
C-comp extraction methods for High-Speed I/O buffers

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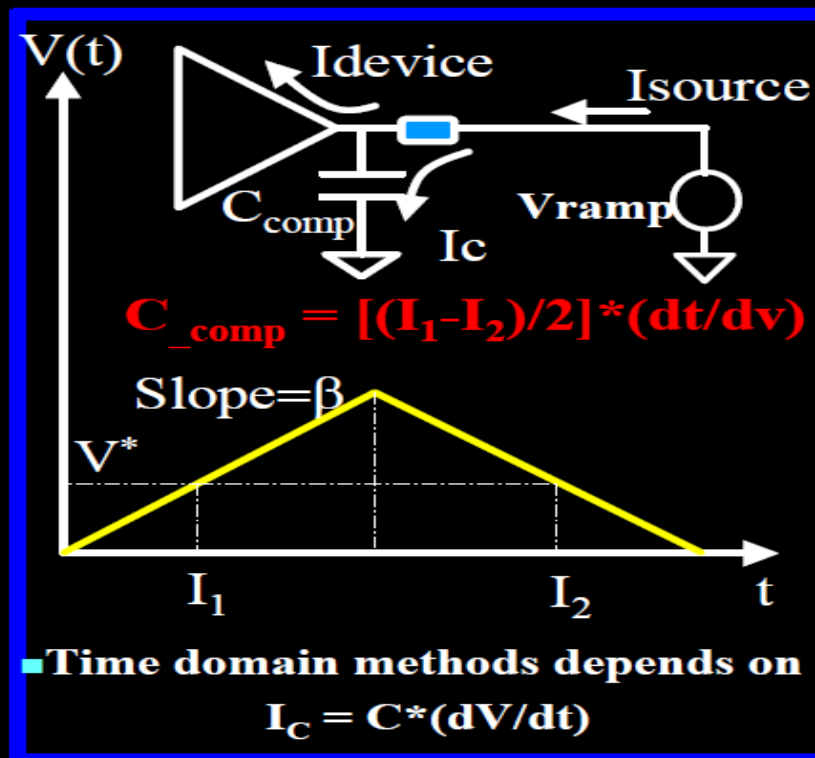
Outlines

- Review C-comp extraction methods
 - Time domain
 - Frequency domain
- Look into C-comp for pullup, pulldown, powerclamp and groundclamp
 - Frequency domain with voltage variables
- Define frequency and voltages
- Conclusions

Time domain

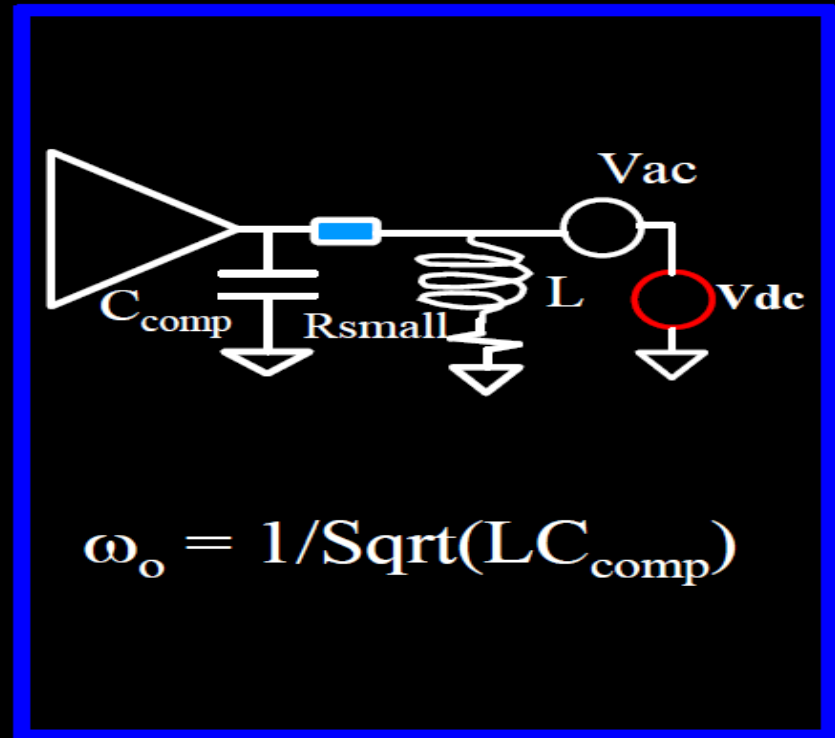
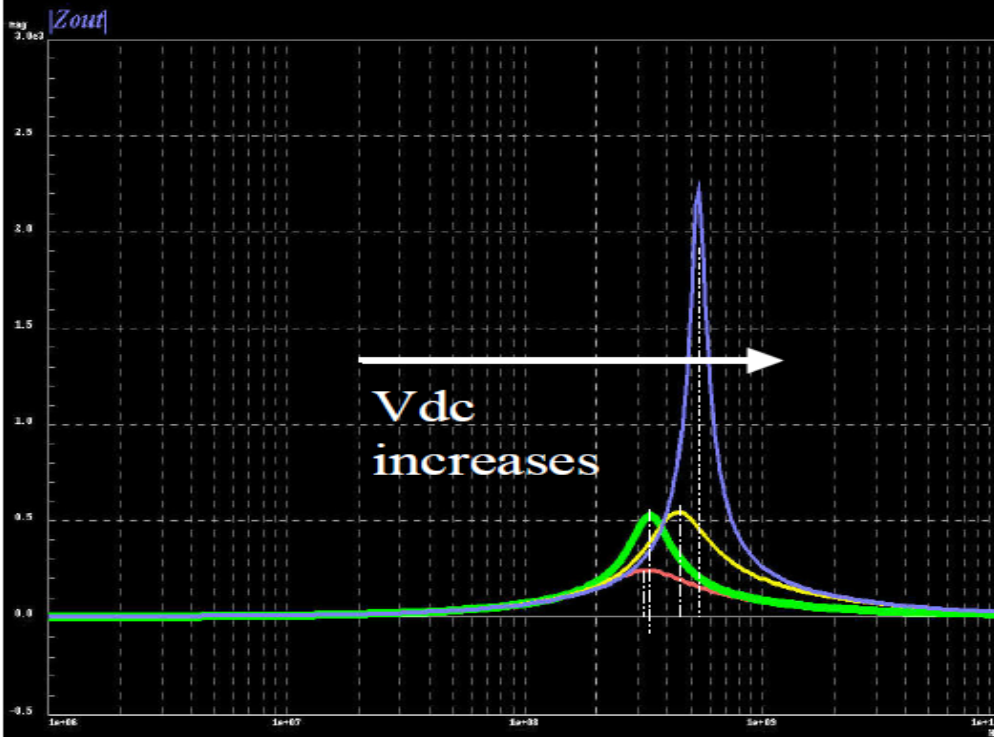
Time Domain Methods

- Apply ramp voltage source ($\beta \cdot t$) & measure the current.
- Subtract DC current in pull up/down device.
- $C(t) = (I_1 - I_2) / 2\beta = (I(t)_{\text{Source}} - I(t)_{\text{Device}}) / \beta$.
- Ccomp varies with β !!!!



Frequency domain

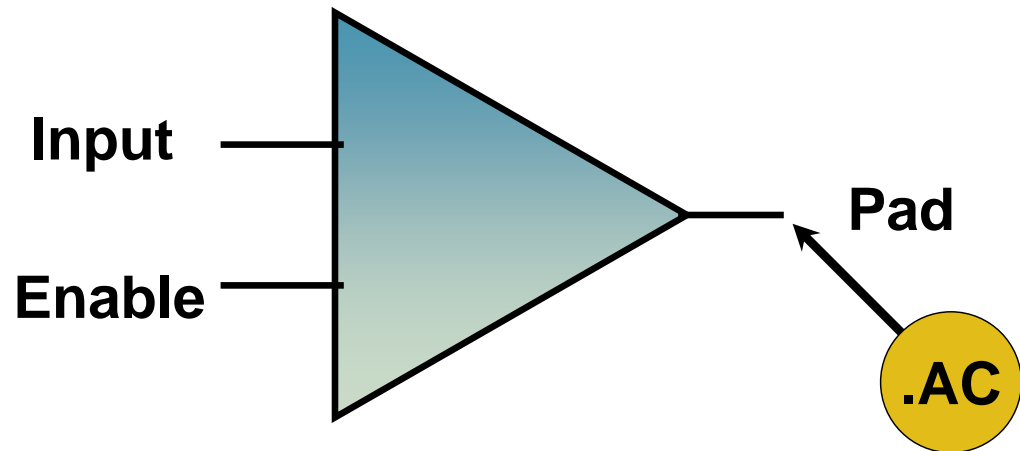
Voltage Dependence



$$\omega_o = 1/\text{Sqrt}(LC_{comp})$$

C-comps for pullup, pulldown, powerclamp and groundclamp

- Pad DC levels
 - 3.3v, 2.2v, 1.1v, 0v
- Input DC levels
 - High, Low
- Enable DC levels
 - Enabled, Disabled

