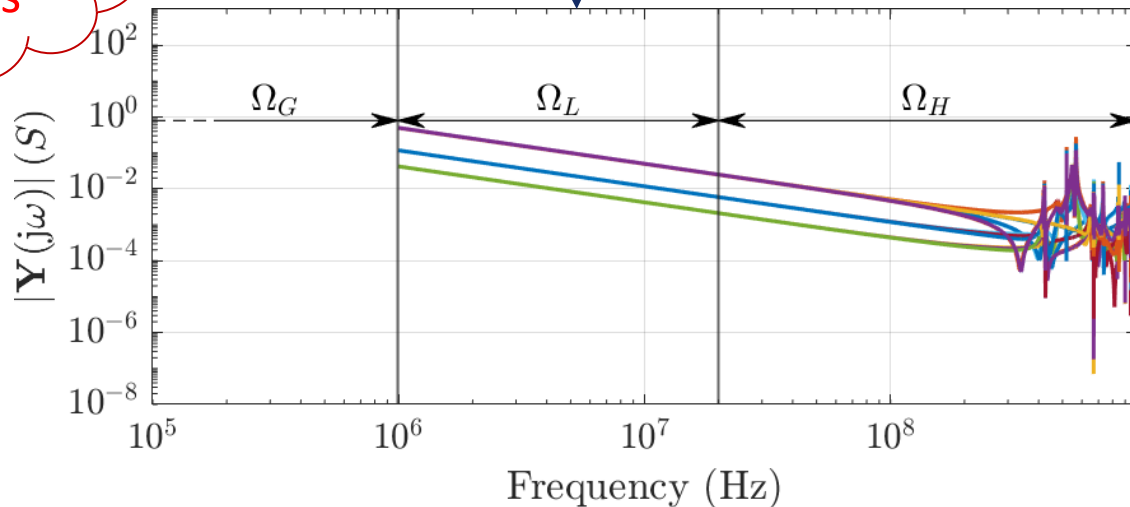
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Field Solver (MoM)

3 frequency regions

1. Ω_H high-frequency, rich of resonances
2. Ω_L mid-frequency, **asymptotic** behavior
3. Ω_G gap region, **unknown** with solver MoM

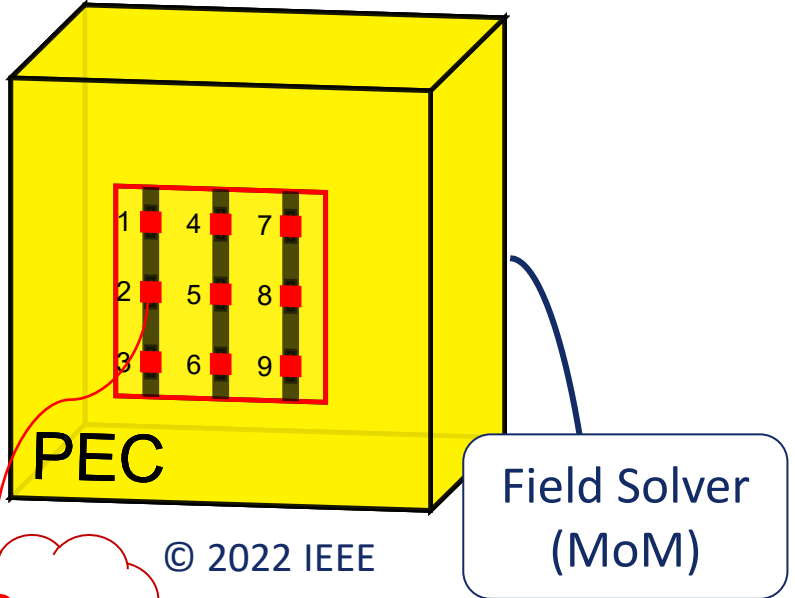
NO Loads



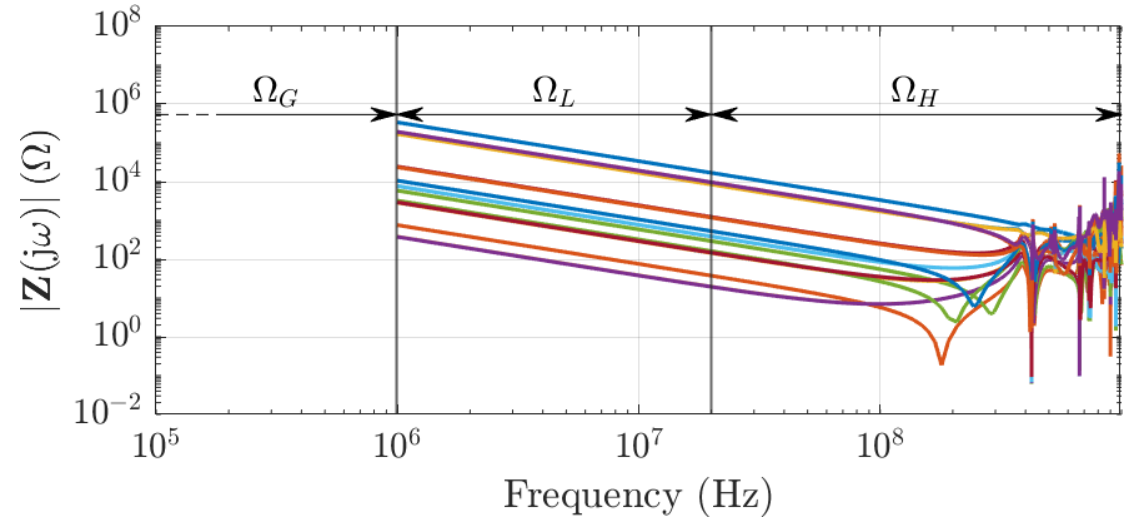
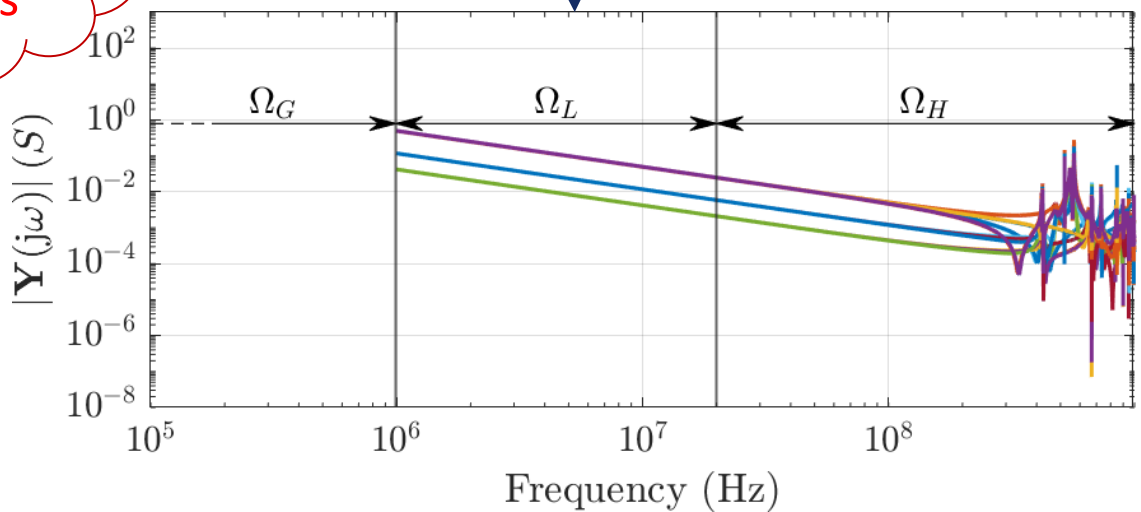
Most general case

Both $Y(j\omega)$ and $Z(j\omega)$ show a pole at DC!!!

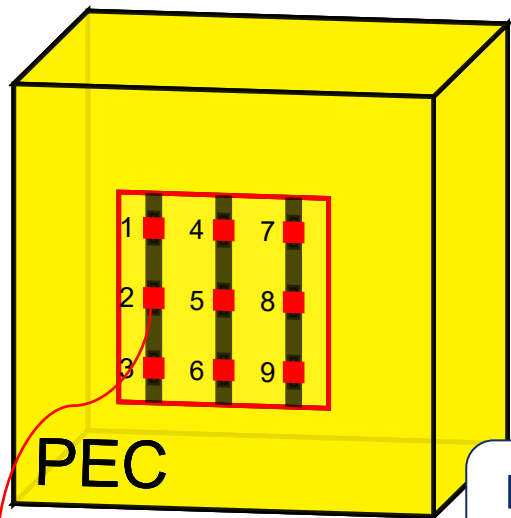
- $\omega \rightarrow 0 \rightarrow Y(j\omega) \rightarrow \infty$
- $\omega \rightarrow 0 \rightarrow Z(j\omega) \rightarrow \infty$



NO Loads



Remove loads → Field Solver → Data $\mathbf{H}(s)$ → Model

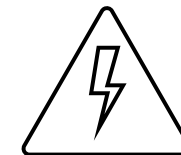


Field Solver (MoM)

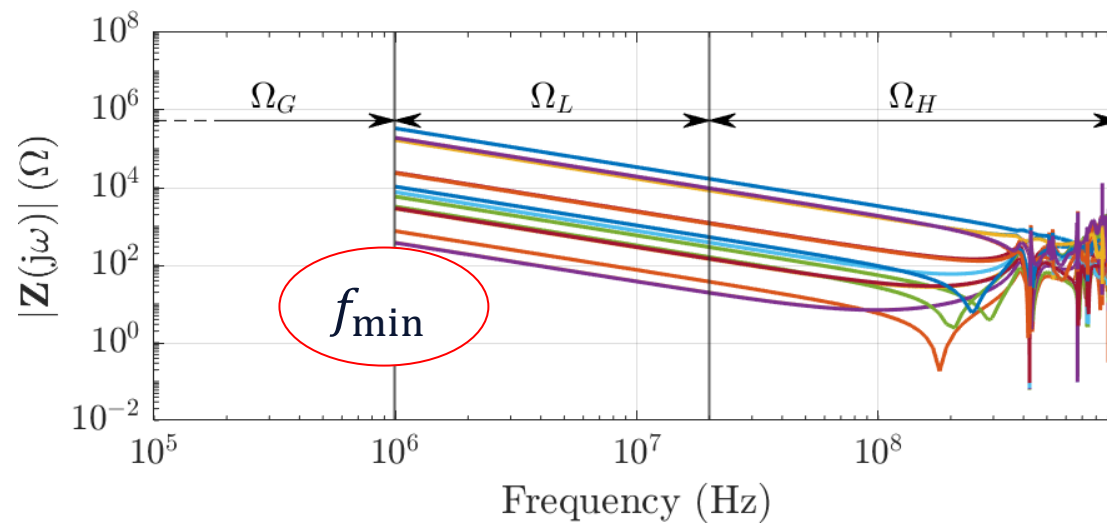
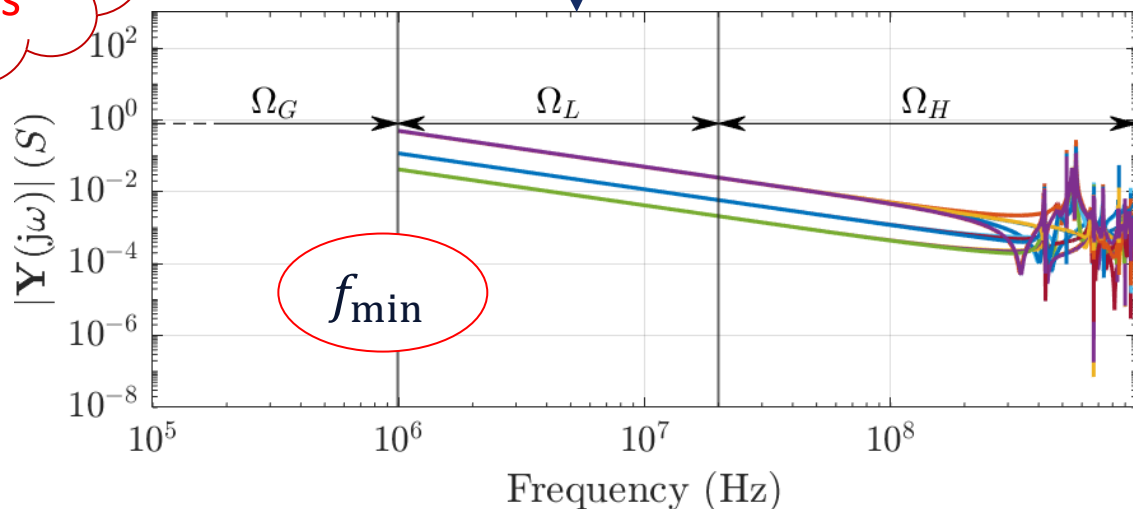
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Macromodeling challenges