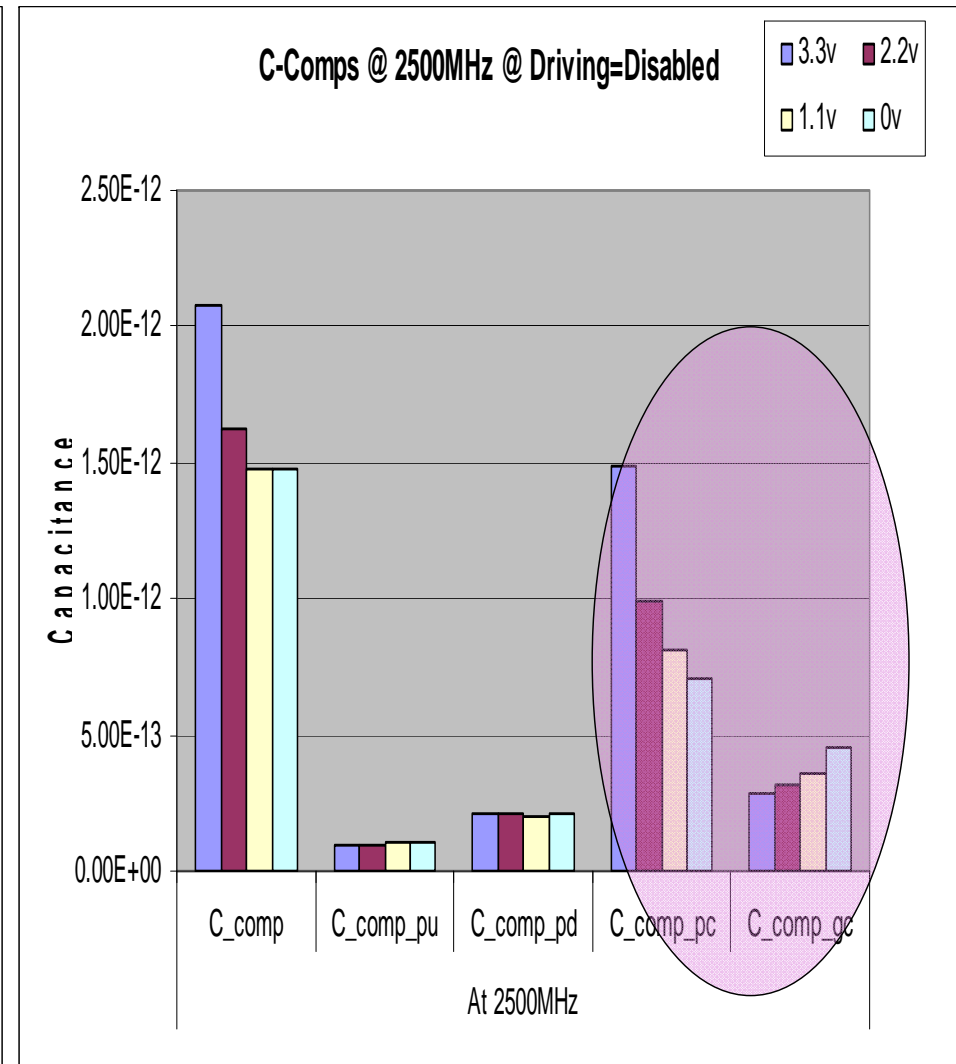
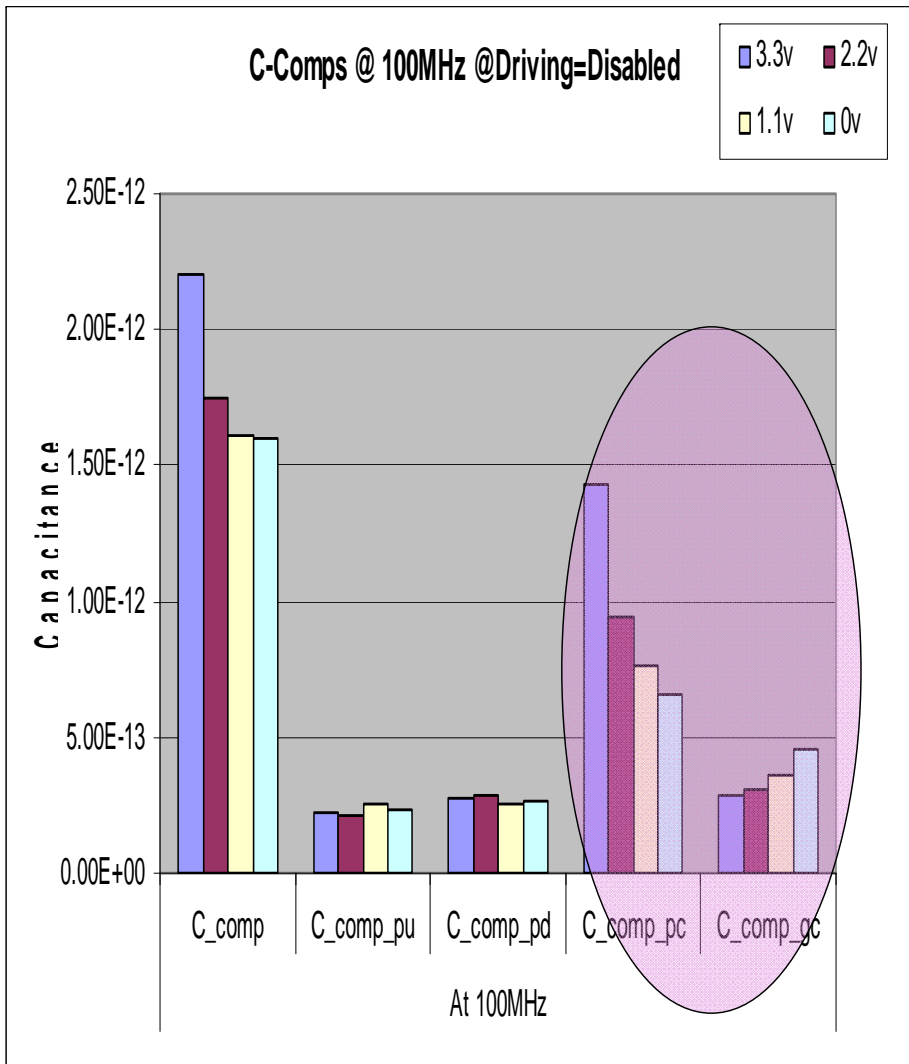


**3 DC variables for C-comp
frequency-domain
extractions**

Non-driving mode summary

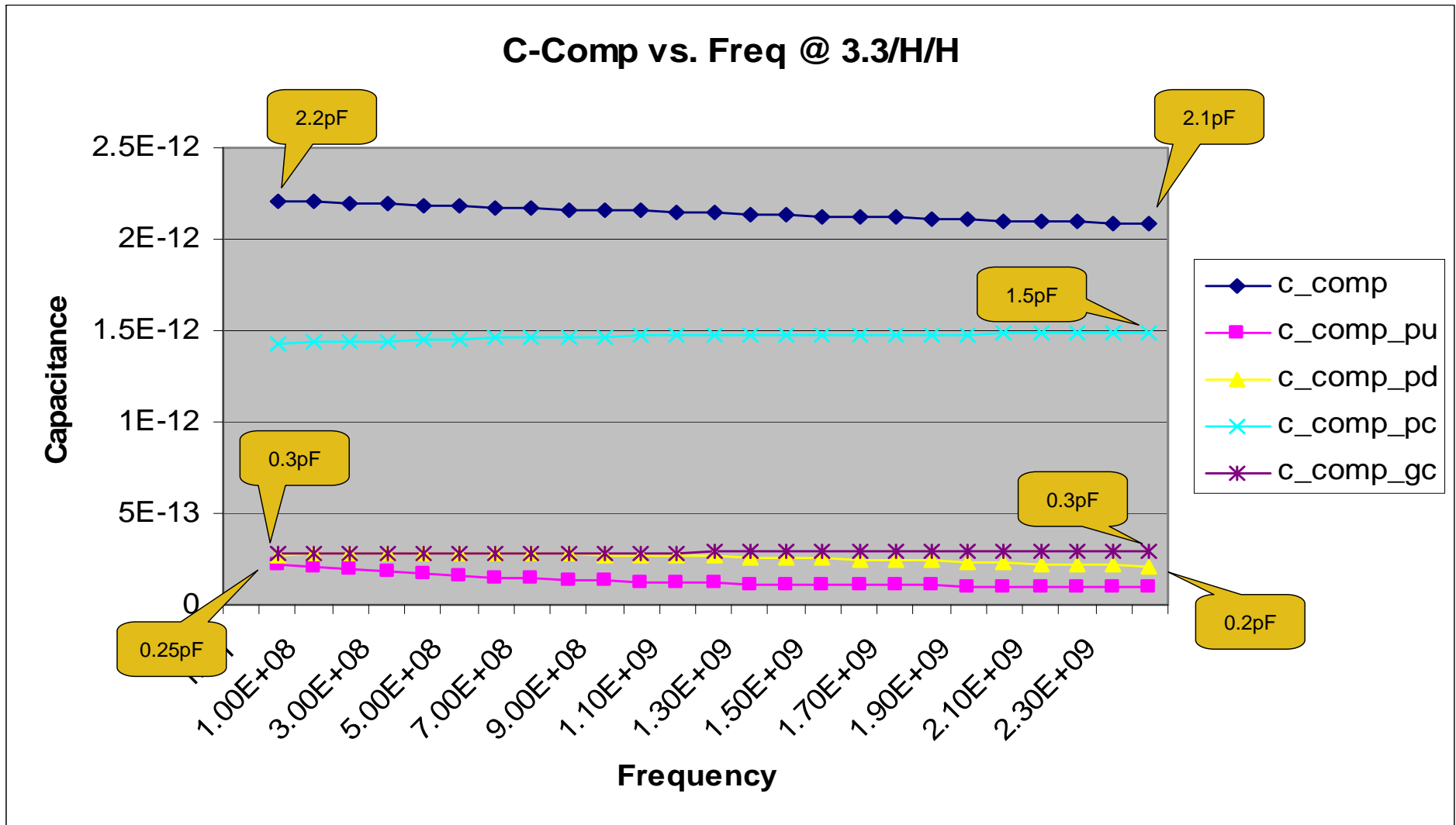
- Almost identical C-comp values for clamps when frequency changes
- Pad DC levels impact C-comp values for clamps
- For I/O buffers, C-comps values for Pullup and Pulldown may not be zero. They could change with frequency changes
- For I/O buffers, non-driving mode C-comp values are different than driving mode's. They could be big enough to affect your simulation analysis result

Non-driving mode @ 100MHz and 2500 MHz



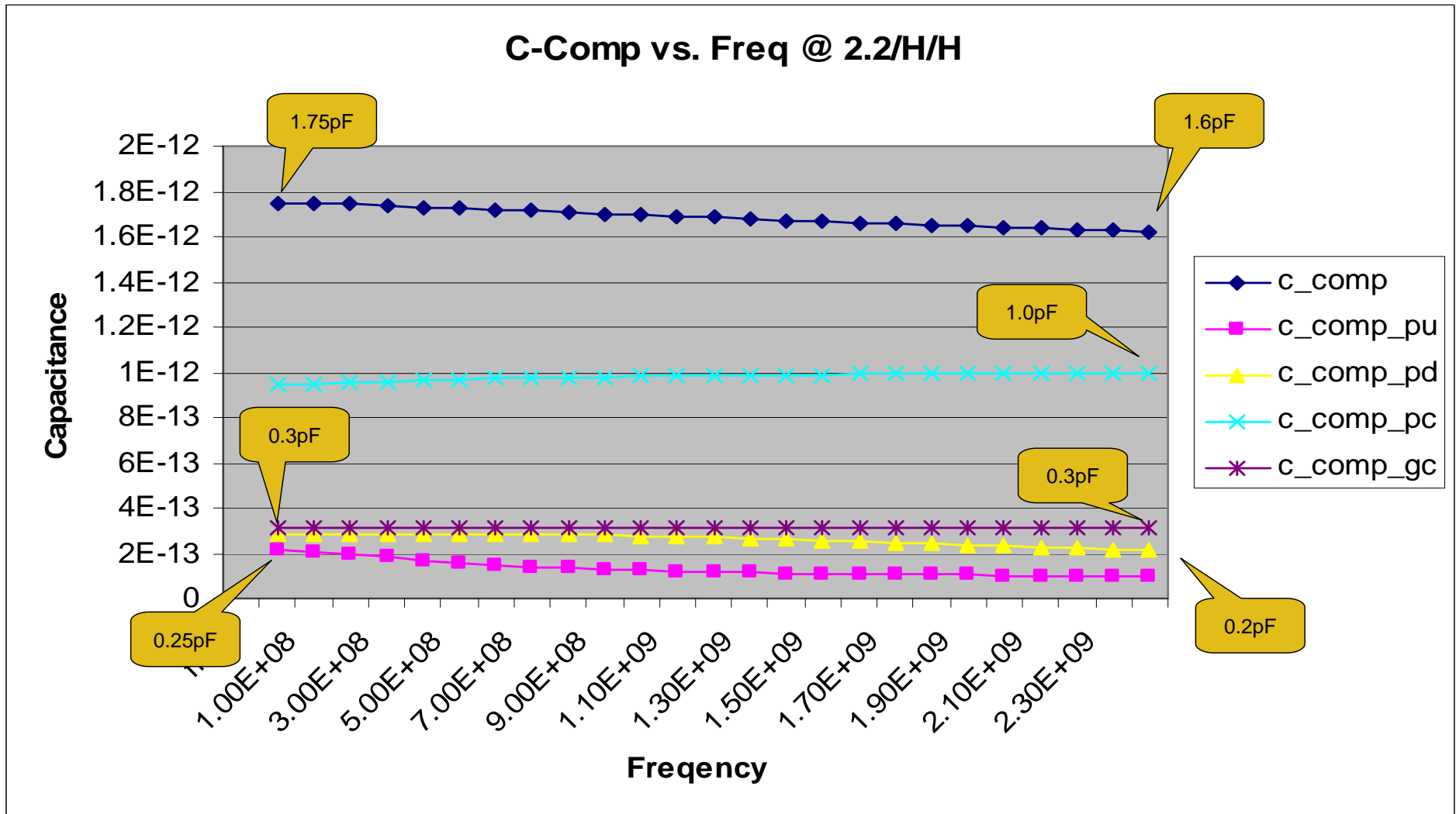
Pad DC = 3.3v

Driving mode = Disabled



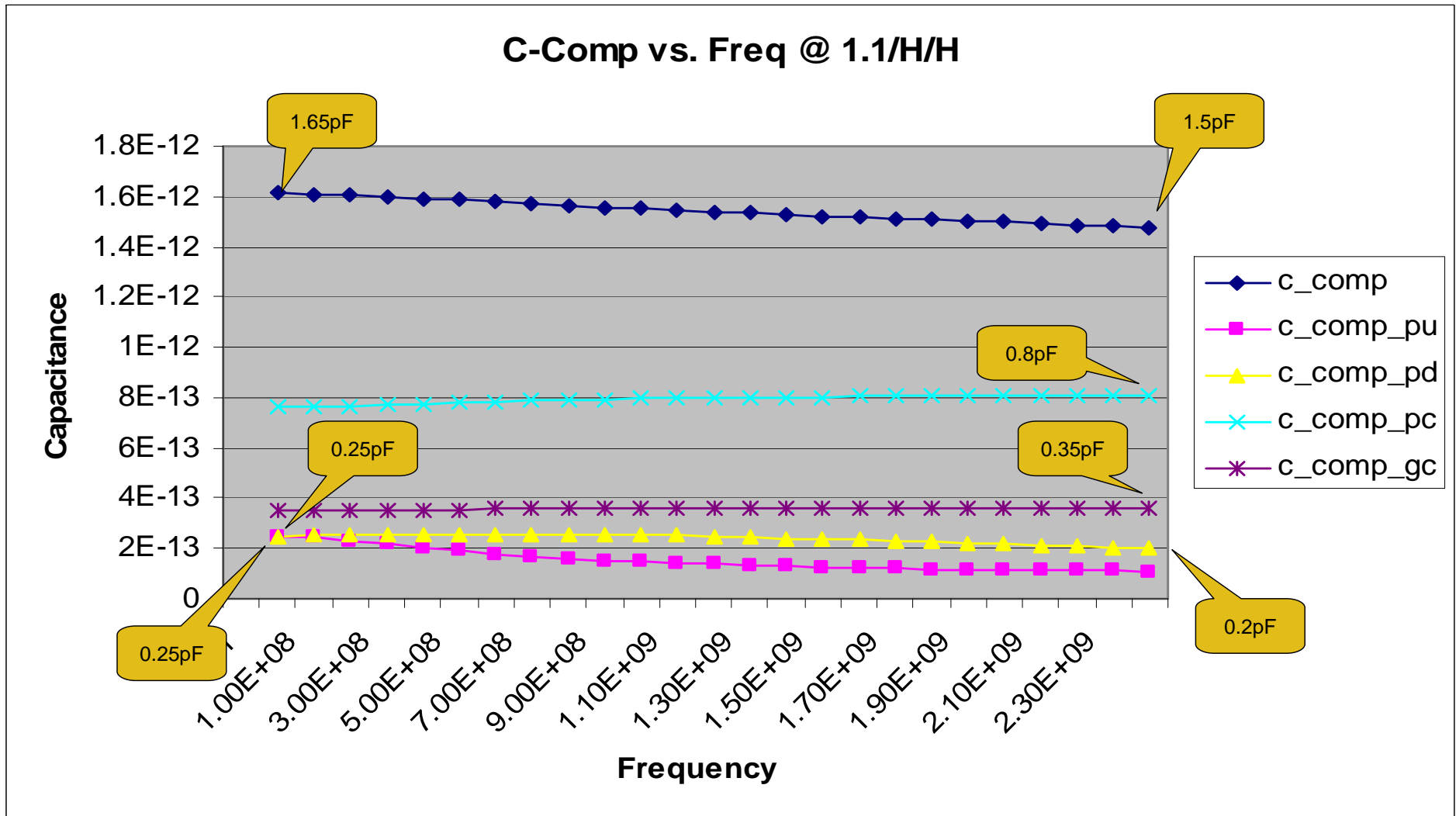
Pad DC = 2.2v

Driving mode = Disabled



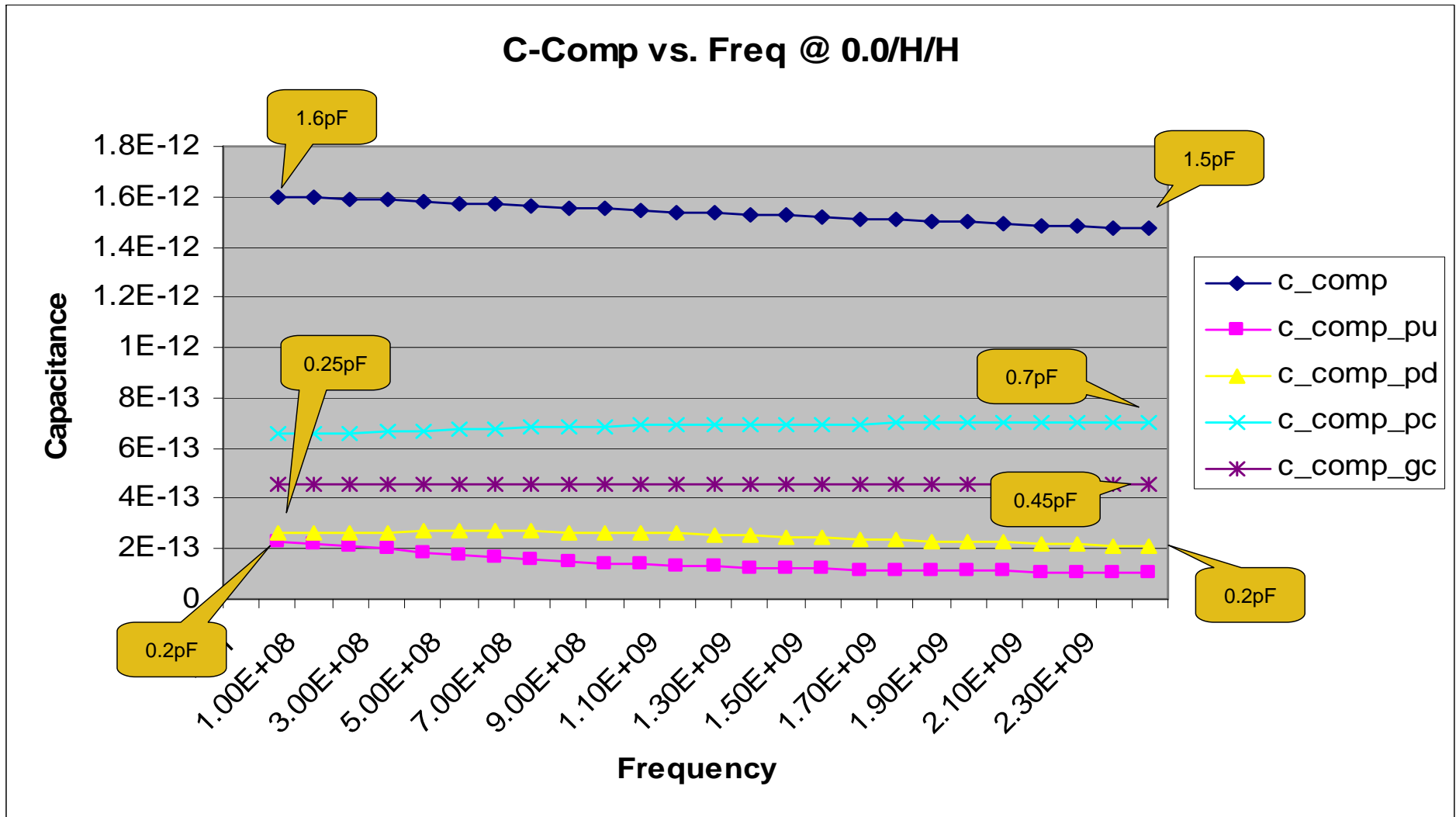
Pad DC = 1.1v

Driving mode = Disabled



Pad DC = 0.0v

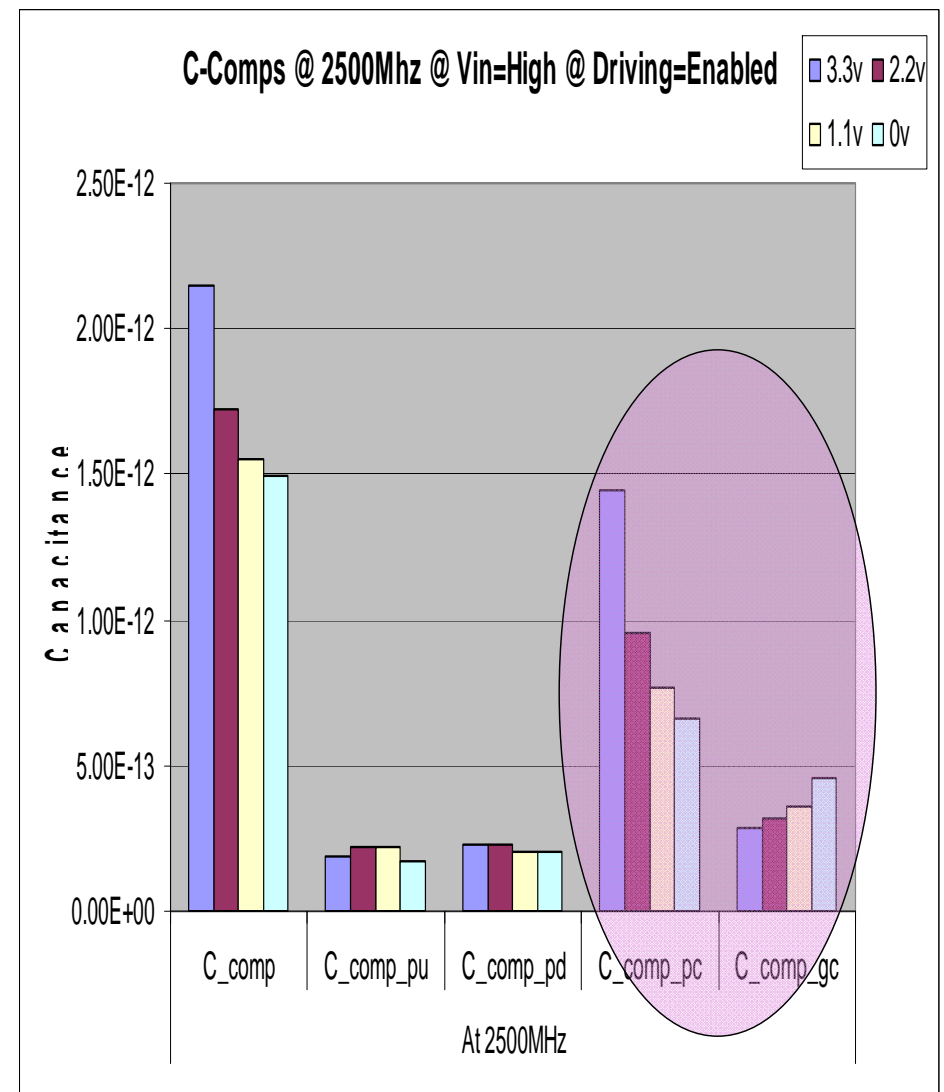
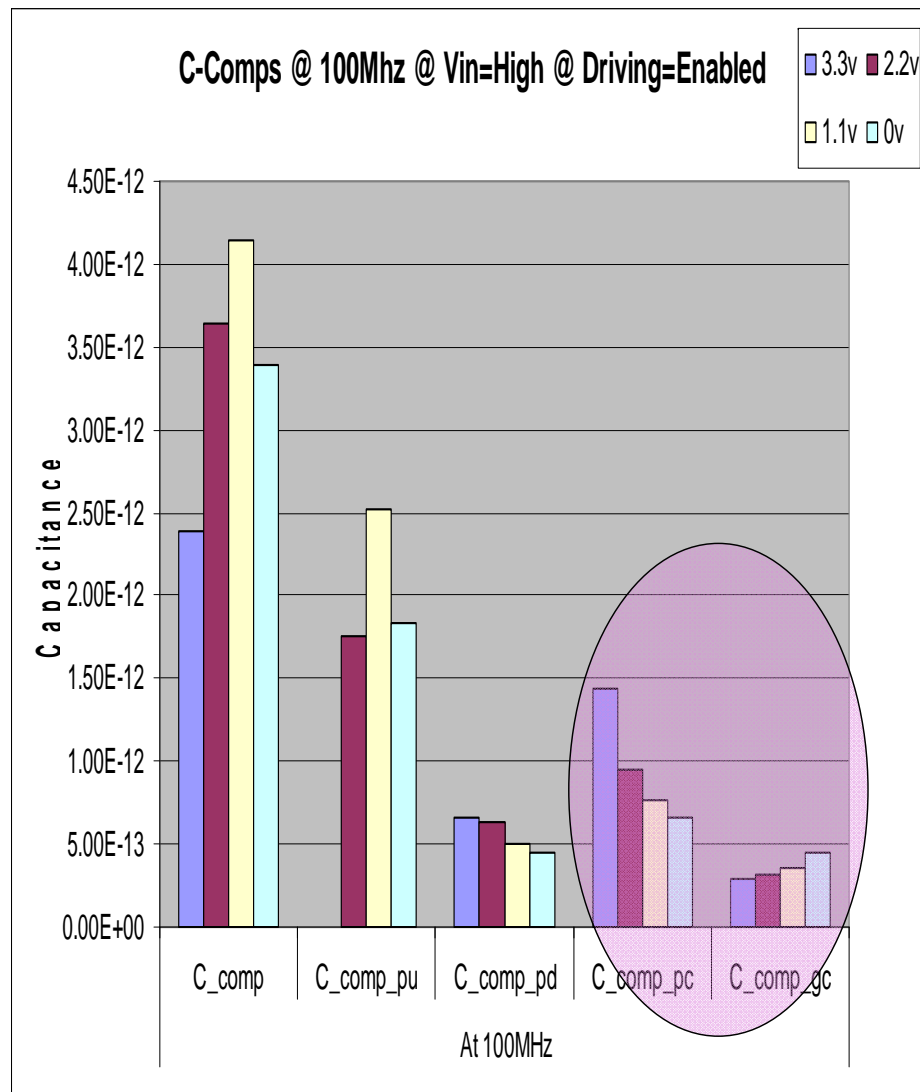
Driving mode = Disabled