- a) DC point is **missing**
- b) Wide **low-frequency gap** Ω_G



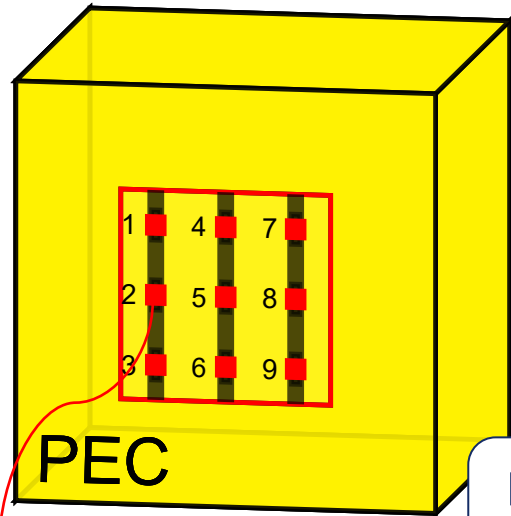
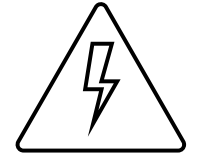
NO Loads



Remove loads \rightarrow Field Solver \rightarrow Data $\mathbf{H}(s)$ \rightarrow Model

Macromodeling challenges

- DC point is **missing**
- Wide **low-frequency gap** Ω_G

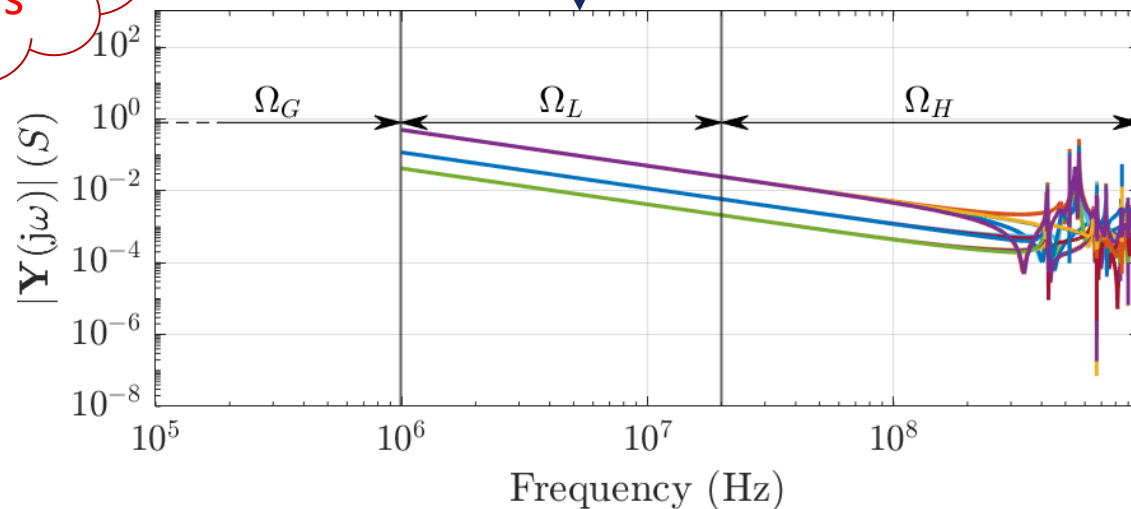


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Field Solver
(MoM)

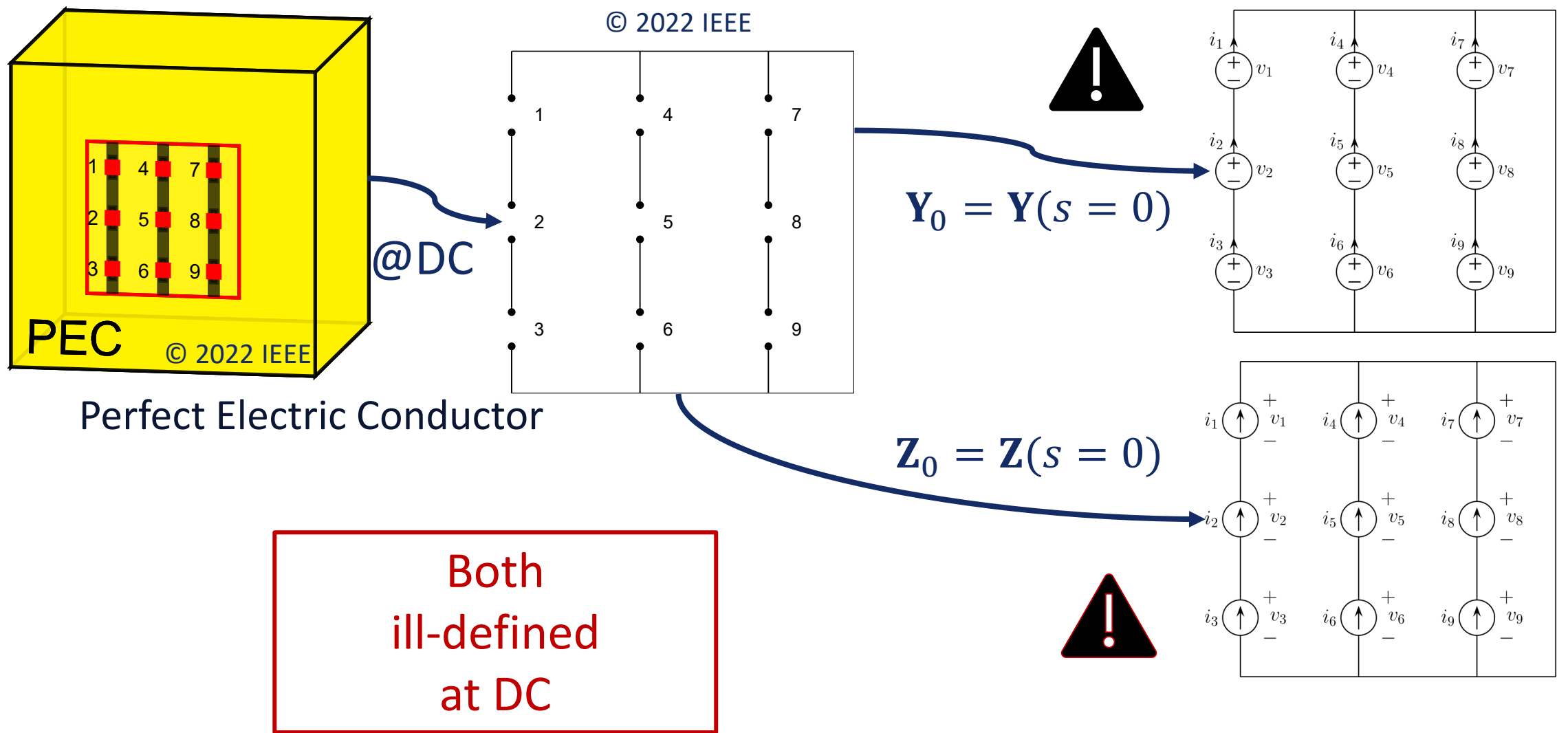
NO
Loads



Proposed solution

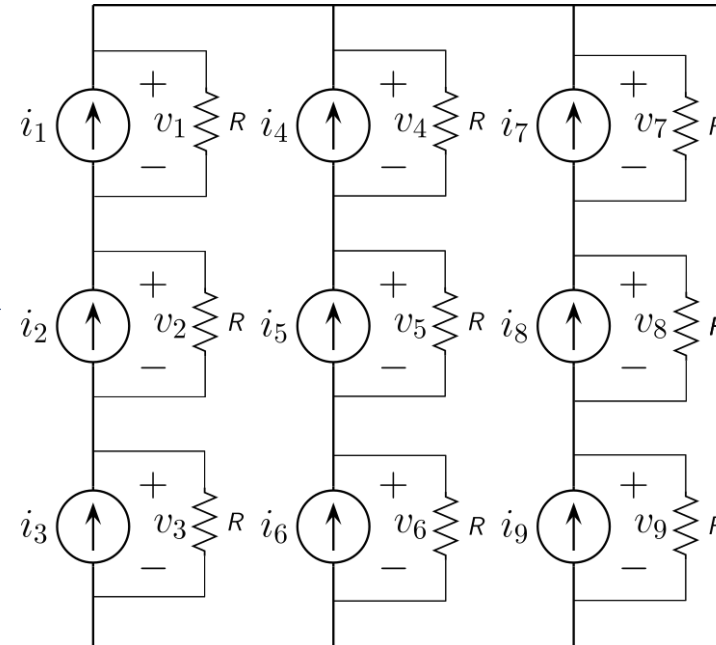
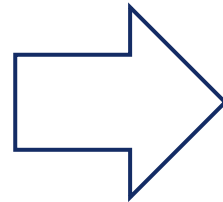
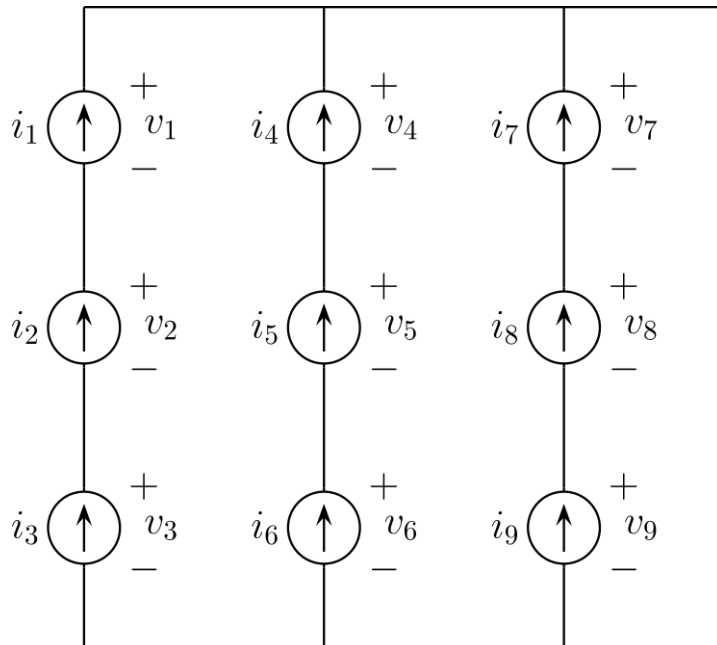
Data preprocessing

- Full-band regularization
- LF **modal** extrapolation



1. How to regularize $\mathbf{Z}(s)$?

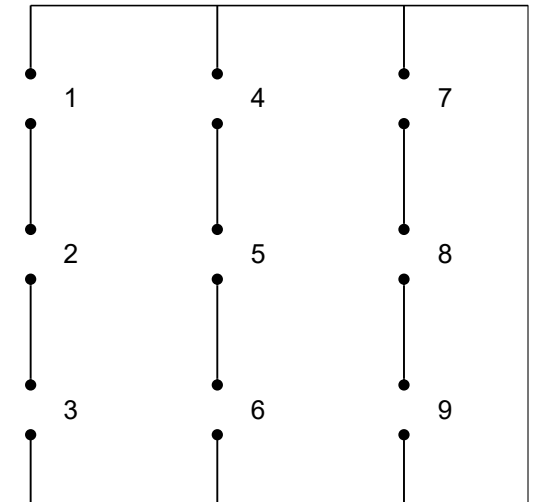
→ add shunt resistor R



How to regularize MoM data ?

$$1. \mathbf{Y}(s) \leftarrow \mathbf{Y}(s) + \frac{1}{R} \mathbf{I}$$

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\mathbf{Z}_0 is well defined

1. How to regularize $Z(s)$?

→ add shunt resistor R

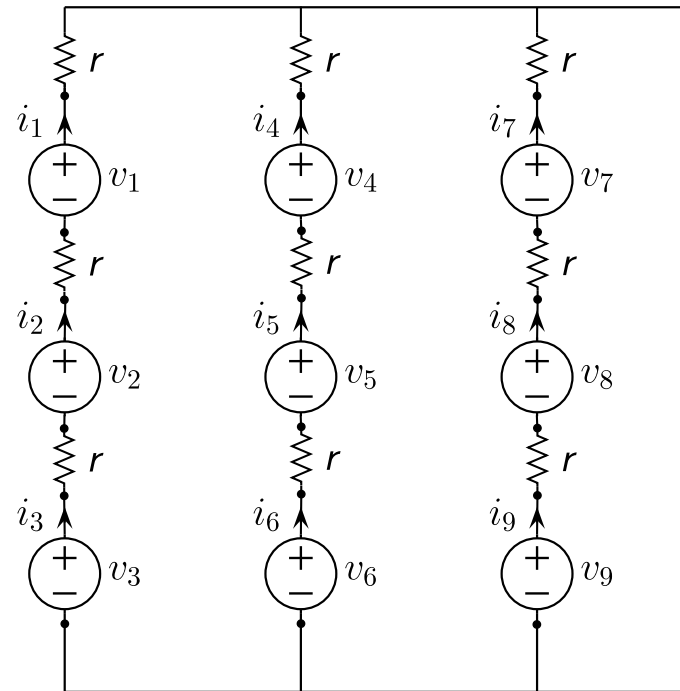
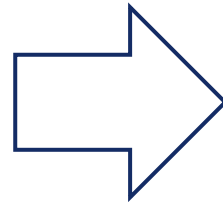
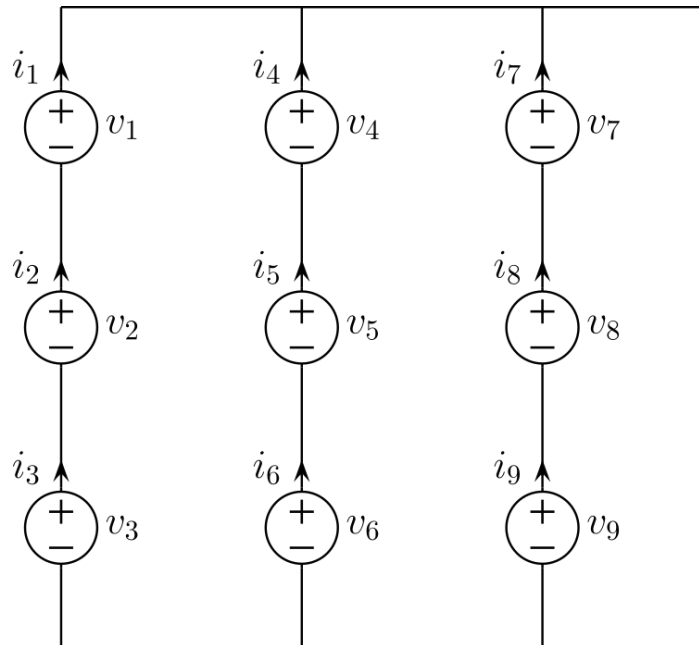
2. How to regularize $Y(s)$?

→ add series resistor r

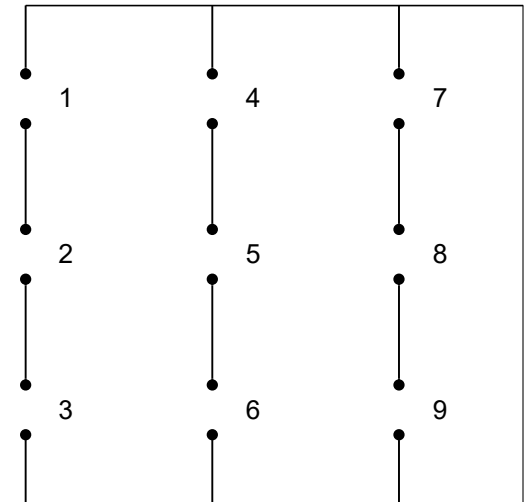
How to regularize MoM data ?

1. $Y(s) \leftarrow Y(s) + \frac{1}{R} \mathbb{I}$

2. $Z(s) \leftarrow Z(s) + r \mathbb{I}$



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Y_0 is well defined

1. How to regularize $\mathbf{Z}(s)$?

→ add shunt resistor R

2. How to regularize $\mathbf{Y}(s)$?

→ add series resistor r

How to regularize MoM data ?

1. $\mathbf{Y}(s) \leftarrow \mathbf{Y}(s) + \frac{1}{R} \mathbb{I}$

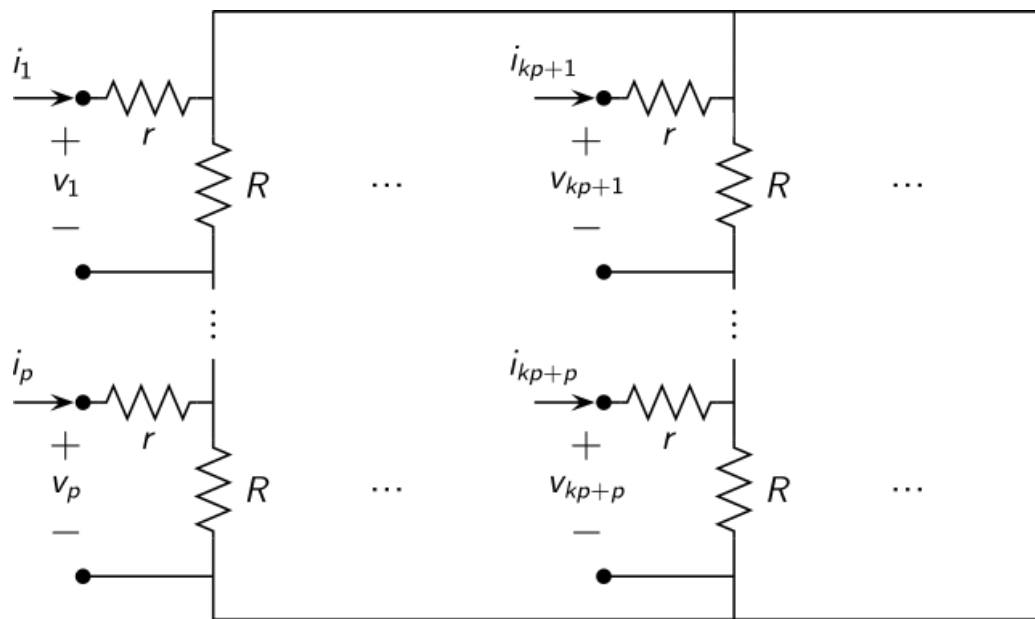
2. Convert to $\mathbf{Z}(s) = (\mathbf{Y}(s))^{-1}$

3. $\mathbf{Z}(s) \leftarrow \mathbf{Z}(s) + r\mathbb{I}$

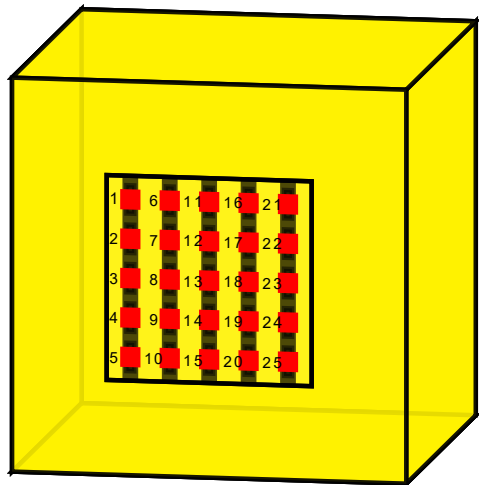
DC matrices can be analytically computed for all system representations

$$\mathbf{Y}_0 = \mathbb{I}_p \otimes \mathbf{Y}_p \qquad \mathbf{Y}_p = \frac{(pr \mathbb{I}_p + R\mathbf{u}\mathbf{u}^T)}{prR'}$$

$$R' = R + r \qquad \mathbf{u}^T = [1, \dots, 1]$$



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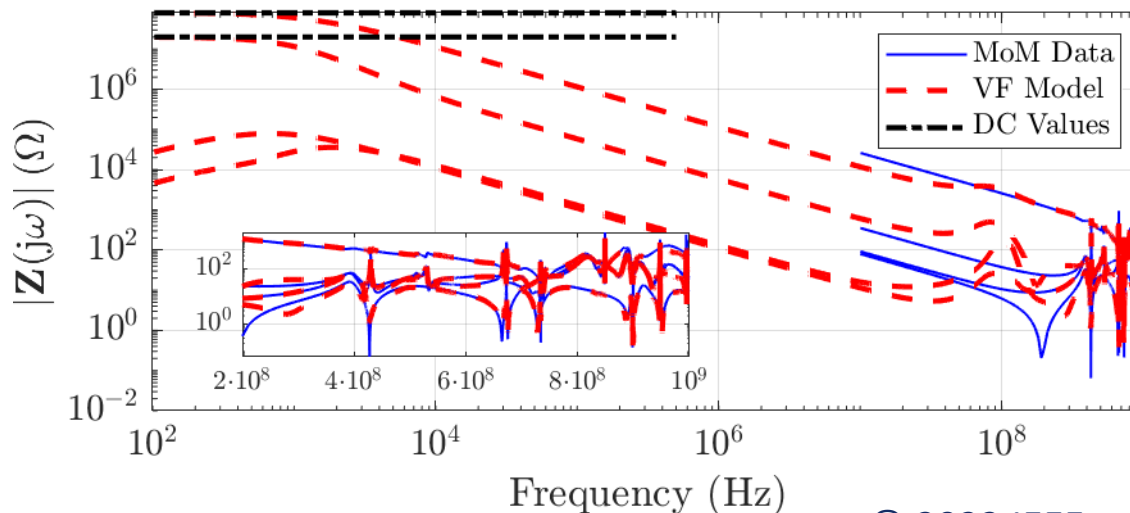
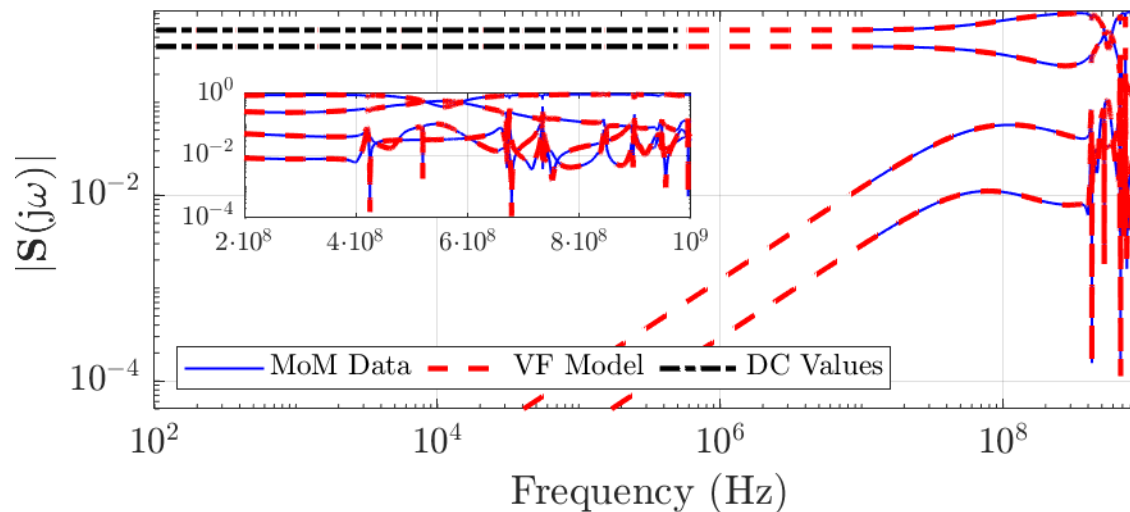


What if we built a model?