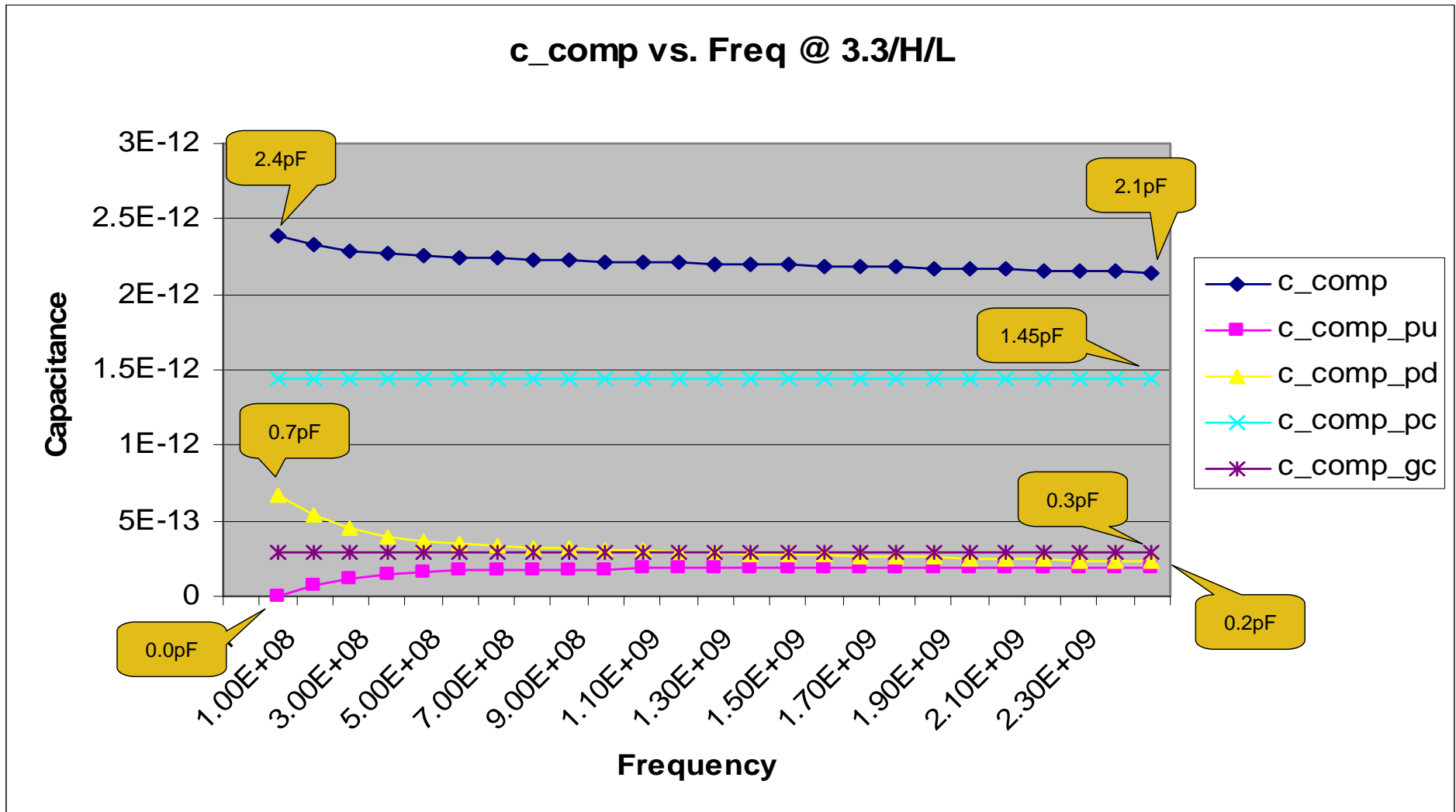
Driving mode summary

- Identical C-comp values for clamps with frequency changes
- Pad DC levels impact C-comp values for clamps
- Pullup and Pulldown C-comp values vary with frequency changes. But it settles at a frequency point and up (being flat)
 - Input DC (level = High) impacts more on Pullup
 - Input DC (level = Low) impacts more on Pulldown