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Macromodeling challenges

- a) ~~DC point is missing~~
 - ✓ Physics-based DC point added for model generation
- b) Wide **low-frequency gap** Ω_G
 - LF extrapolation is needed



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Start with original data

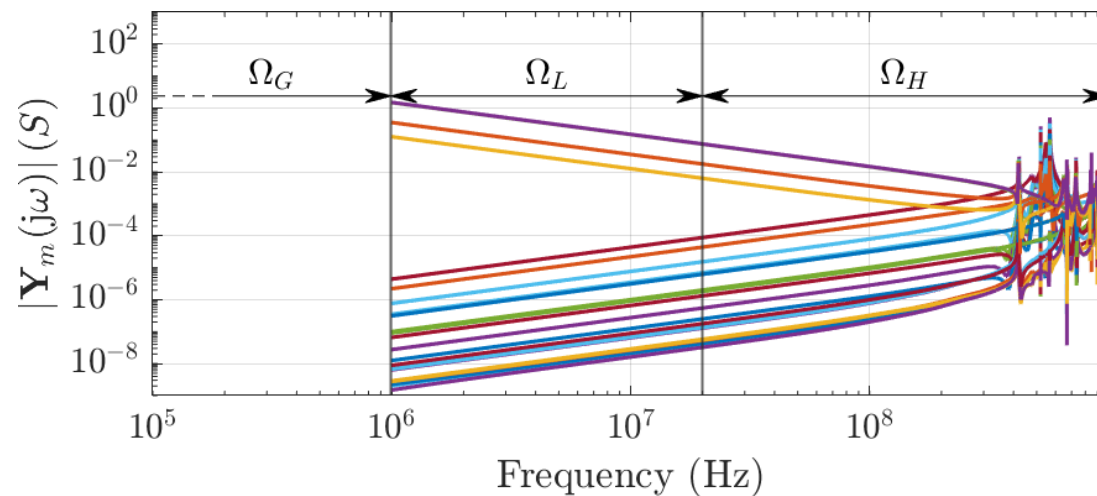
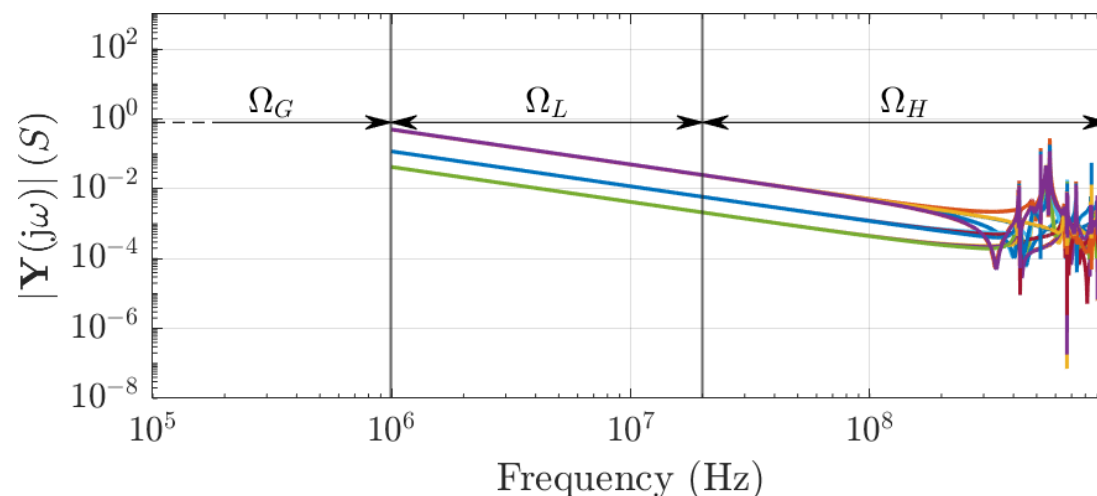
1. Eigenvalue decomposition at DC

$$\mathbf{Y}_0 = \mathbf{Q}\mathbf{\Lambda}_0\mathbf{Q}^T, \quad \mathbf{\Lambda}_0 = \mathbf{Q}^T\mathbf{Y}_0\mathbf{Q} = \begin{bmatrix} \frac{1}{R'}\mathbb{I}_c & \mathbf{0} \\ \mathbf{0} & \frac{1}{r}\mathbb{I}_\ell \end{bmatrix} \quad (2)$$

2. Projection to DC modal domain

$$\mathbf{Y}_m(j\omega_k) = \mathbf{Q}^T\mathbf{Y}(j\omega_k)\mathbf{Q}, \quad k = 1, \dots, K. \quad (4)$$

Causality and passivity are preserved by the constant (real) and orthogonal \mathbf{Q}



Start with original data

1. Eigenvalue decomposition at DC

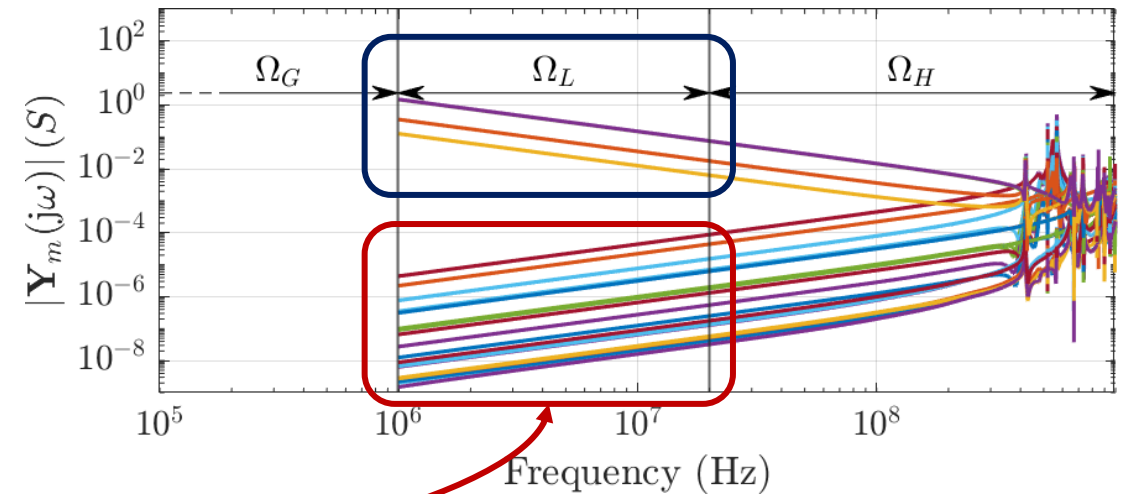
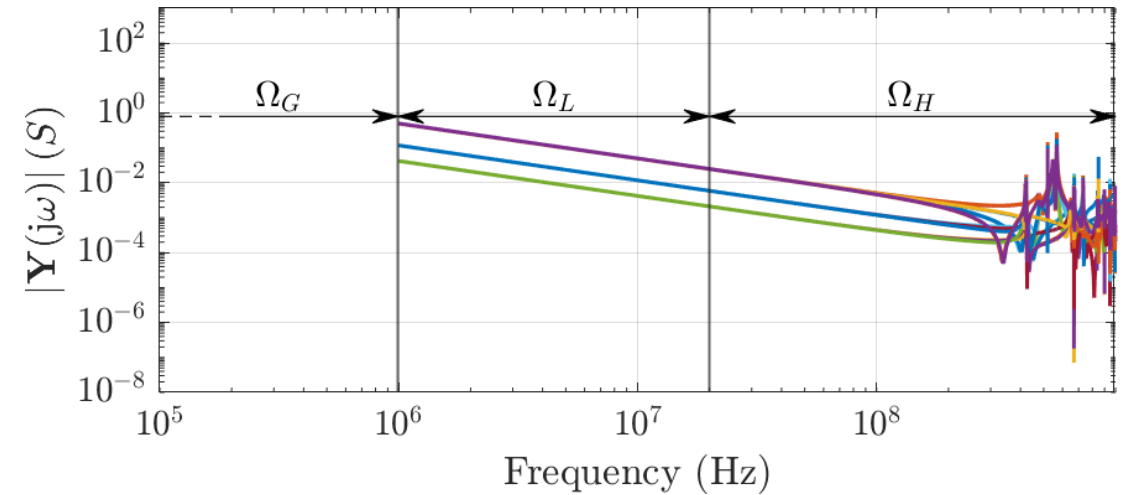
$$\mathbf{Y}_0 = \mathbf{Q}\mathbf{\Lambda}_0\mathbf{Q}^T, \quad \mathbf{\Lambda}_0 = \mathbf{Q}^T\mathbf{Y}_0\mathbf{Q} = \begin{bmatrix} \frac{1}{R'}\mathbb{I}_c & \mathbf{0} \\ \mathbf{0} & \frac{1}{r}\mathbb{I}_\ell \end{bmatrix} \quad (2)$$

2. Projection to DC modal domain

$$\mathbf{Y}_m(j\omega_k) = \mathbf{Q}^T\mathbf{Y}(j\omega_k)\mathbf{Q}, \quad k = 1, \dots, K. \quad (4)$$

Low-frequency (asymptotic) behaviors are well separated in the modal domain!

$$\mathbf{Y}_m(j\omega) \approx \left(\frac{1}{j\omega} \mathbf{\Gamma}_m \right) \left(j\omega \mathbf{C}_m \right) = \begin{bmatrix} j\omega \tilde{\mathbf{C}} & j\omega \mathbf{X} \\ j\omega \mathbf{X}^T & \frac{1}{j\omega} \tilde{\mathbf{\Gamma}} \end{bmatrix} \quad (5)$$



Start with original data

1. Eigenvalue decomposition at DC

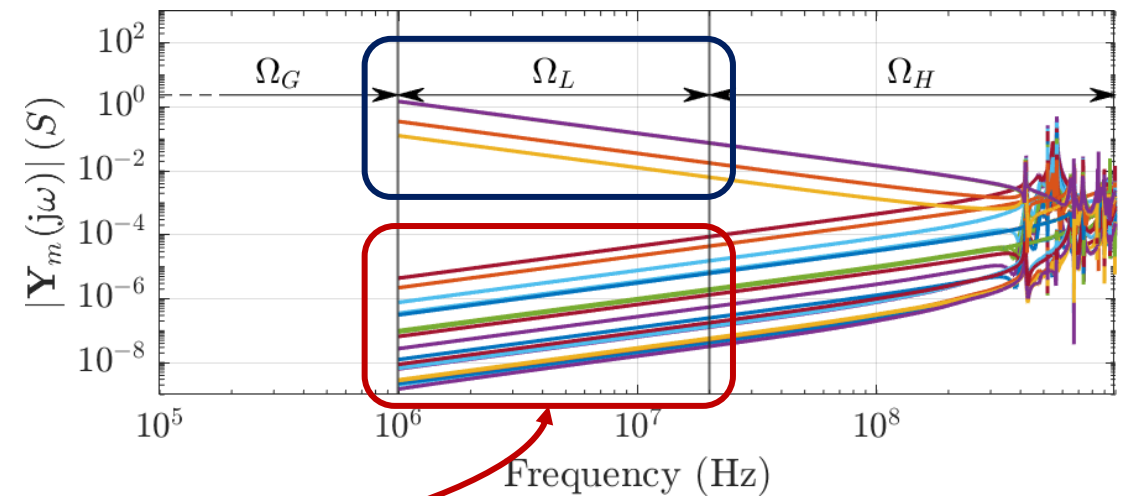
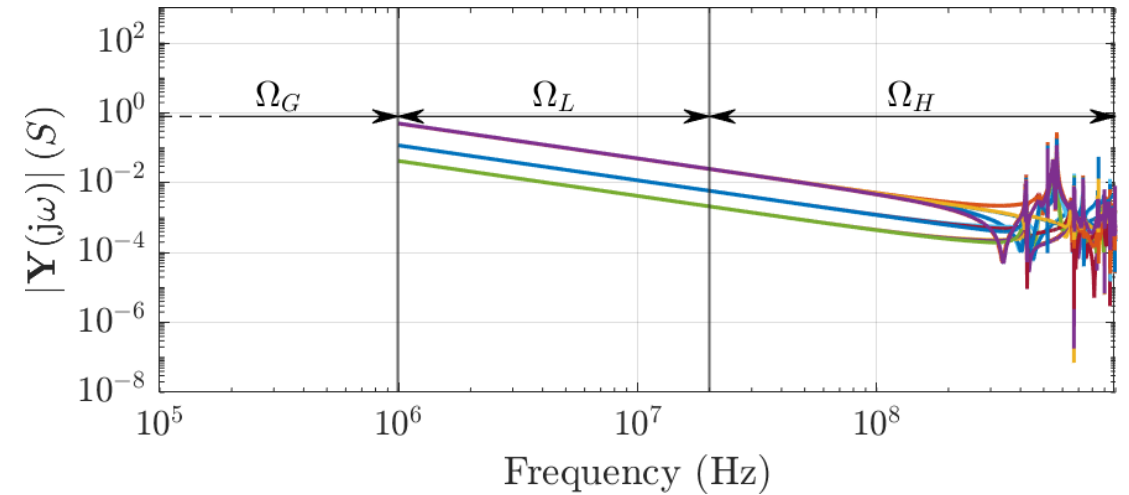
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2. Projection to DC modal domain

$$\mathbf{Y}_m(j\omega_k) = \mathbf{Q}^T\mathbf{Y}(j\omega_k)\mathbf{Q}, \quad k = 1, \dots, K. \quad (4)$$

3. Fit (5) with element-wise regression in Ω_L

$$\mathbf{Y}_m(j\omega) \approx \underbrace{\frac{1}{j\omega}\mathbf{\Gamma}_m}_{\text{blue circle}} \underbrace{j\omega\mathbf{C}_m}_{\text{red circle}} = \begin{bmatrix} j\omega\tilde{\mathbf{C}} & j\omega\mathbf{X} \\ j\omega\mathbf{X}^T & \frac{1}{j\omega}\tilde{\mathbf{\Gamma}} \end{bmatrix} \quad (5)$$



Start with original data

1. Eigenvalue decomposition at DC

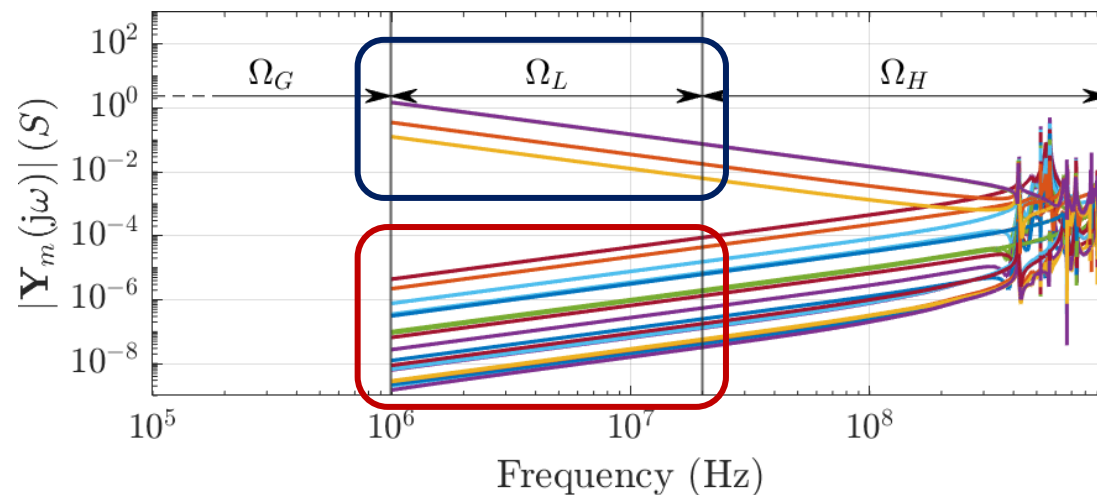
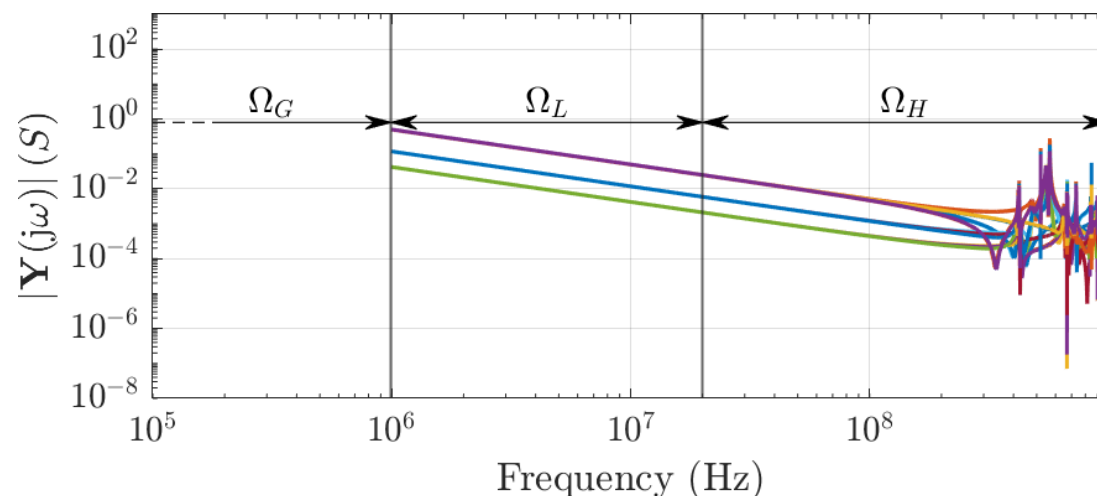
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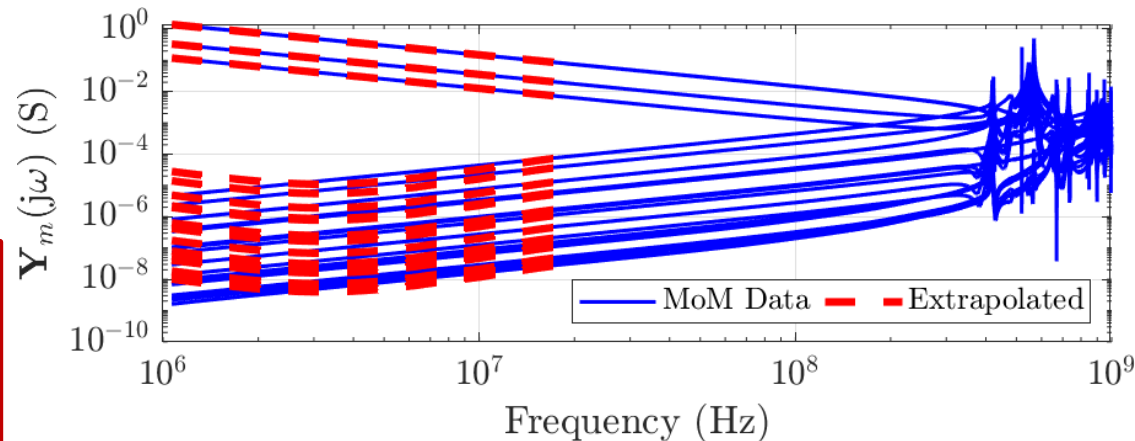
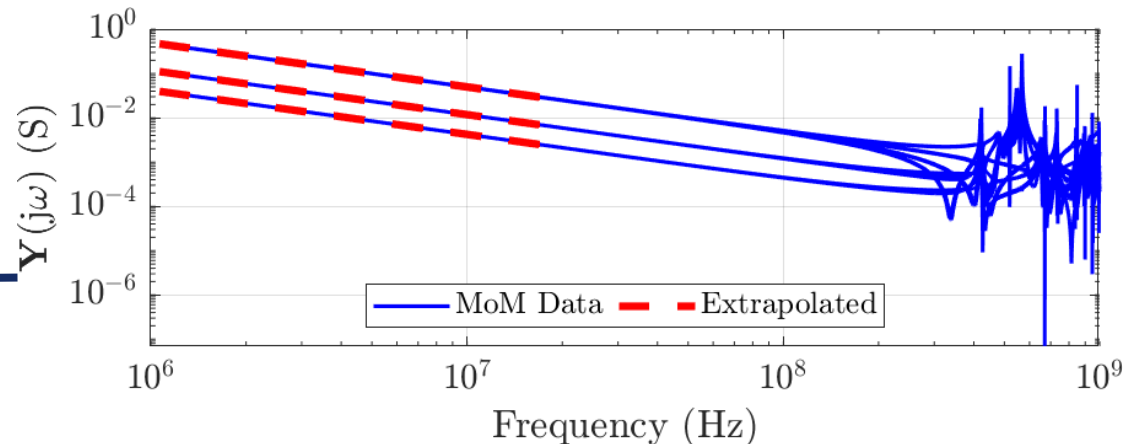
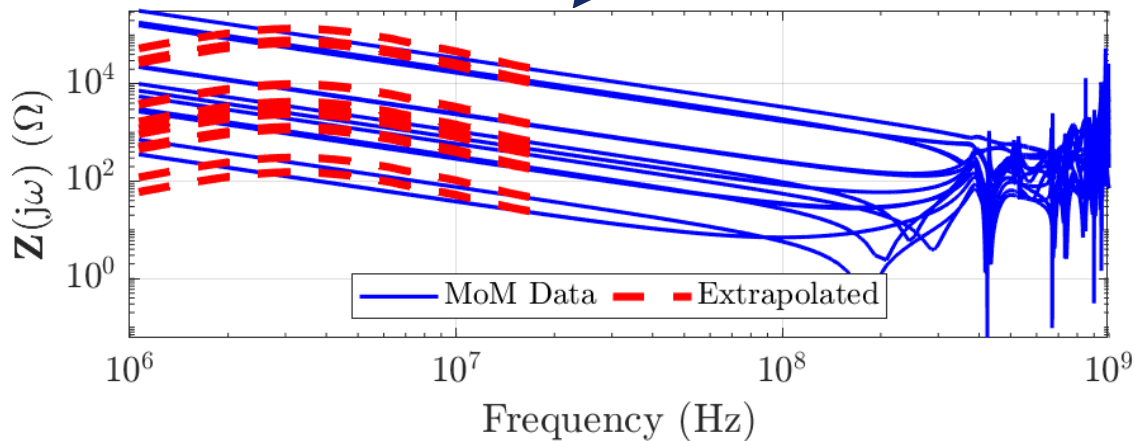
3. Fit (5) with element-wise regression in Ω_L

4. Extrapolate in the gap band Ω_G



Why not a Direct Extrapolation?

Direct fit at low-frequency
 → **inaccurate results**
 (changing representation)



Capacitive modes are not well visible in the admittance representation!

Start with original data

1. Eigenvalue decomposition at DC

$$\mathbf{Y}_0 = \mathbf{Q}\mathbf{\Lambda}_0\mathbf{Q}^T, \quad \mathbf{\Lambda}_0 = \mathbf{Q}^T\mathbf{Y}_0\mathbf{Q} = \begin{bmatrix} \frac{1}{R'}\mathbb{I}_c & \mathbf{0} \\ \mathbf{0} & \frac{1}{r}\mathbb{I}_\ell \end{bmatrix} \quad (2)$$