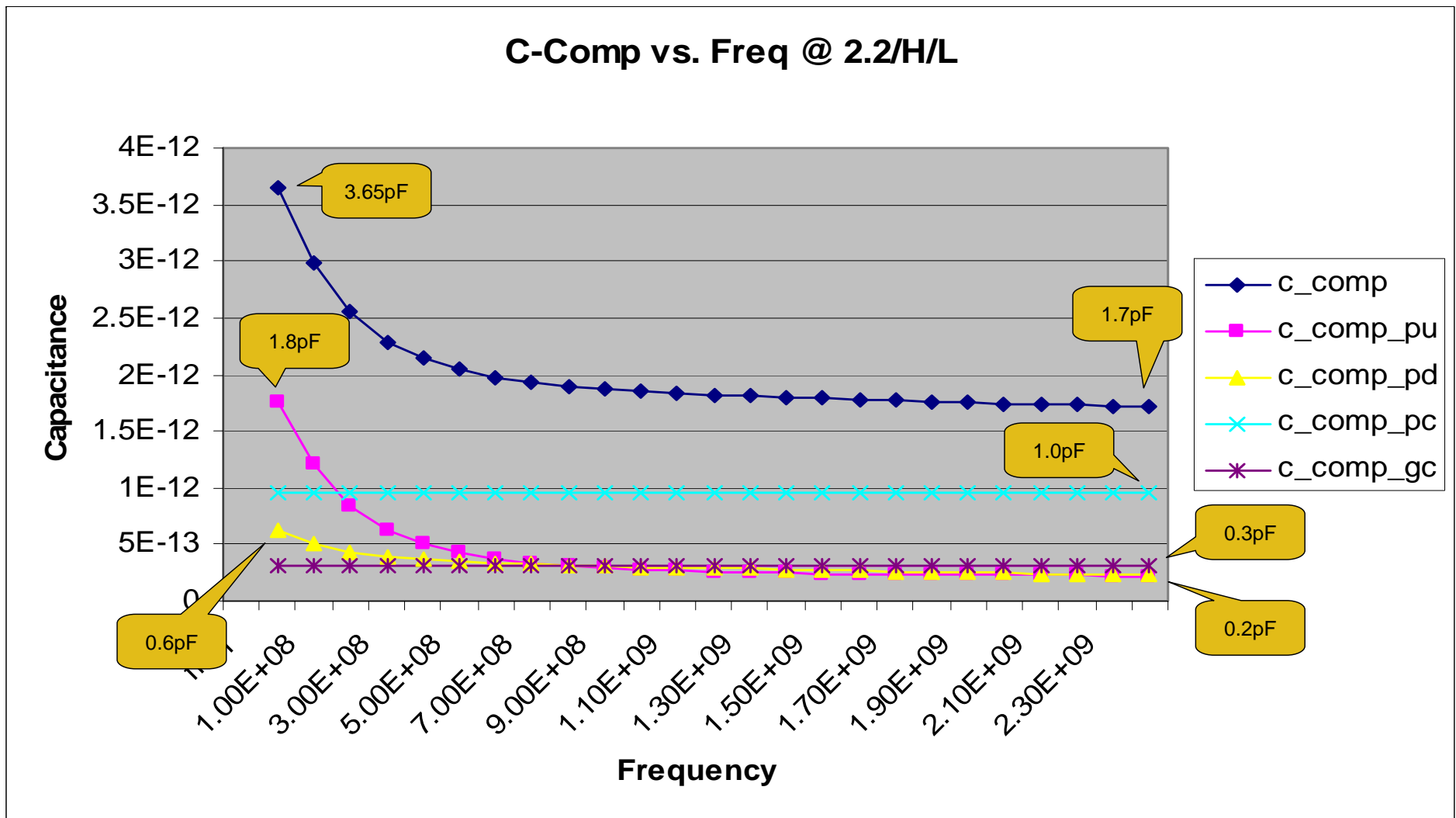
Driving mode with Vin=High @ 100MHz and 2500MHz



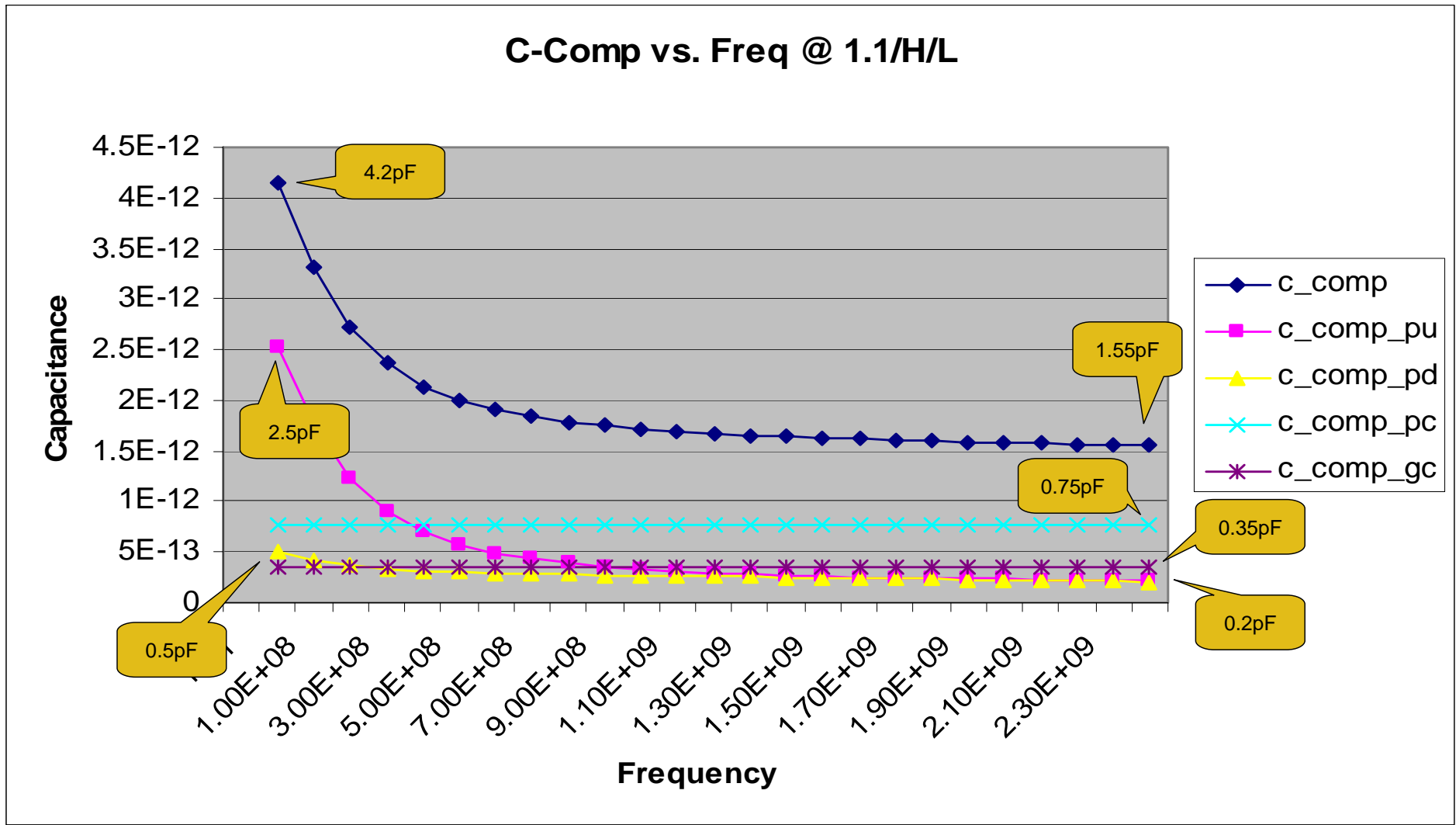
Pad DC = 3.3v, Input DC = High, Driving mode = Enabled



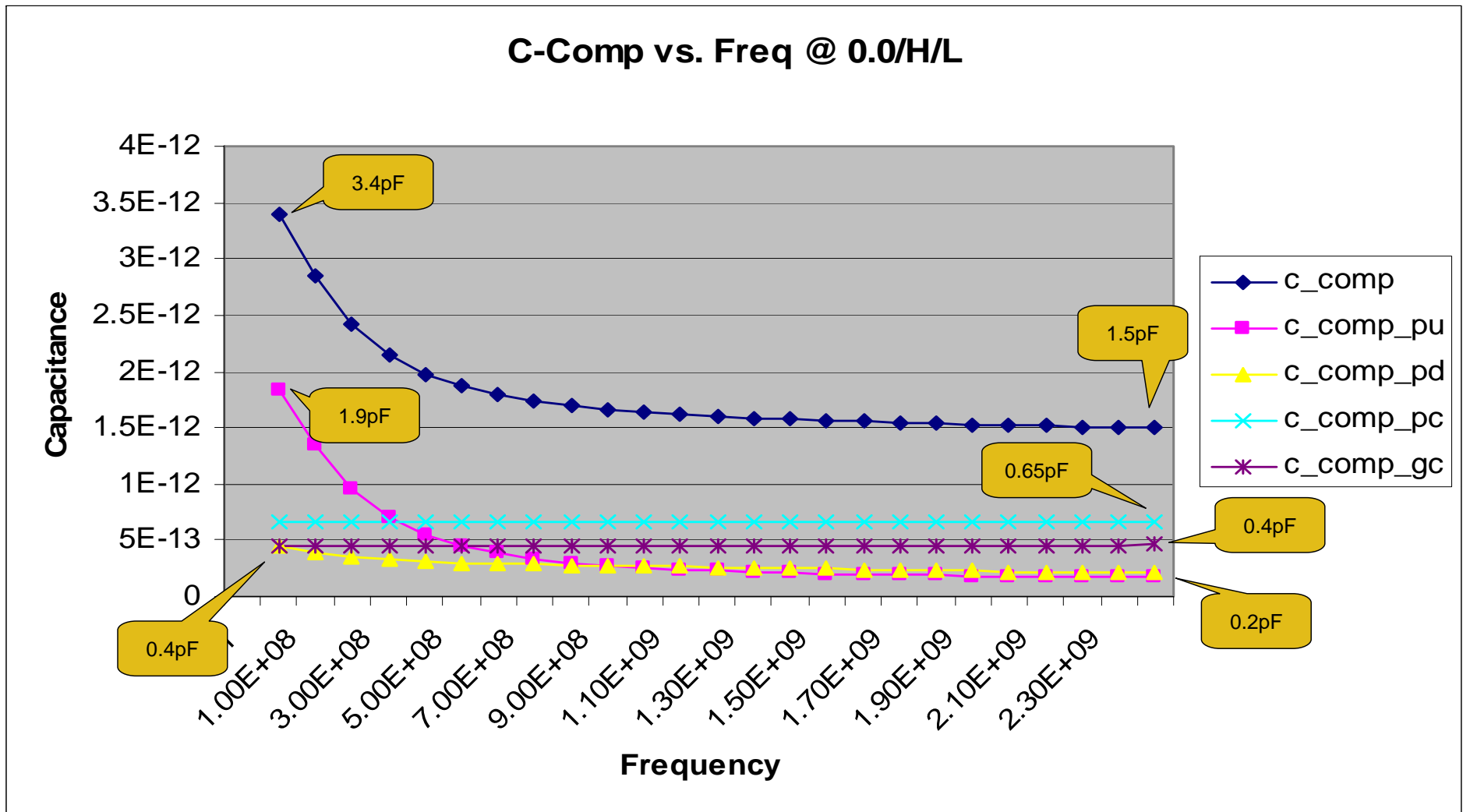
Pad DC = 2.2v, Input DC = High, Driving mode = Enabled