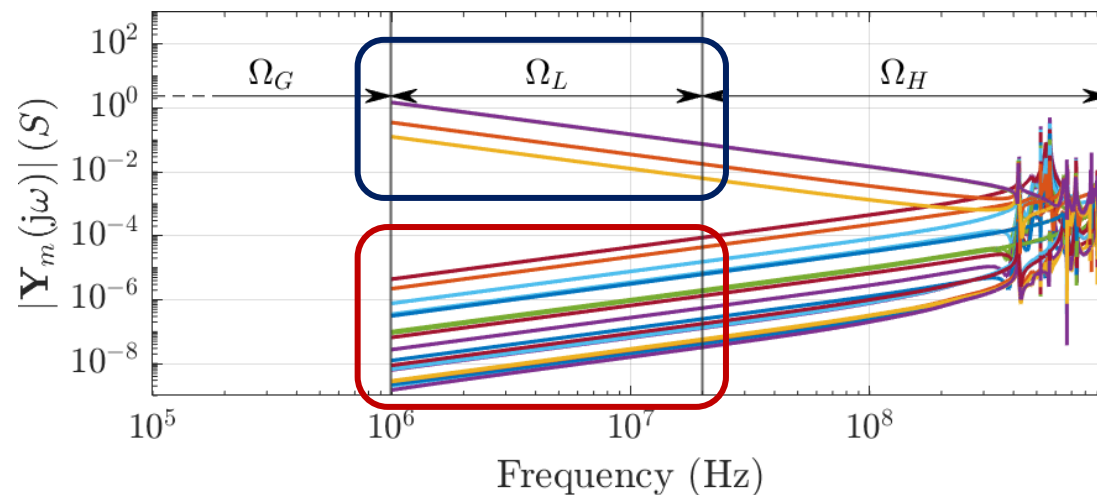
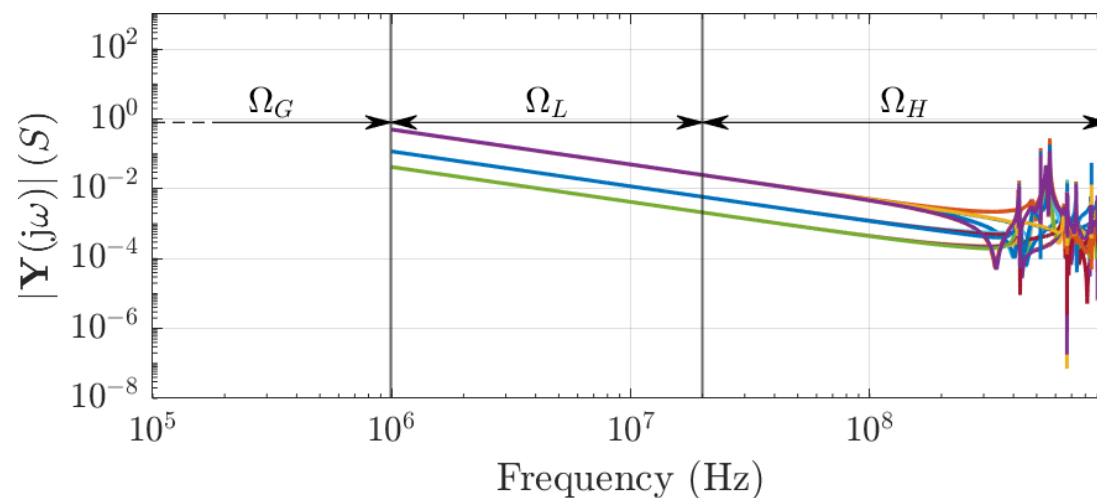
2. Projection to DC modal domain

$$\mathbf{Y}_m(j\omega_k) = \mathbf{Q}^T\mathbf{Y}(j\omega_k)\mathbf{Q}, \quad k = 1, \dots, K. \quad (4)$$

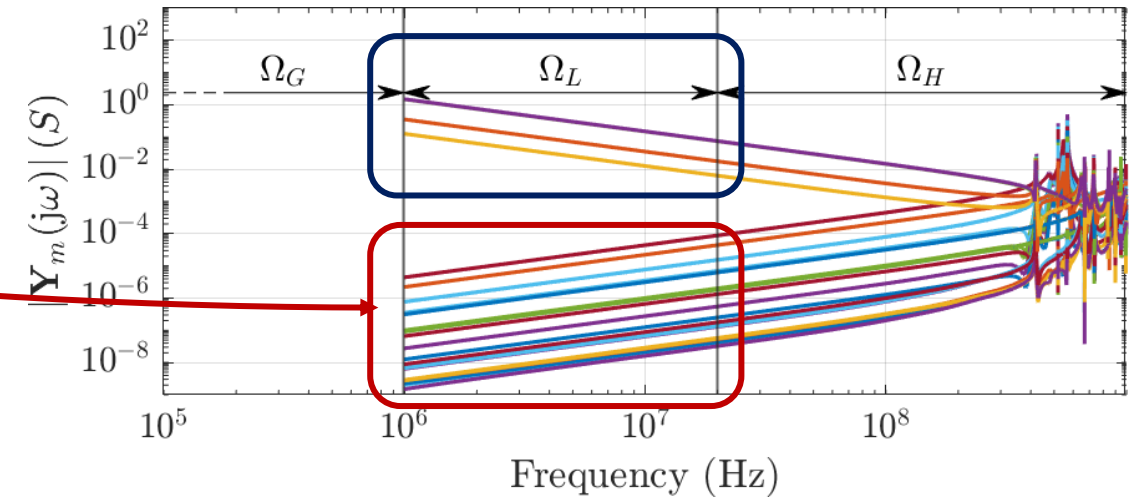
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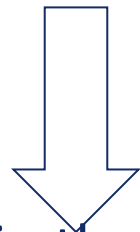
5. Regularize data in the modal domain



$$\mathbf{Y}_m(j\omega) \approx \frac{1}{j\omega} \mathbf{\Gamma}_m - j\omega \mathbf{C}_m = \begin{bmatrix} j\omega \tilde{\mathbf{C}} & j\omega \mathbf{X} \\ j\omega \mathbf{X}^\top & \frac{1}{j\omega} \tilde{\mathbf{\Gamma}} \end{bmatrix} \quad (5)$$



Capacitive blocks are responsible for the singularity of (modal) admittance in DC



Minimize the perturbation: modify only the eigenvalues associate to capacitive blocks

5. Regularize data in the modal domain

a) Regularize (modal) admittance

$$\hat{\mathbf{Y}}_m(j\omega) = \mathbf{Y}_m(j\omega) + \begin{bmatrix} \frac{1}{R'} \mathbb{I}_c & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}$$

b) Regularize (modal) impedance

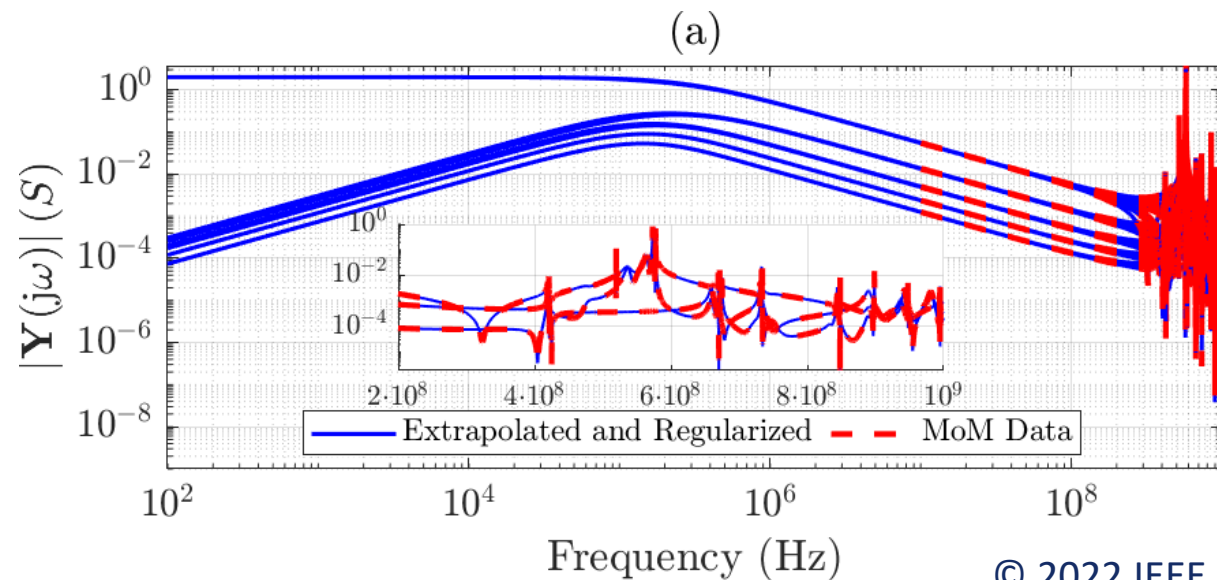
$$\check{\mathbf{Z}}_m(j\omega) = \hat{\mathbf{Y}}_m(j\omega)^{-1} + \begin{bmatrix} \mathbf{0} & \mathbf{0} \\ \mathbf{0} & r \mathbb{I}_\ell \end{bmatrix} = \begin{bmatrix} R' \mathbb{I}_c + \star_1 & \star_2 \\ \star_2 & r \mathbb{I}_\ell + \star_1 \end{bmatrix}$$

6. Convert back to the physical domain

$$\check{\mathbf{Z}}(j\omega) = \mathbf{Q} \check{\mathbf{Z}}_m(j\omega) \mathbf{Q}^\top$$

Start with original data

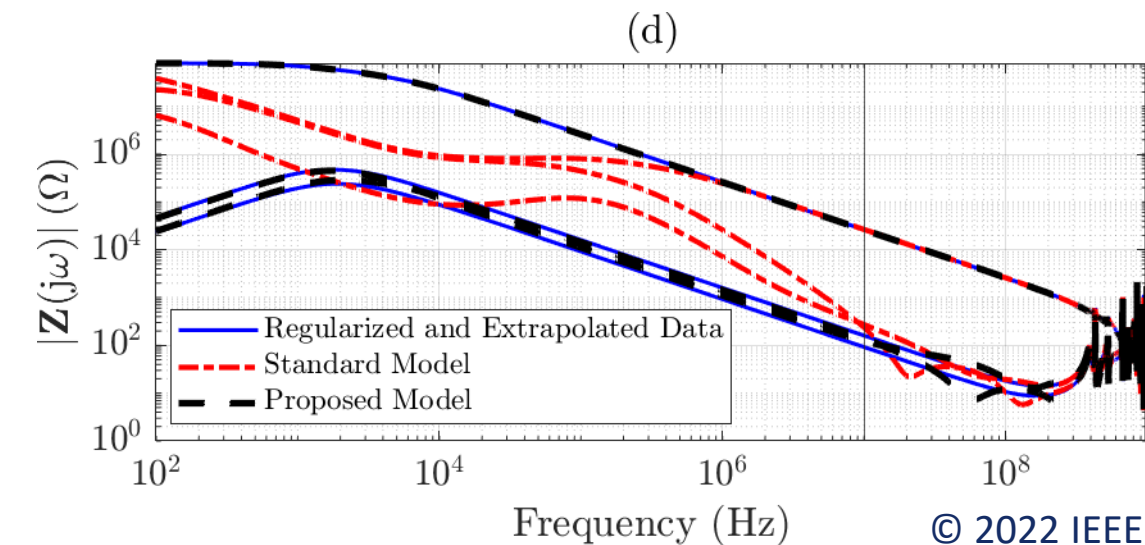
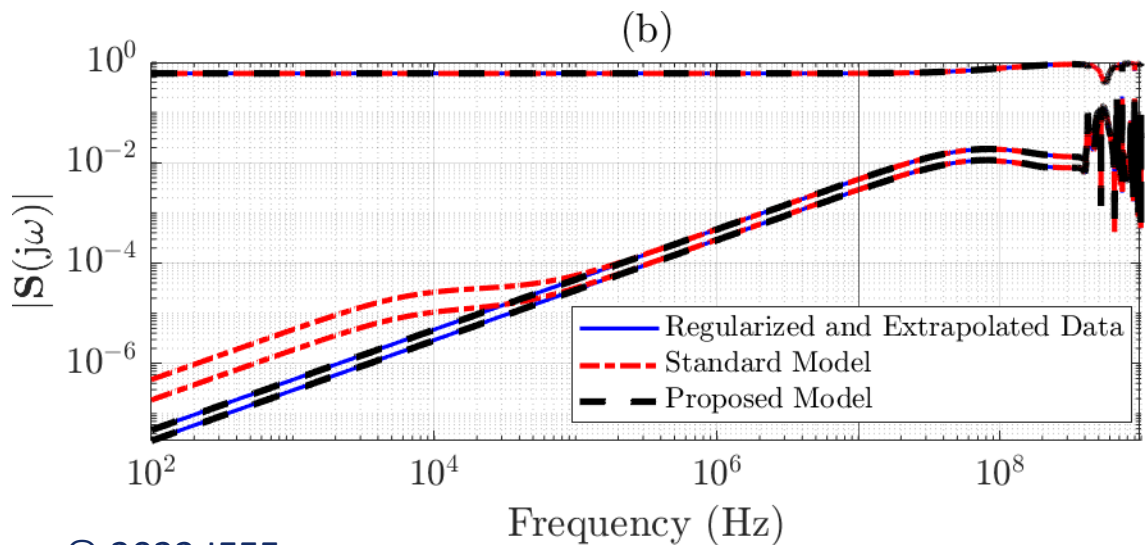
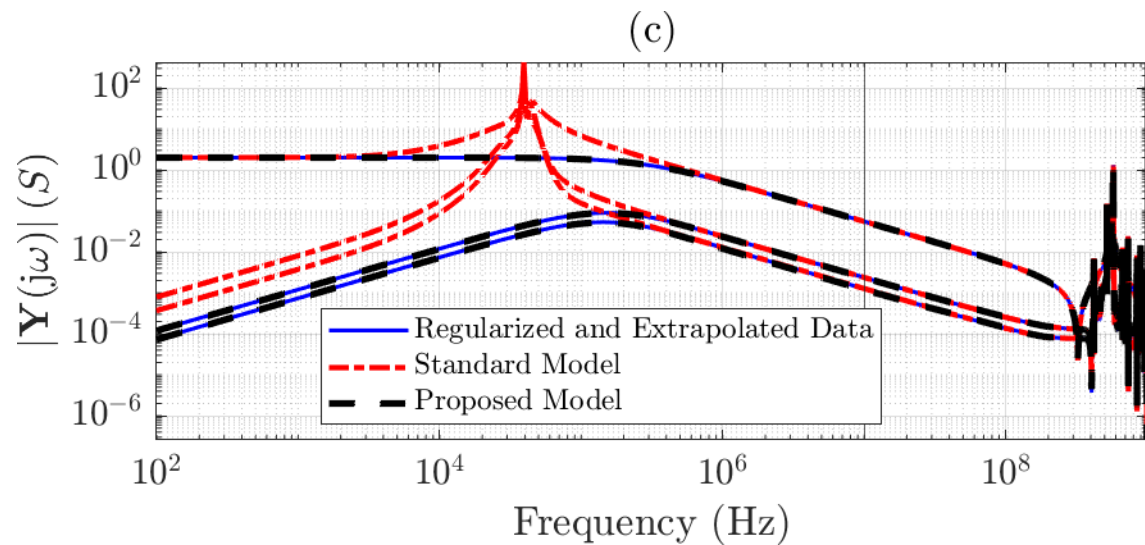
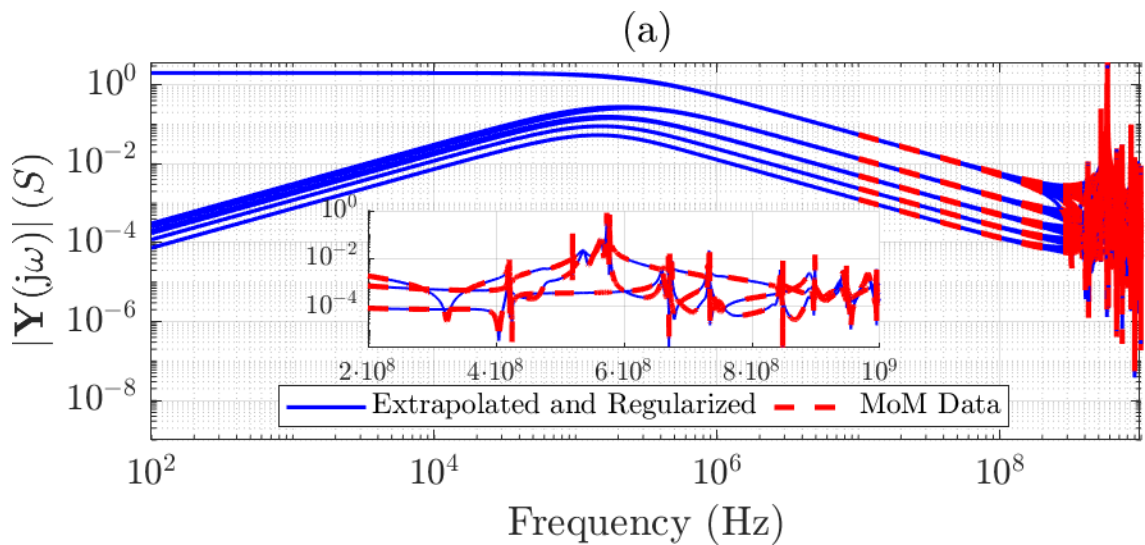
1. Eigenvalue decomposition at DC
2. Projection to DC modal domain
3. Fit (5) with element-wise regression in the low-frequency range Ω_L
4. Extrapolate in the gap band Ω_G
5. Regularize data in the modal domain
 - a) Regularize (modal) admittance
 - b) Regularize (modal) impedance
6. Convert back to the physical domain



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Well-defined full-bandwidth data
 → now we can build a model

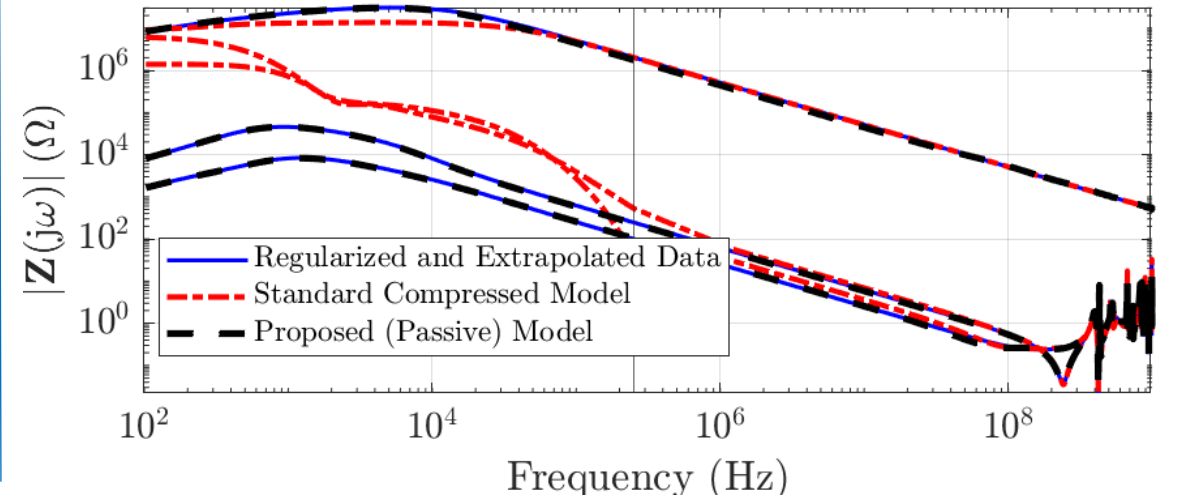
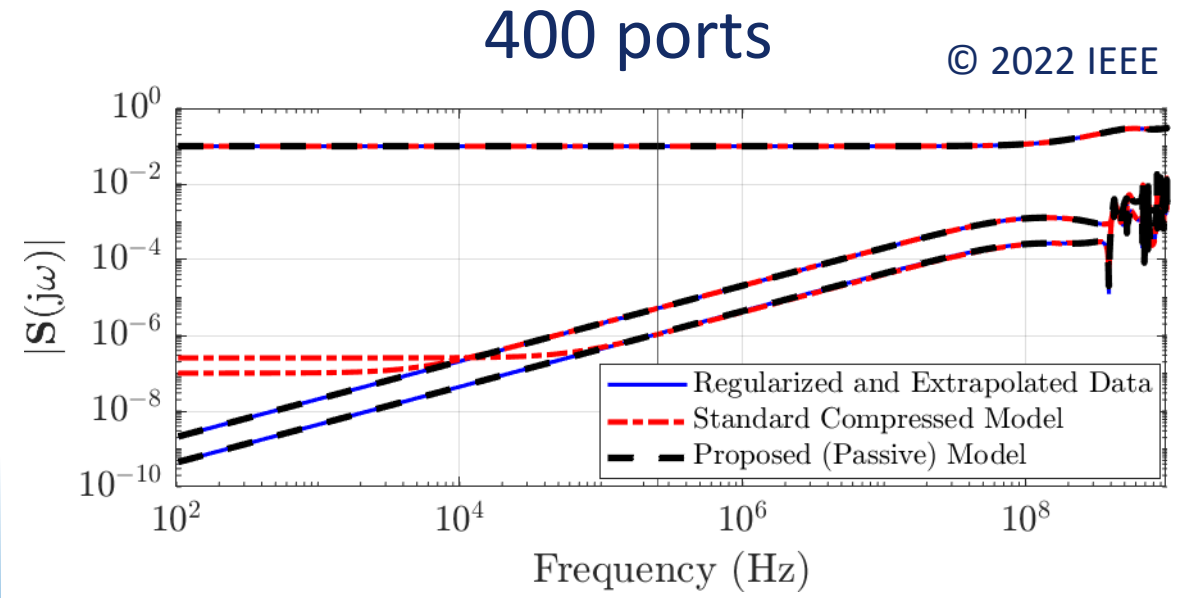
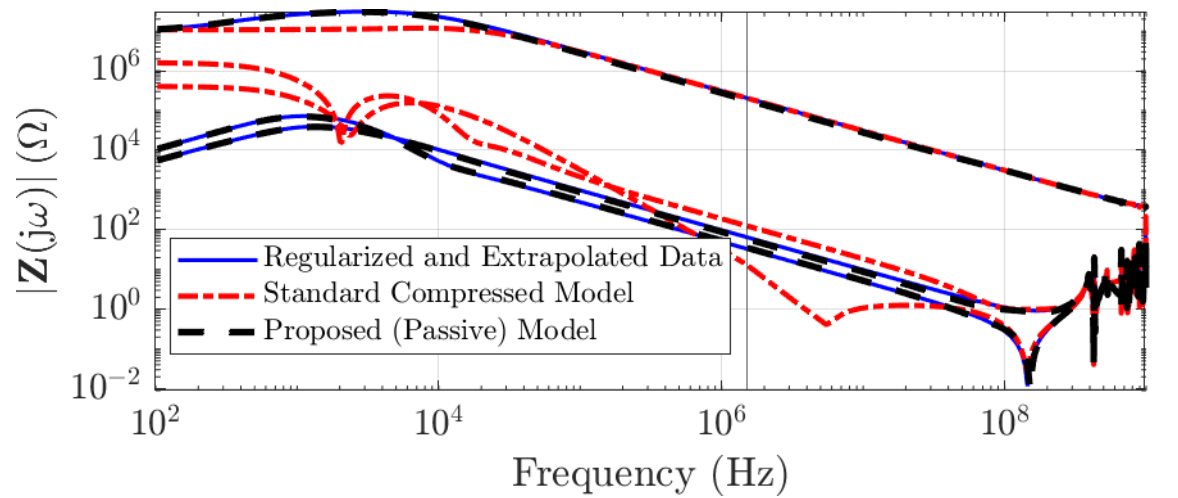
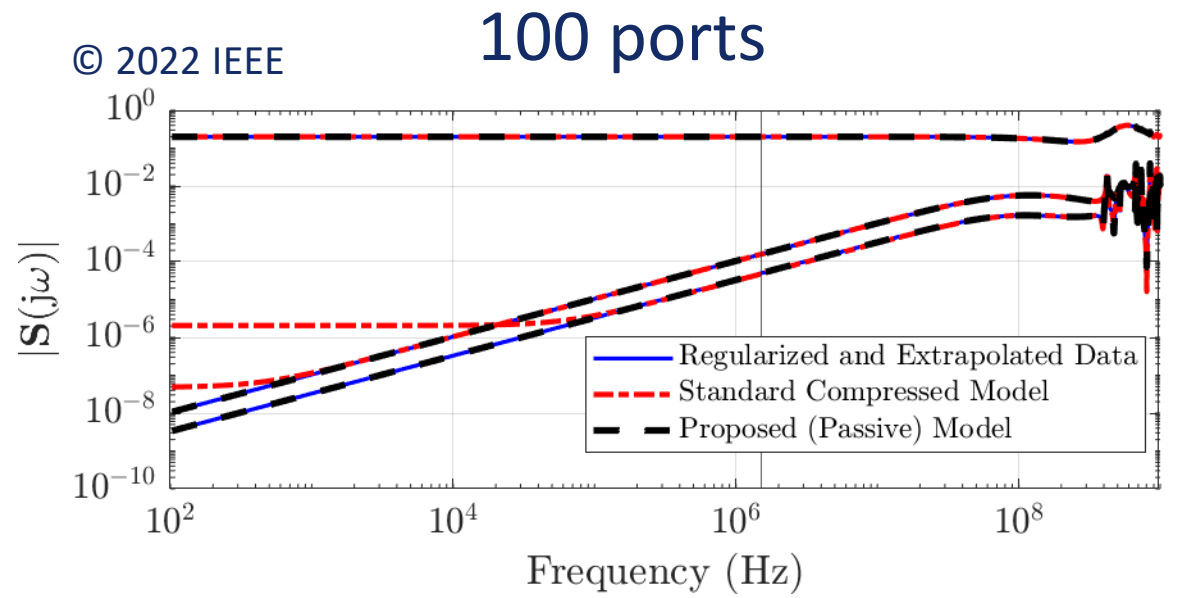
A 25-ports Shielding Enclosures