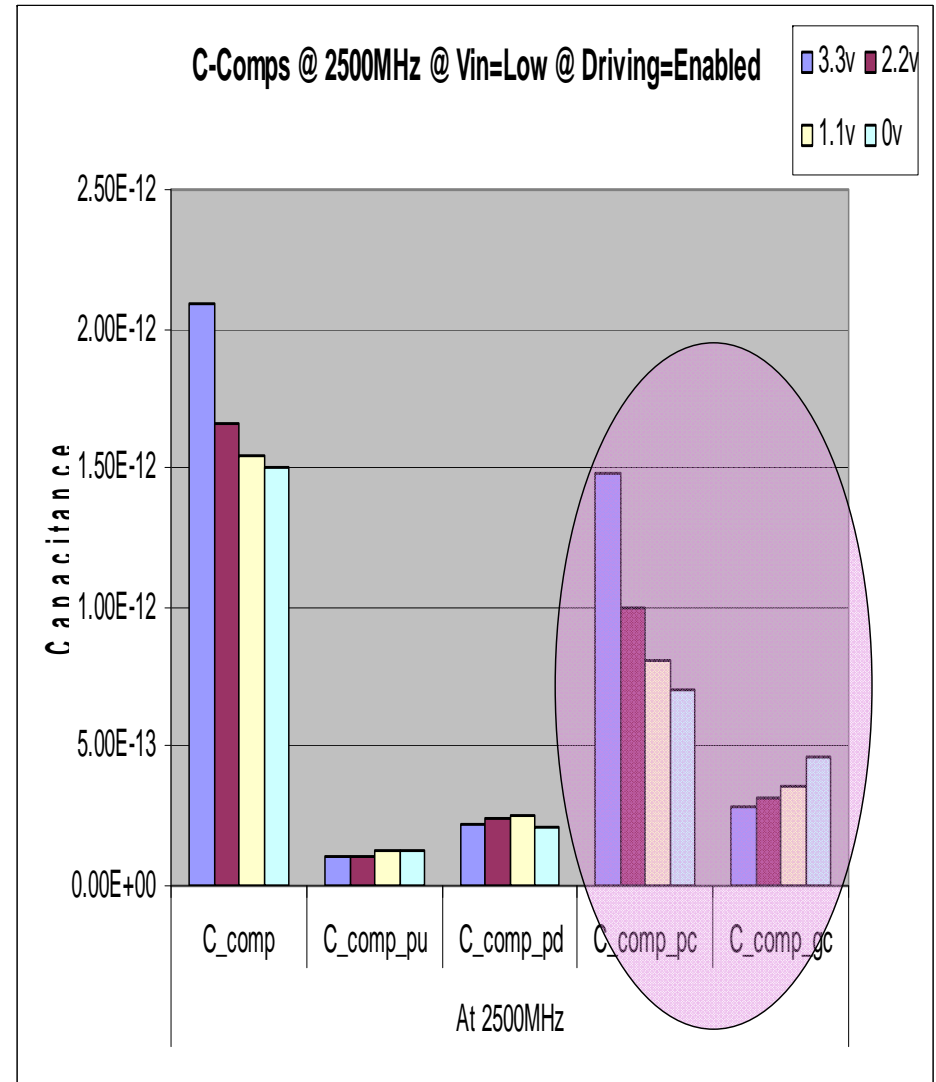
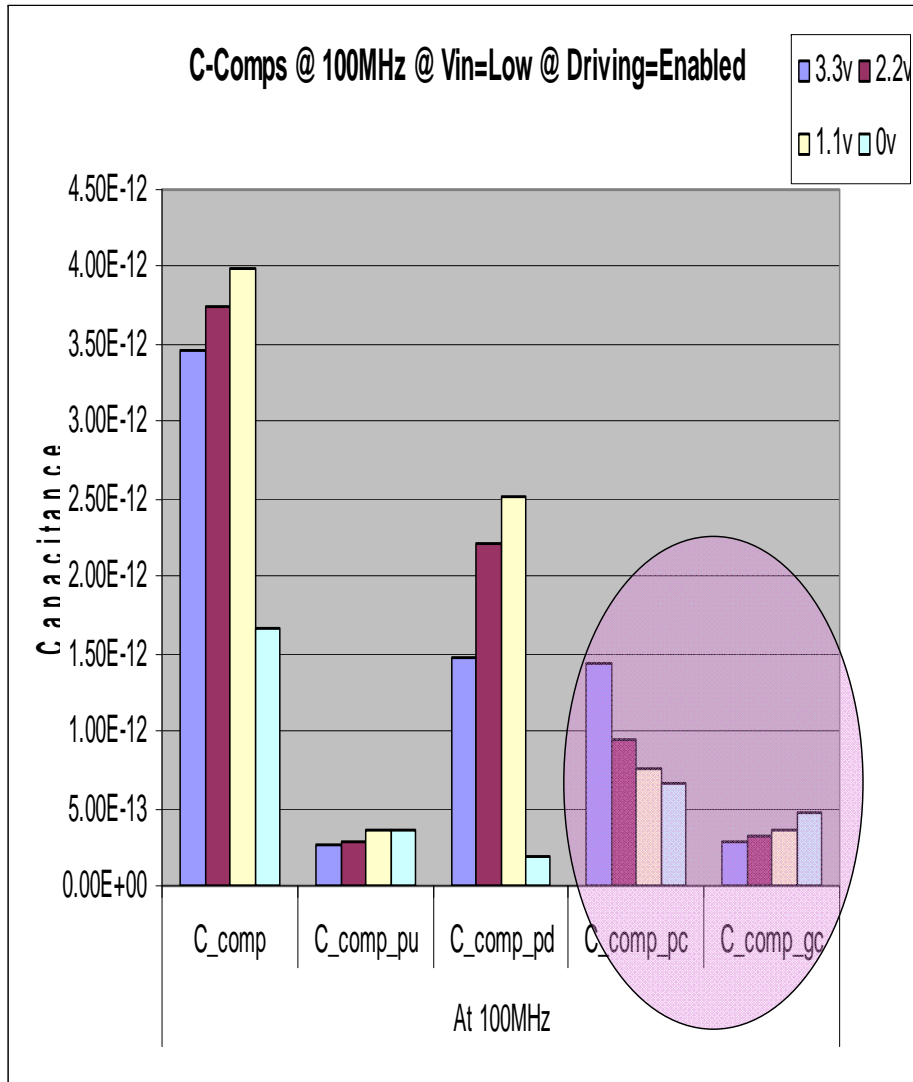
Pad DC = 1.1v, Input DC = High, Driving mode = Enabled



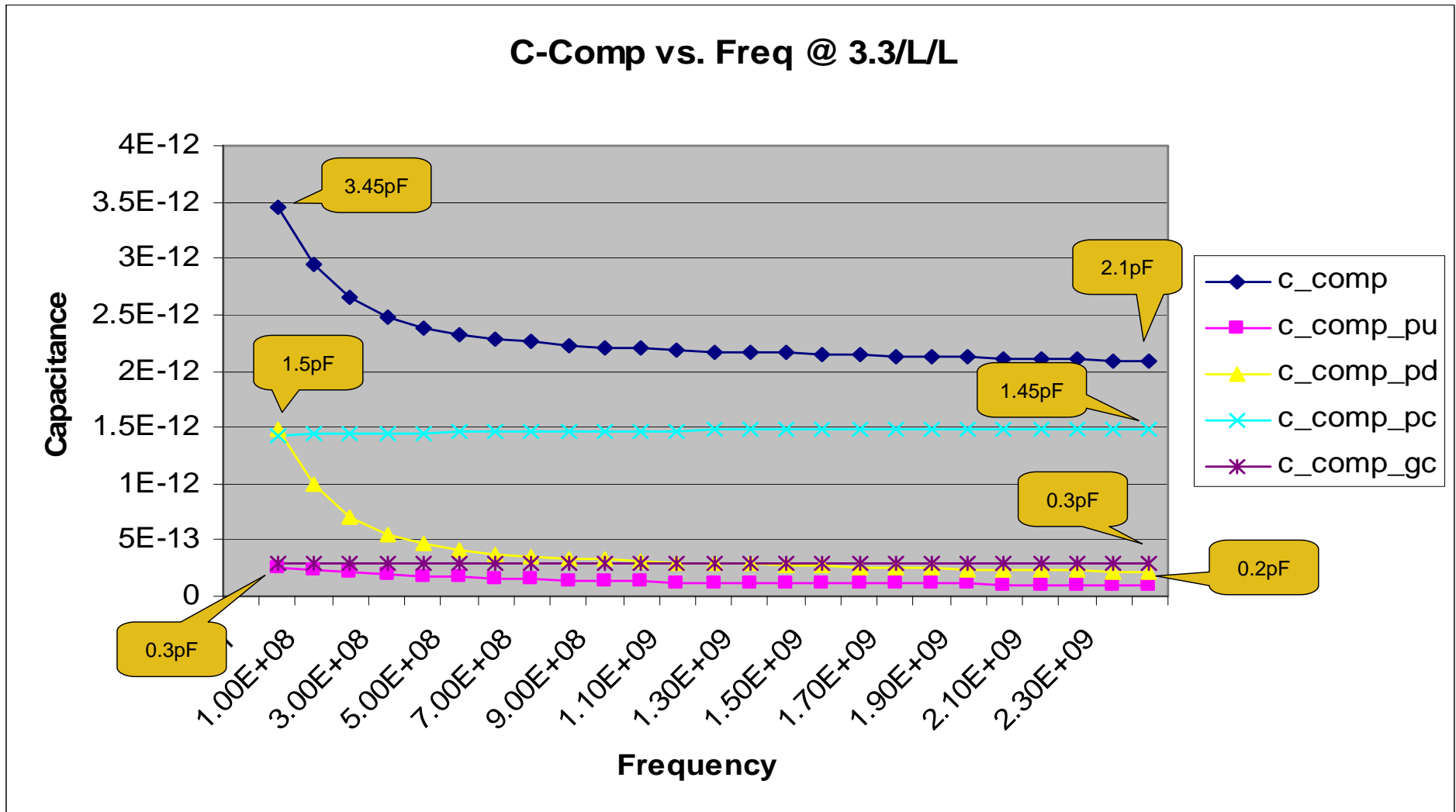
Pad DC = 0.0v, Input DC = High, Driving mode = Enabled