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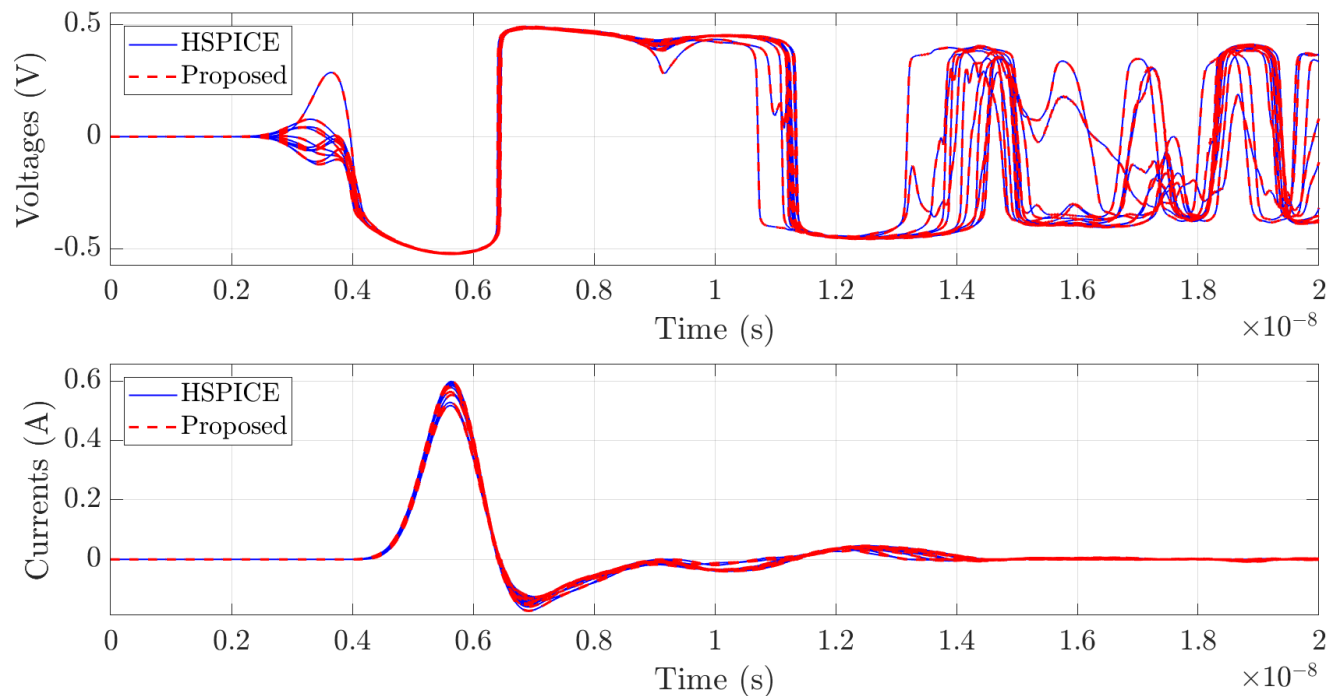
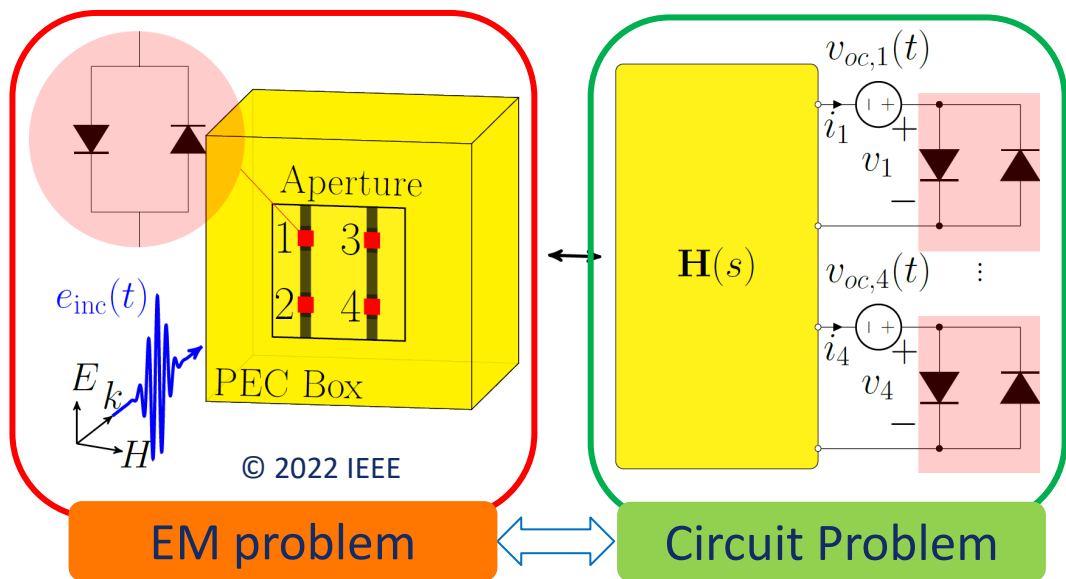
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Shielding Enclosures of Increasing Complexity



From: M. De Stefano, T. Wendt, C. Yang, S. Grivet-Talocia, and C. Schuster, "Regularized and Compressed Large-Scale Rational Macromodeling: Theory and Application to Energy-Selective Shielding Enclosures," *IEEE Trans. Electromagn. Compat.*, accepted

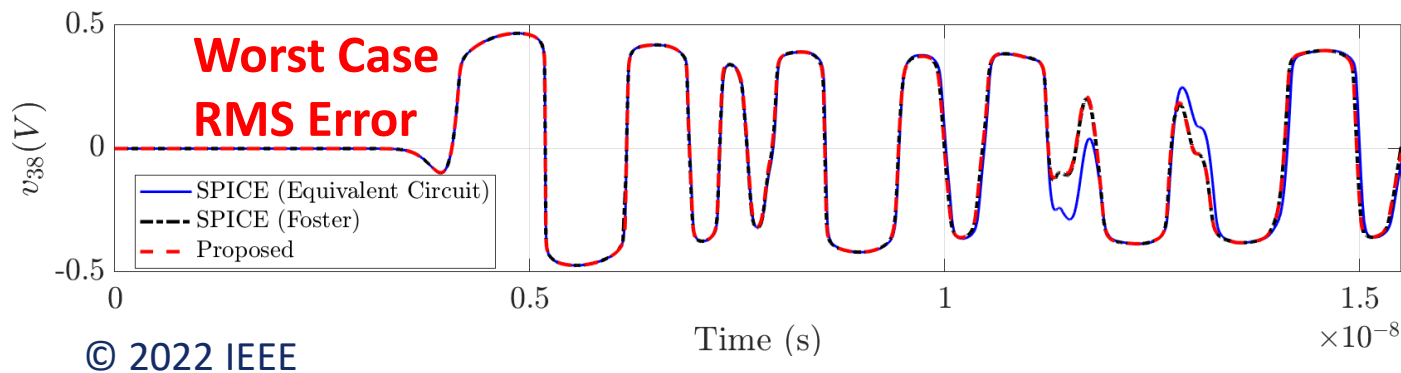
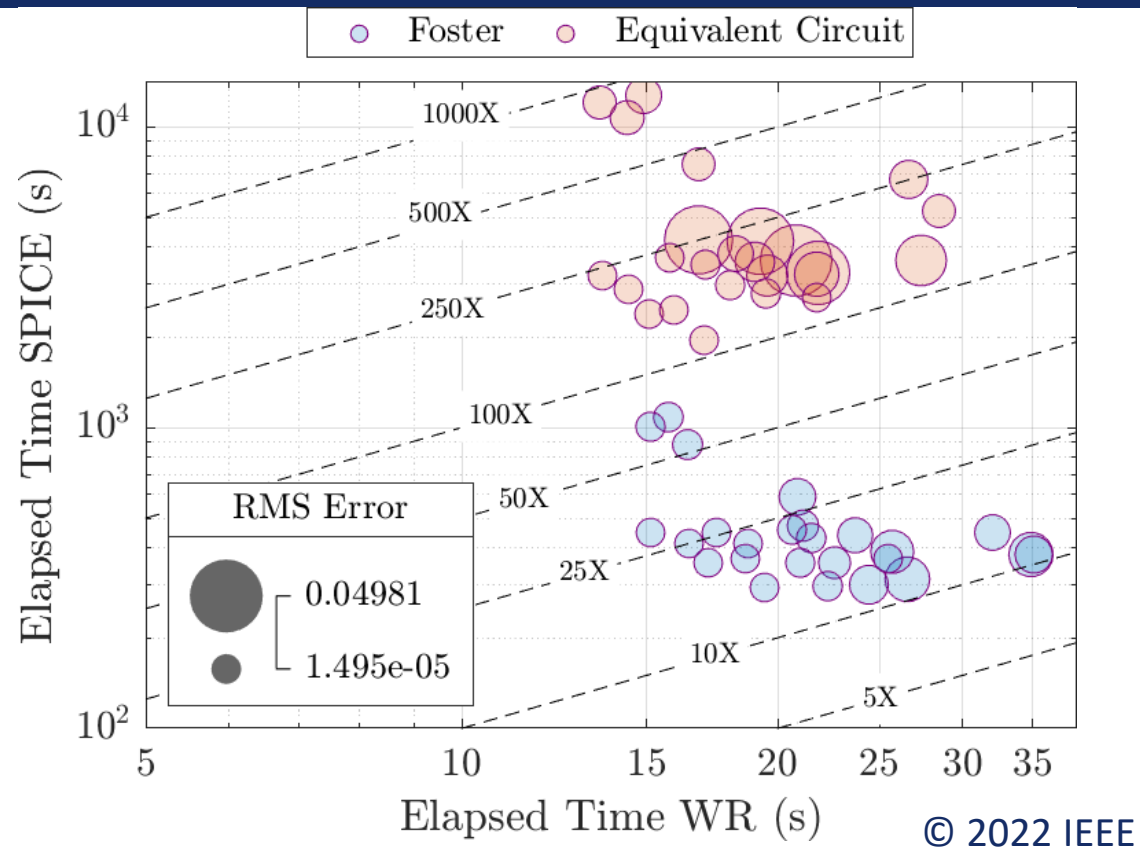
A Simulation Example with 400 Ports



- $H(s)$ is a **400-ports** box (**85 poles**)
- Incident wave $e_{inc}(t)$ is a Gaussian Modulated Pulse centered at 400MHz
- The resulting $v_{oc}(t)$ has a maximum amplitude of 473 V
- HSPICE Elapsed time: ≈ 1.27 hours
- Hybrid solver (Proposed) time: ≈ 203 seconds \rightarrow **SPEED UP $\approx 22X$**

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- 100-port Box + Gaussian Modulated Pulse
- **25 different simulations**
 - Sweep on center frequency and amplitude
- **2 SPICE representations**
(Foster and Equivalent Circuit)
- Total of **50 simulations**



Now we can run systematic analyses **safely!**

- A **full-bandwidth regularization and extrapolation procedure**
- Reliable data **pre-processing phase** for later **macromodeling**
 - **Full control of DC** → nonlinear simulations
 - **Data driven** → no need of a specific solver for the **low-frequency extrapolation**
- **Applicable to multiport** structures with **similar asymptotic behavior**
 - DC regularization circuit is needed
- If a **DC characterization is already available** → **minor modifications**

Thank you! Questions?