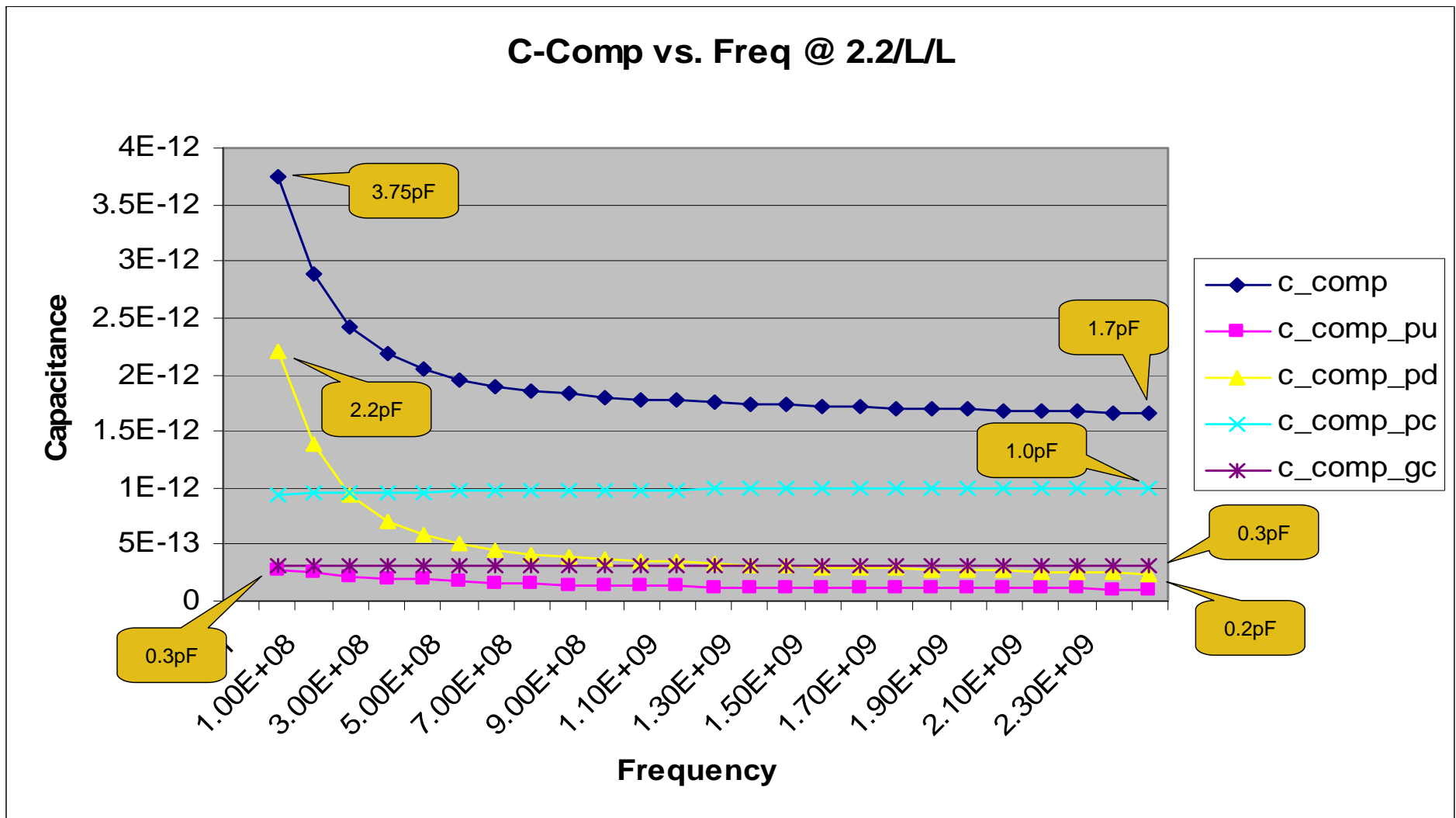
Driving mode with Vin=Low @ 100MHz and 2500 MHz



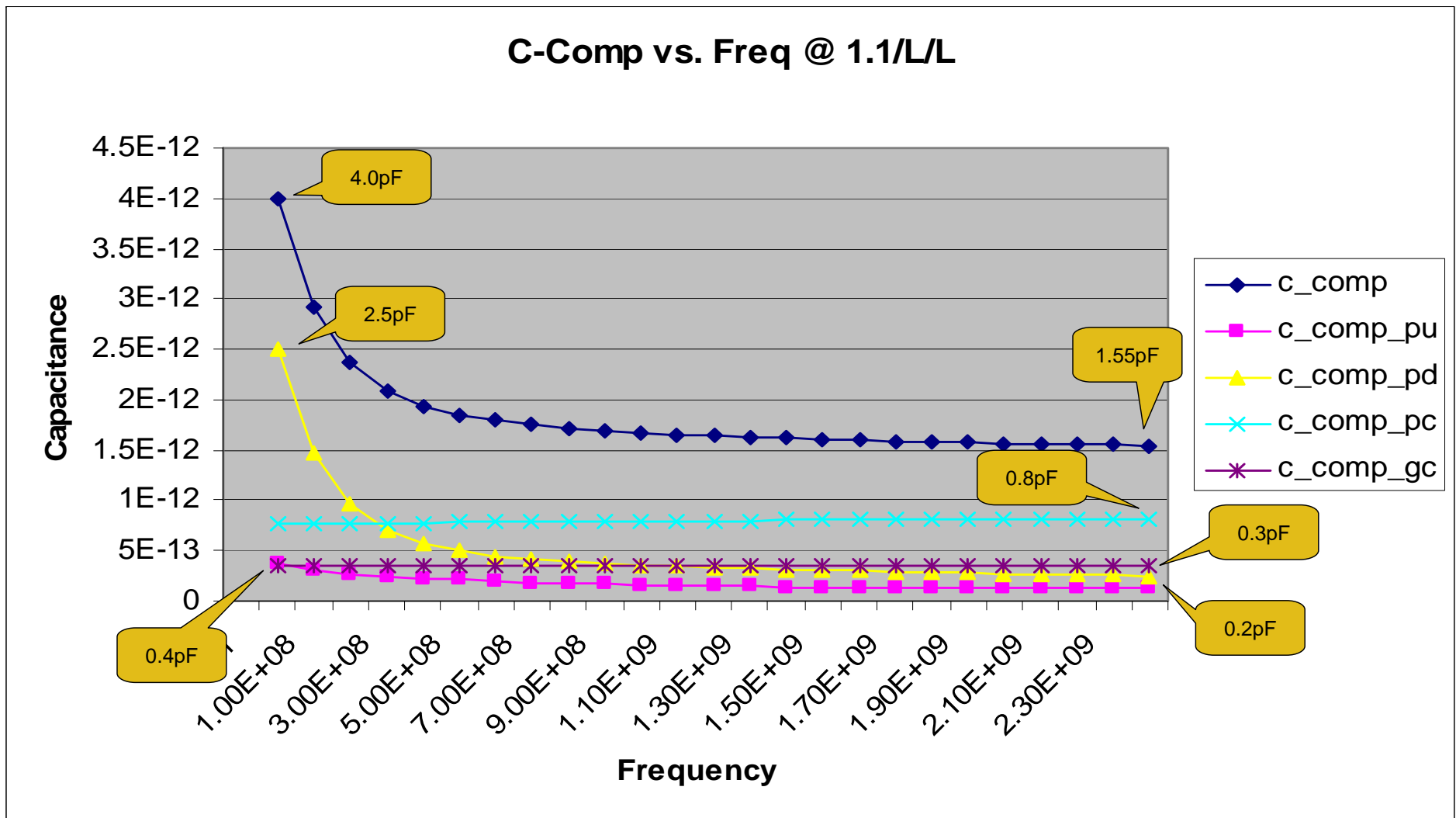
Pad DC = 3.3v, Input DC = Low, Driving mode = Enabled



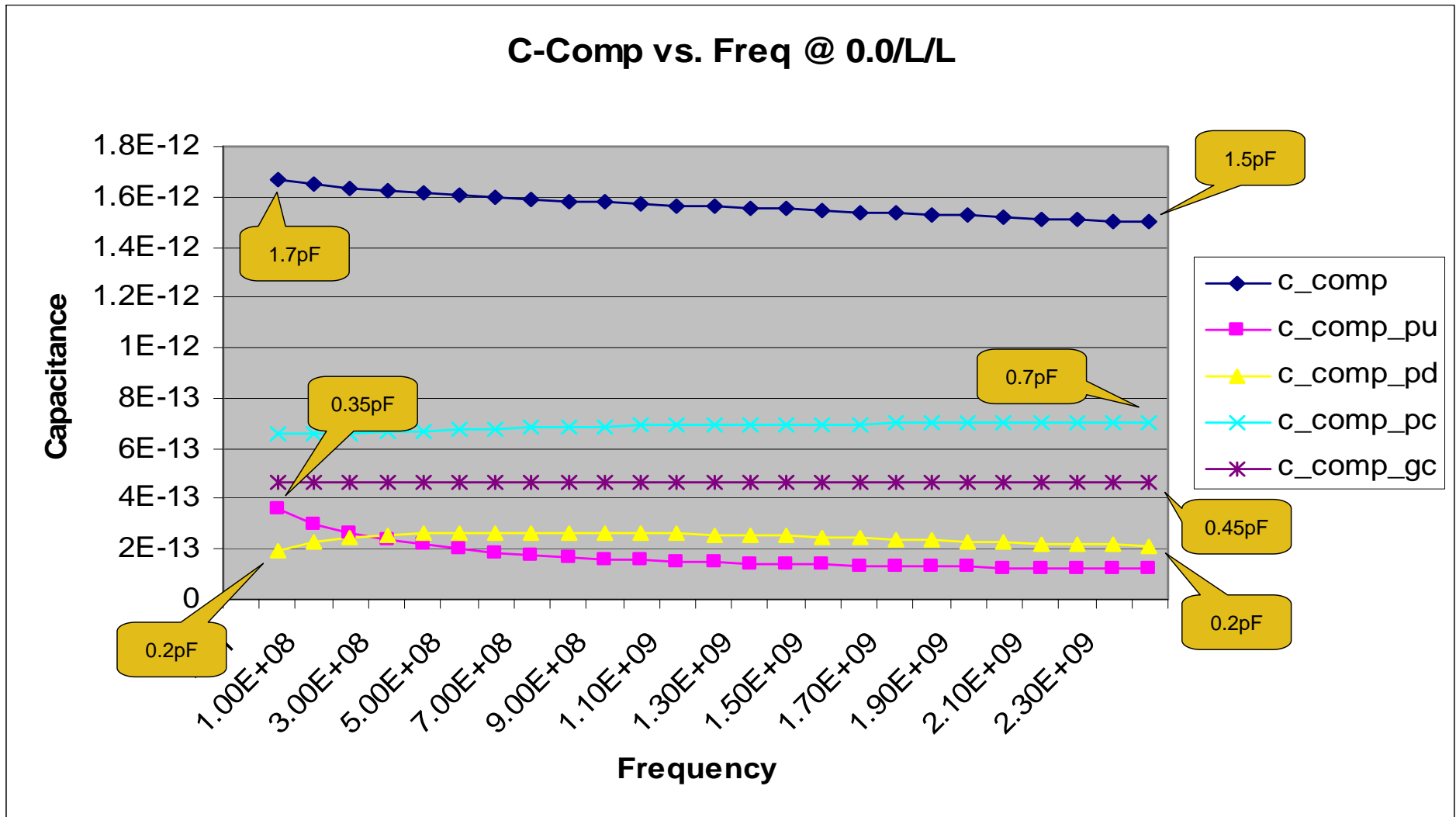
Pad DC = 2.2v, Input DC = Low, Driving mode = Enabled



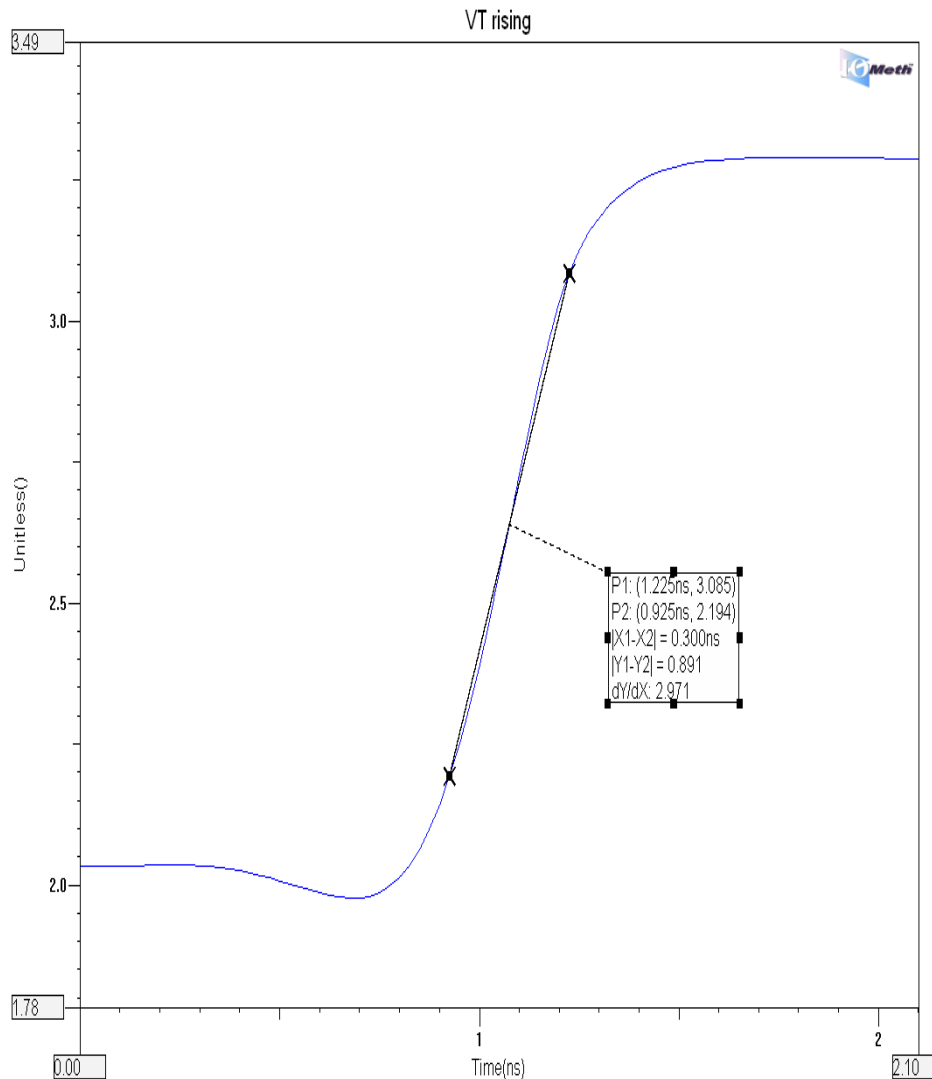
Pad DC = 1.1v, Input DC = Low, Driving mode = Enabled



Pad DC = 0.0v, Input DC = Low, Driving mode = Enabled



Define frequency and voltages



■ Frequency

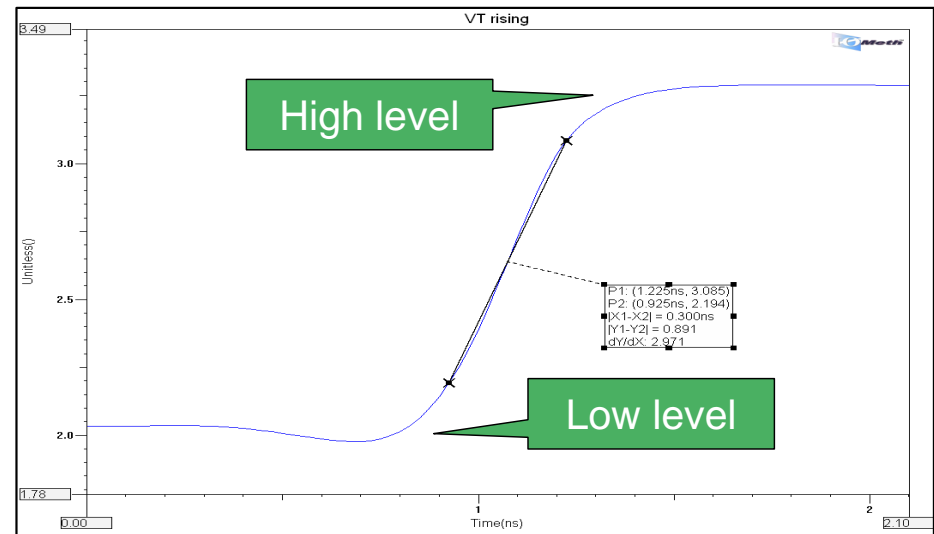
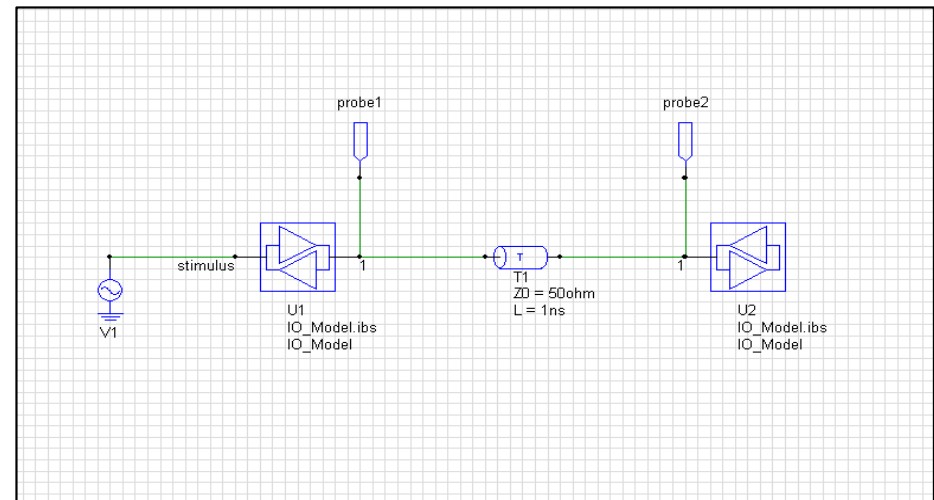
- Use [Ramp] data as the reference
- Buffer output frequency (F_{output})

$F_{\text{output}} = 1/(\text{Rising_dt} + \text{Falling_dt})$
(for the most of high-speed buffer, the calculated output frequency point is in the settled region)

- Input buffer c-comp is not impacted much by output frequency changes. But suggest to use slightly higher frequency

Define frequency and voltages

- Voltages
 - Typical application settings
 - Operation voltage ranges
 - Using High and Low level DC settings
 - Averaging extracted C-comp values is a practical way for IBIS model
- Important to correctly define DC voltages



Conclusions

- C-comp (die capacitance) is important in high-speed buffers
- Understand your high-speed buffer die-capacitance arrangement is the first step for extractions
- Frequency domain with defined frequency and DC voltage settings is practical for accurate C-comp extractions
- IBIS specification improvements are required:
 - Separate driving and non-driving mode C-comp values for accurate high-speed simulations
 - Separate different DC level C-comp values for different applications

Thank You

谢谢

ありがとうございました



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